Stellarators and Stellarator Physics

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Outline

- What is a stellarator?
 - Twisted magnetic fields and different types of stellarators
- (Performance-limiting) plasma transport in stellarators
- Advantages and disadvantages of stellarators over tokamaks ⇒ is one concept going to win the race?
- Field-optimized stellarators and the Wendelstein 7-X project
- Cost of fusion electricity



A stellarator is magnetic confinement system based on currents solely driven by external coils

Conceptual advantages:

- Inherently steady-state
- No current disruptions (or current-driven instabilities)

Drawbacks/opportunity:

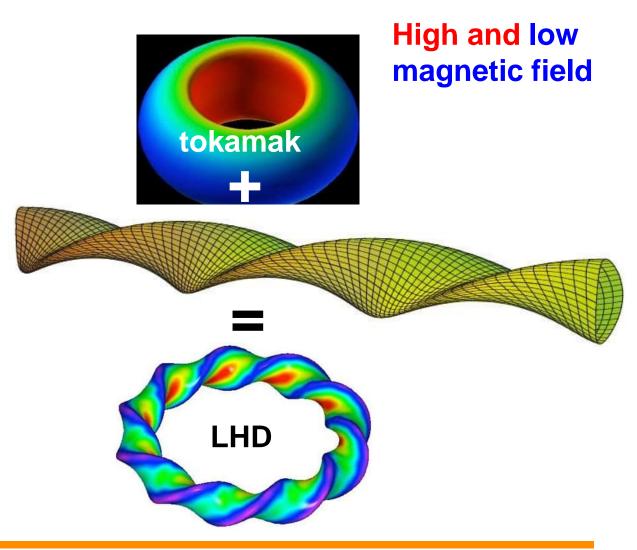
- No guaranteed flux surfaces

 Due to 3-D geometry, additional losses, complexity, localized heating of wall



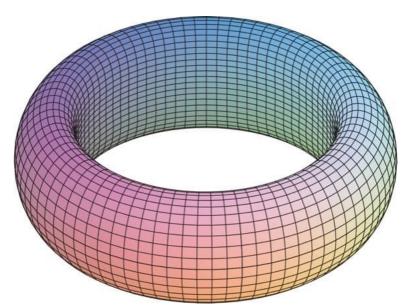
Having to deal with a full 3-D magnetic field configuration allows dedicated design of it

- Magnetic confinement requires:
 - Nested flux surfaces
 - Finite toroidal transform



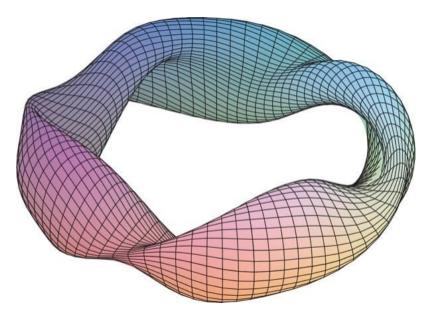
In a tokamak toroidal symmetry is preserved, in stellarators imposed

Tokamak



Axisymmetry

Stellarator



- Periodicity $\phi \rightarrow \phi + 2\pi/P$ (P: number of field periods)
- Stellarator (flipping)
 symmetry: (φ,θ) → (-φ,-θ)

Tokamaks and stellarators produce two different types of rotational transforms

Tokamak

- transform produced by plasma current
- transform decreases with radius (safety factor increases)
- Axisymmetric

plasma current

- 2-D configuration
- Current-driven instabilities and disruptions
- Pulsed

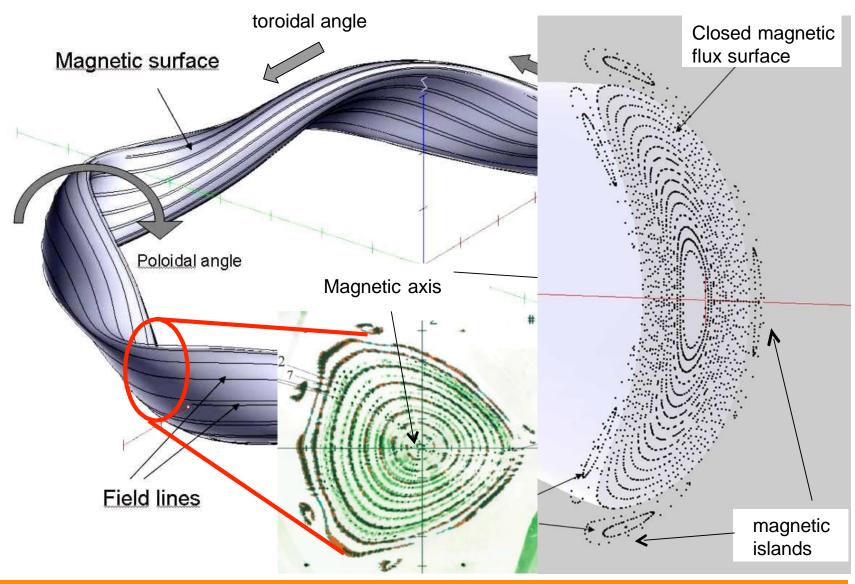
Stellarator

- transform produced by external coils
- transform increases with radius

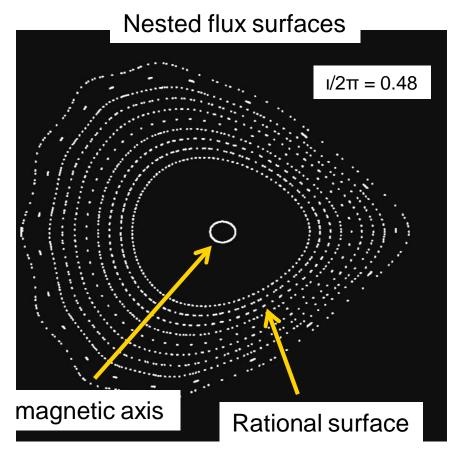
no externally driven TOTAL toroidal current

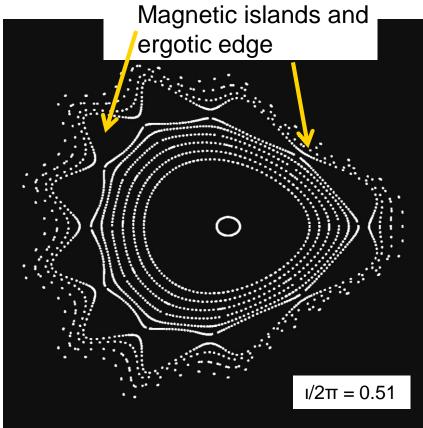
- 3-D configuration by definition ⇒ complex, prone to higher radial transport losses
- No disruptions
- Steady-state

Magnetic confinement in a stellarator is toroidally asymmetric



Closed field lines exist at rational values of m toroidal and n poloidal transit $1/2\pi = m/n$





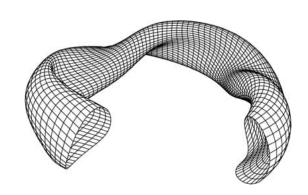
- Rotational transform: $R < B_{\theta} > / r_{eff} < B_{\phi} >$
 - Local pitch angle may vary strongly on flux surface

The stellarator equilibrium can be derived from the standard MHD equations

Equations (as for tokamaks):

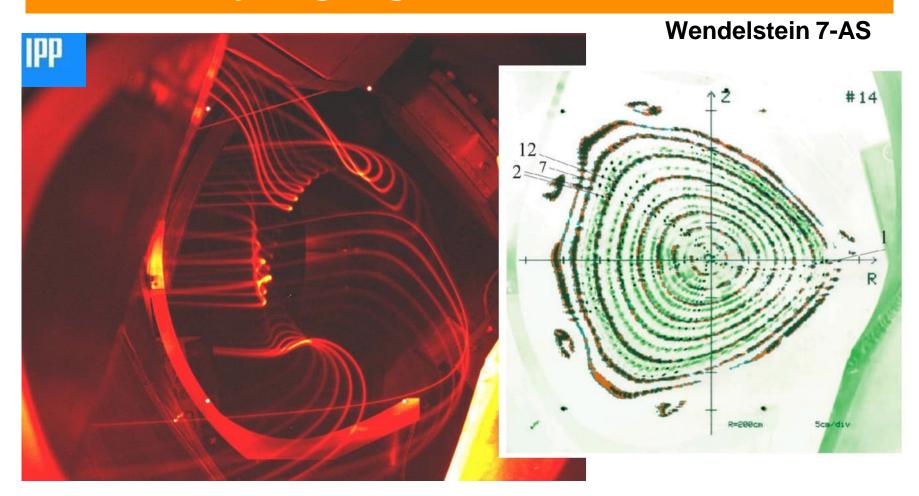
$$\mathbf{j} \times \mathbf{B} = \nabla p$$
 $\nabla \times \mathbf{B} = \mu_0 \mathbf{j}$

$$\nabla \cdot \mathbf{B} = \mathbf{0}$$



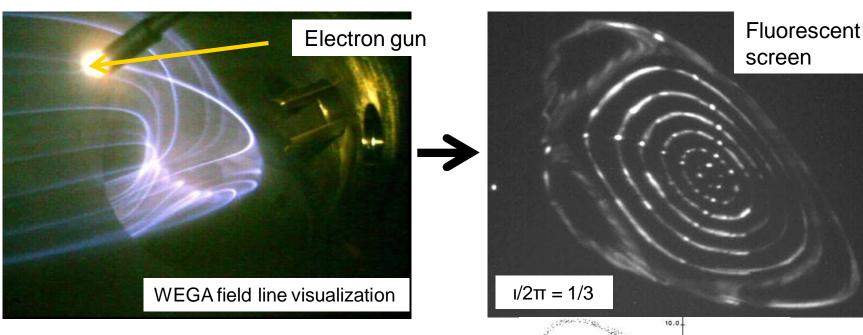
- Equilibrium determined by:
 - Radial profiles (e.g., pressure, total toroidal current J=0)
 - ⇒ Outer flux surface can be parameterized (in cylindrical coordinates (R, Z, Φ) with periodic conditions
- Boundary conditions: B tangential to surface
- **⇒** Solution of MHD equations inside surface

Field lines can be visualized using an electron beam in a hydrogen gas

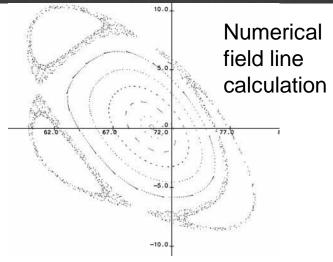


 Structures of magnetic field: shear, island, ergodic regions ⇒ shortcuts of transport to wall

There is generally no analytic proof of existence of flux surfaces in helical devices ⇒ field line tracing



 Electrons emitted parallel to B in vacuum field without plasma ⇒ fluorescent projector and interaction with (Ar) background gas



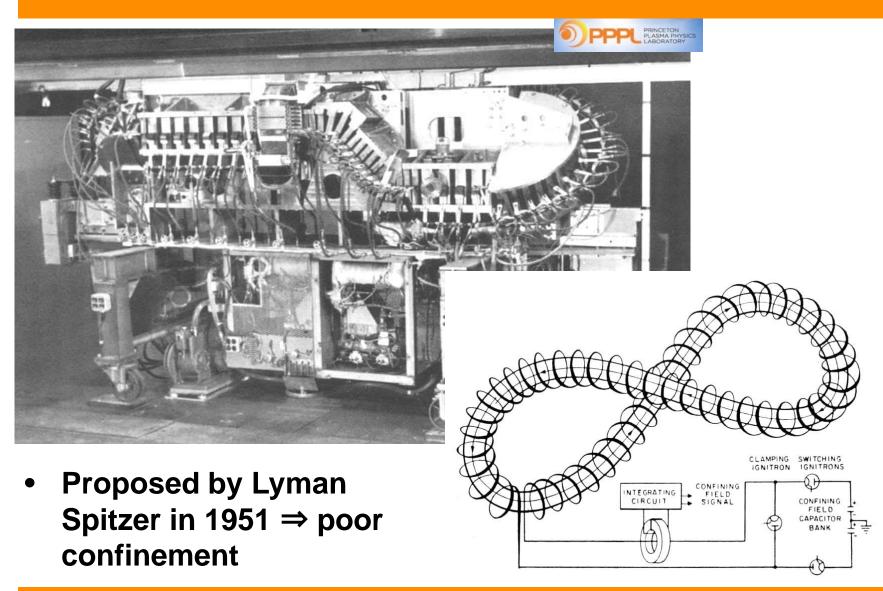
Three basic types of stellarators

All helical confinement concepts revolve around the question of how to build 3D toroidal flux surfaces

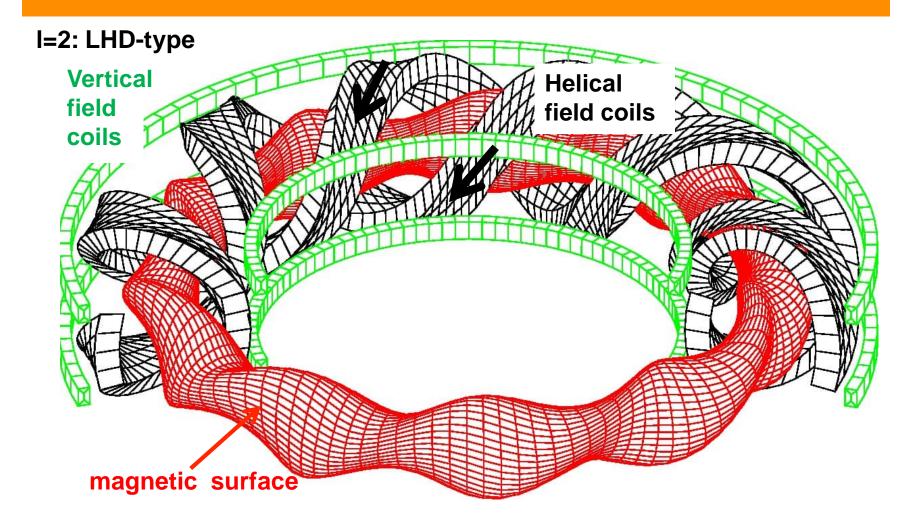
- Three basic types of systems
 - Heliotrons, "classical" stellarators, heliacs
- Principle research questions are very similar
 - Design vacuum field (and coils) w/ good flux surfaces
 - Reduce particle losses (drifts) in 3D geometry (fast particles, neoclassical transport, trapped particles) ⇒ similar to tokamaks
 - Operation at maximum density (and pressure)
- ⇒ For steady-state, additional issues, such as power exhaust and impurity control exist
- **⇒** Second-generation stellarators include modular coils



Twisting the torus and hence magnetic field produced helicity (Princeton Figure-8 stellarator)



A heliotron, or torsatron, is a stellarator with a circular axis and helically twisted coils

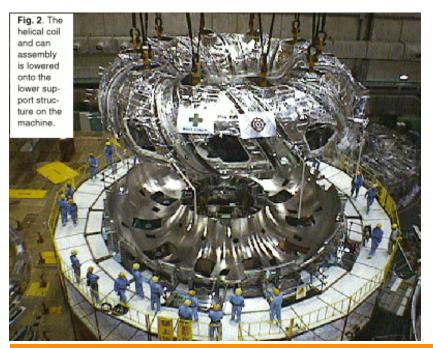


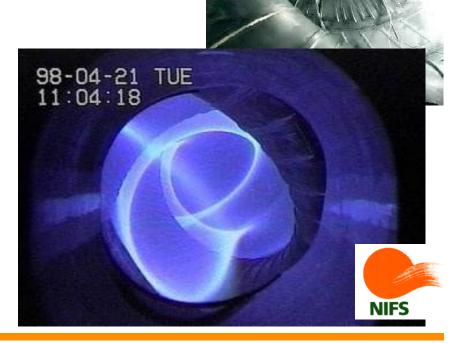
Vertical field is needed to counteract the helical field



The Large Helical Device (LHD) is an example of an heliotron

- LHD dimensions: R=3.5 to 4.1 m, volume= 28 m³
- Primary device and line of stellarator research in Japan



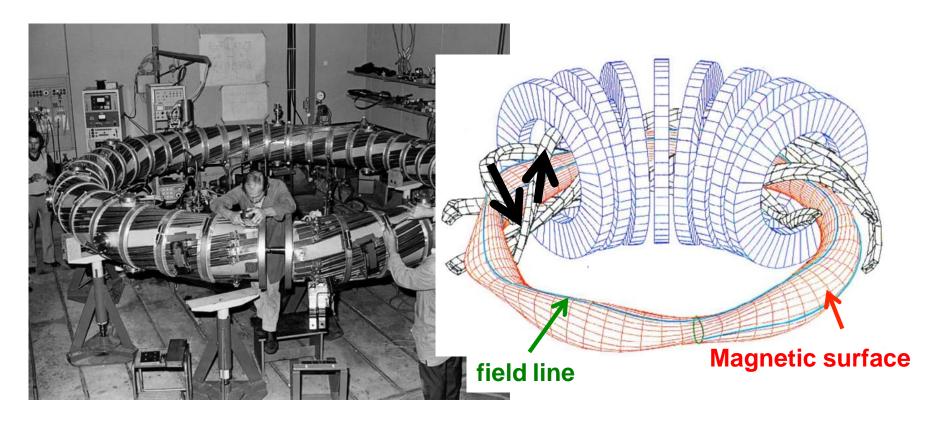


Helical coils,

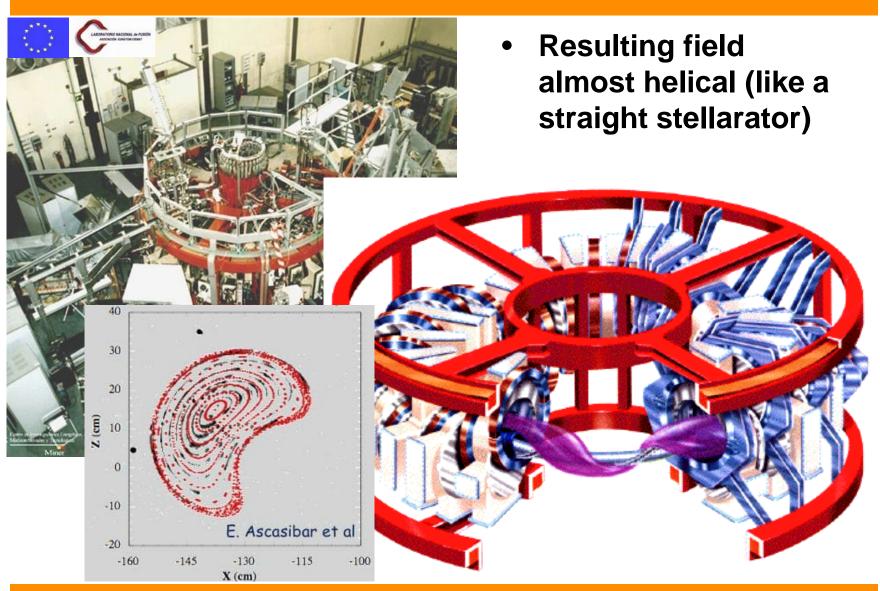
superconducting

The previous Wendelstein 7-A stellarator used both helical and toroidal coils (classic stellarator)

- Wendelstein 7-A dimensions: R=2 m, a=10cm, I=2, m=5, volume << 1 m³
- [Wendelstein family: WEGA, W7-A, W7-AS, W7-X]

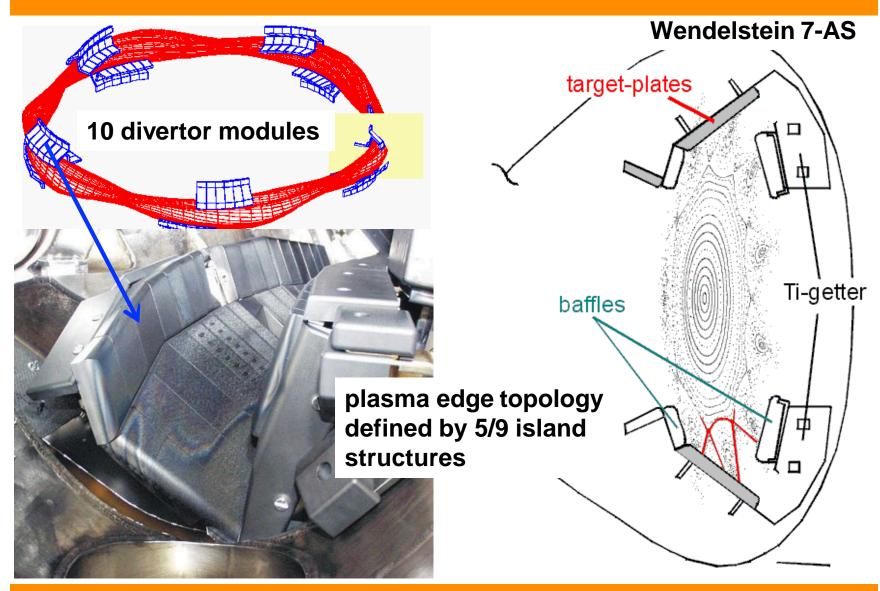


In a heliac (TJ-II, CIEMAT, Spain) the plasma is wound around a single central conductor

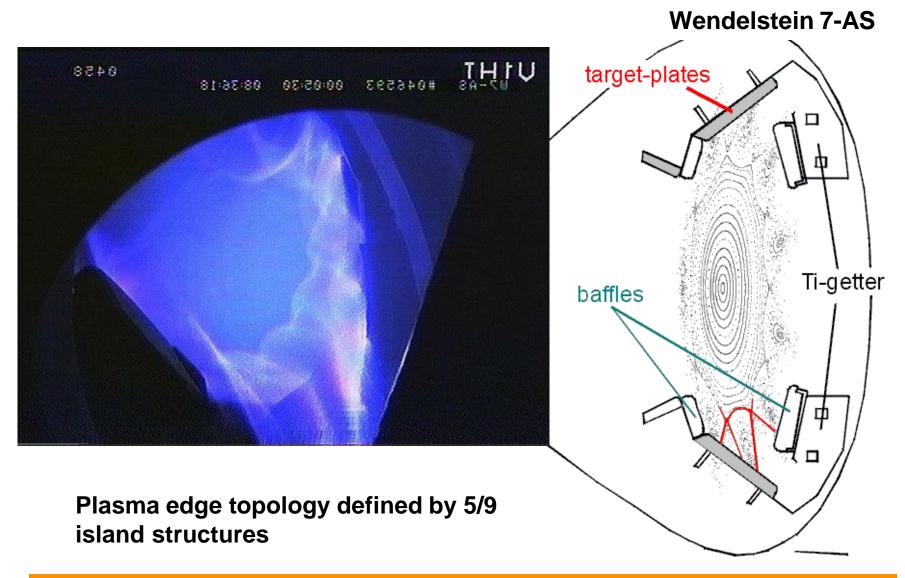




Islands in the edge can be used for energy and particle exhaust

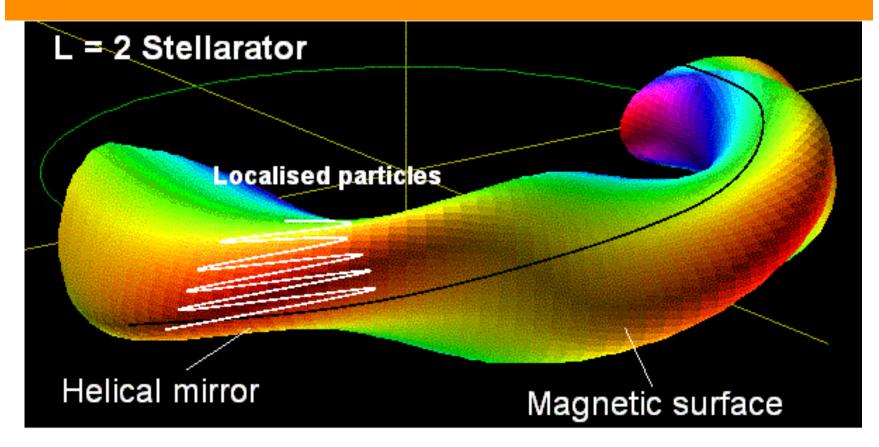


The island structure was observed with a toroidally viewing camera system



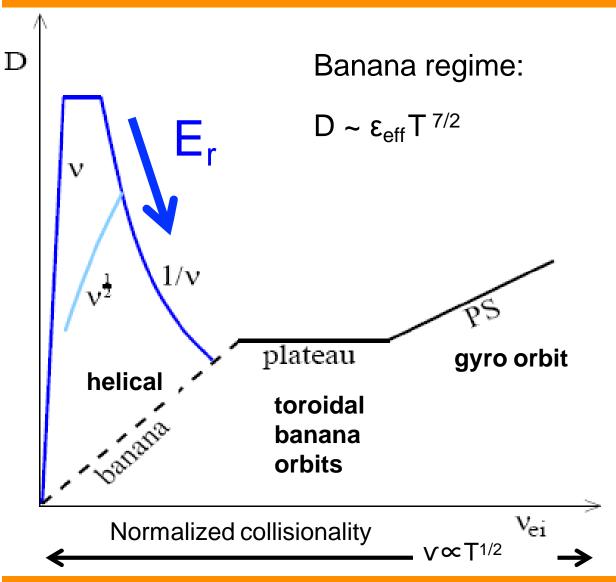
Transport processes in stellarators

Orbit drifts (in an inhomogeneous magnetic field) lead to losses of particles and energy



- Stellarators have more classes of trapped particles than tokamaks
- ⇒ (Diffusive) neoclassical transport of particles = losses

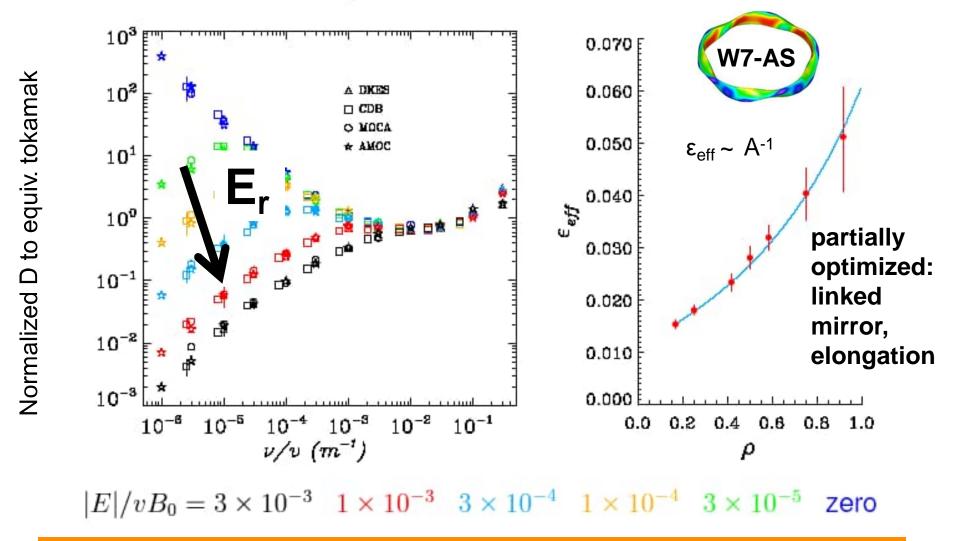
Stellarators require a strong reduction of radial convective transport to be high-performing



- Diffusion in low collisionality regime is large (ripple trapped particles)
- Radial electric field leads to de-trapping of via ExB drifts
- ⇒ Optimization of B-field (ε_{eff}) ⇒ linked mirror concept)

With increasing radial electric field (de-trapping), cross-field transport can be reduced at low collisionality

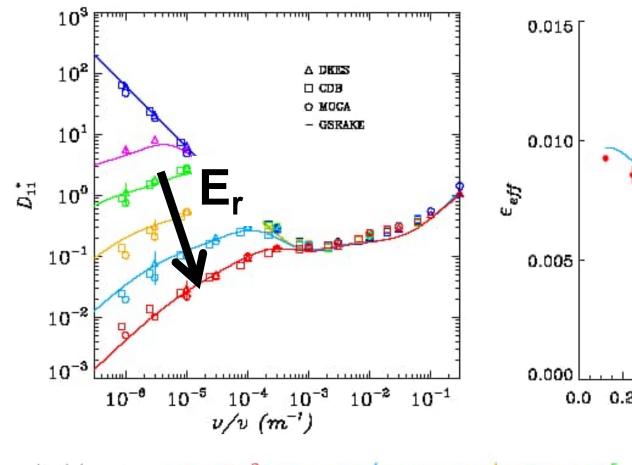
W7-AS $_{\ell} = 0.35$ Configuration

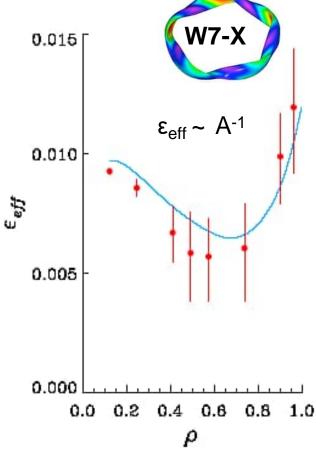


Normalized D to equiv. tokamak

In a drift-optimized stellarator (Wendelstein 7-X), neoclassical diffusion is significantly reduced

W7-X Standard Configuration

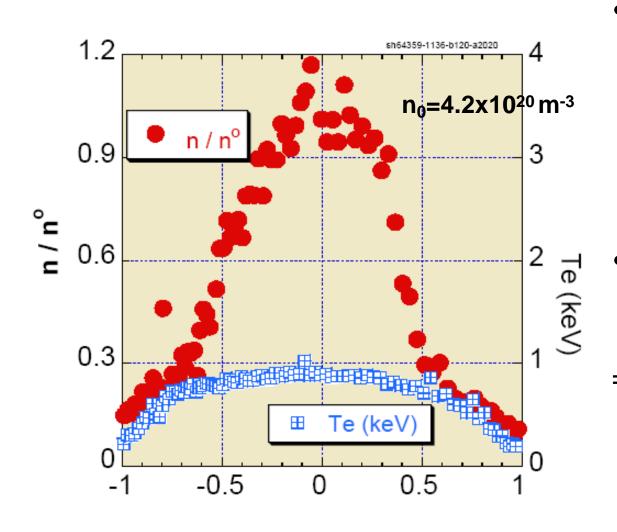




 $|E|/vB_0 = 1 \times 10^{-3}$ 3×10^{-4} 1×10^{-4} 3×10^{-5} 1×10^{-5} zero

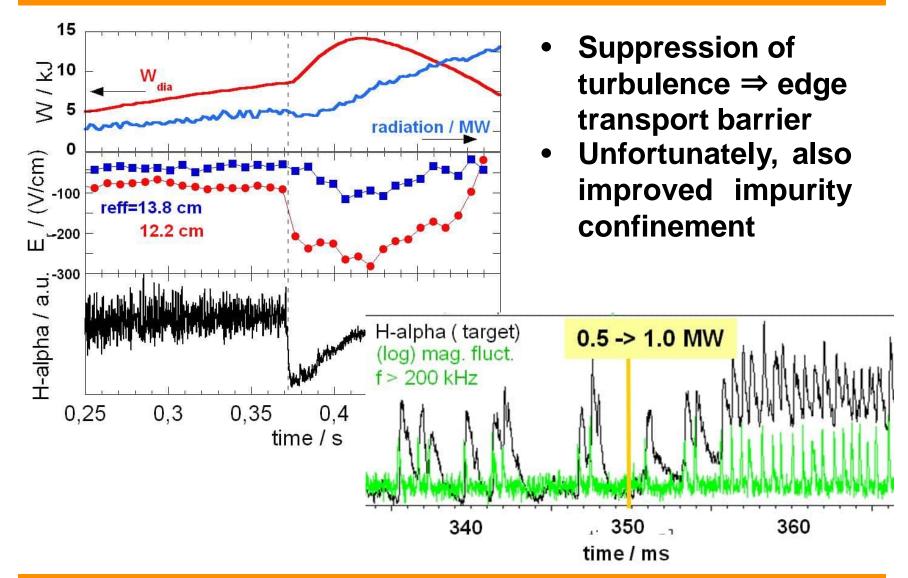


Superdense core plasmas have been obtained in the LHD stellarator



- High-density
 operation is
 preferable also in
 stellarators: fusion
 yield, confinement,
 low edge
 temperatures
- Stellarators have no disruptive density limit
- ⇒ Yet, operation still require density and impurity control

H-mode confinement and edge localized modes were also observed in stellarators (W7-AS)



Presemo quiz #1

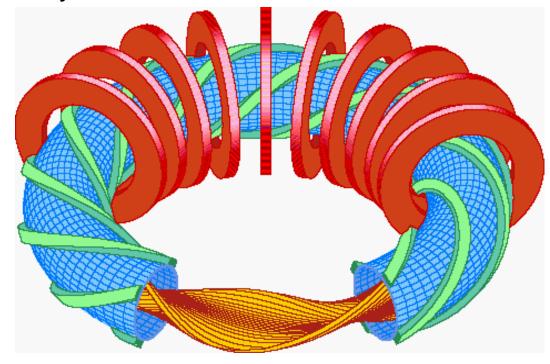
https://presemo.aalto.fi/fet/

Toward future stellarator reactors

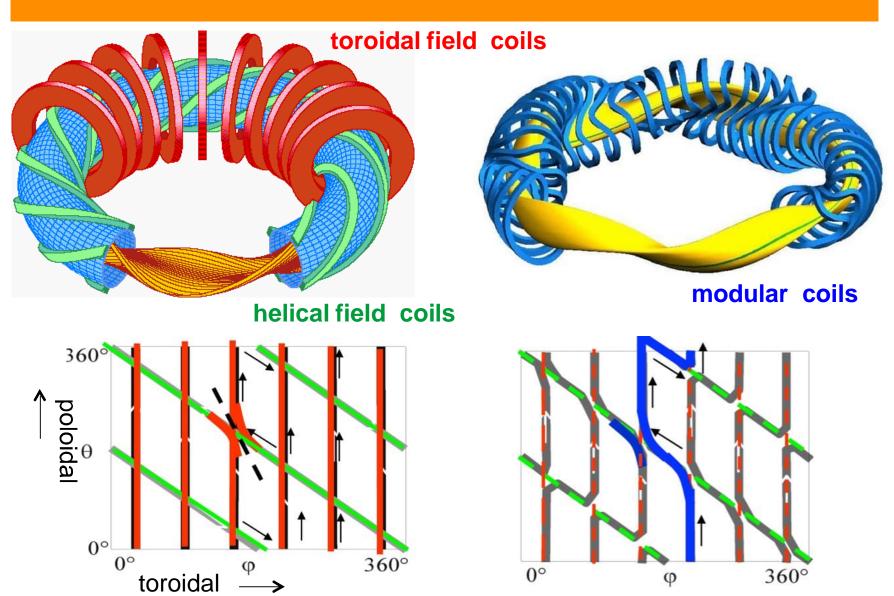
To make stellarators successful, one needs to minimize transport losses

- Steady-state capability without need for current drive
 ⇒ no current disruption
- Maintain confining field and divertor island structures even at high pressure
- High-density operation: no density limit like in tokamaks
- Collisional losses: fast particles, neoclassical transport, turbulence and flows

⇒ Option: design an optimized magnetic configuration



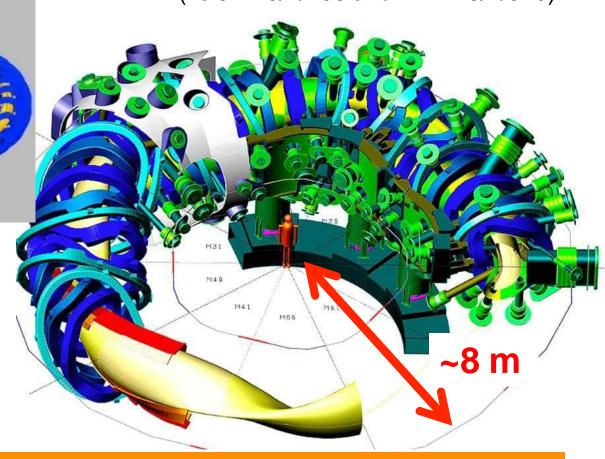
Modular coils give wider accessible Fourier distribution of currents, and 3-D shaping of axis



The Wendelstein 7-X is the first optimized superconducting stellarator

HELIAS ("pure stellarator")
 ⇒ drift-optimized

• R=5.5 m, a=0.52 m, V_{plasma} ~30 m⁻³ (vs JET 3/1/100 and ITER 6/2/840)

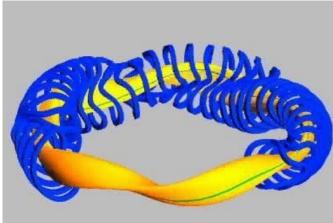


 Fully cooled invessel components and island divertor

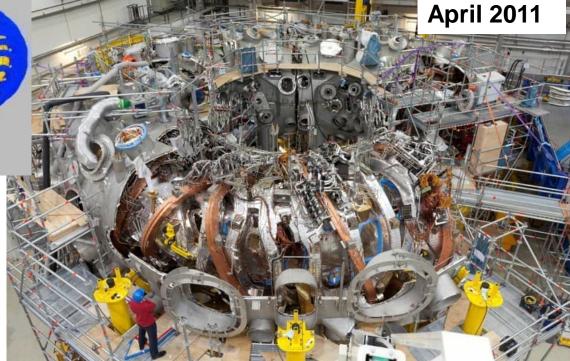
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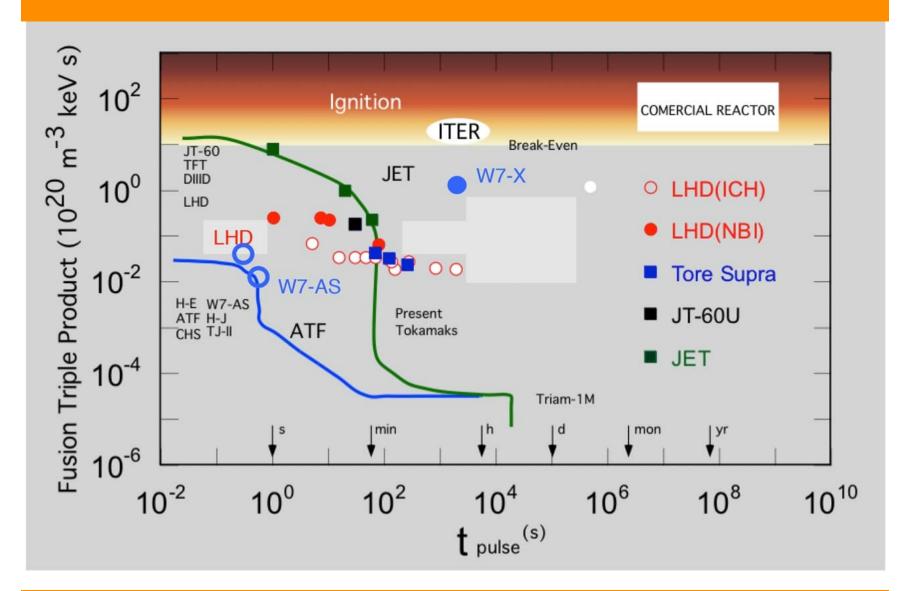
R=5.5 m, a=0.52 m, $V_{plasma} \sim 30 \text{ m}^{-3}$



 Fully cooled invessel components and island divertor

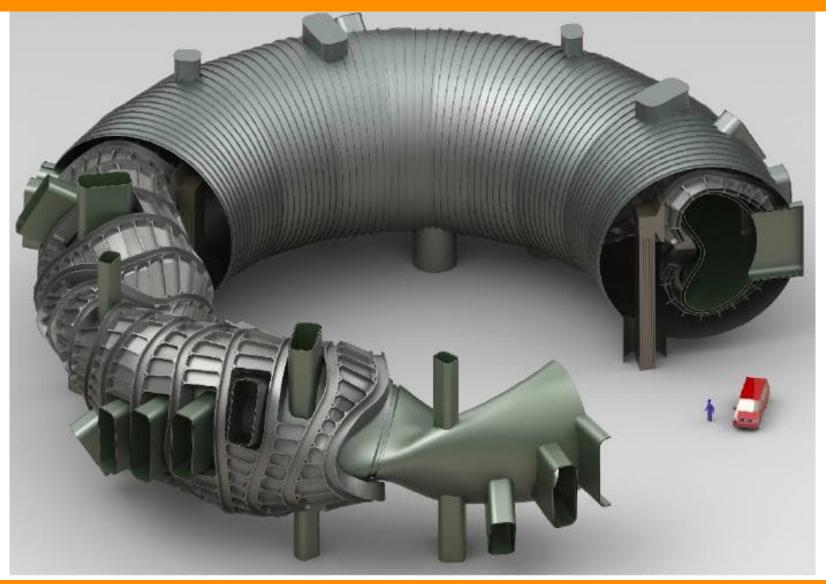


The projected performance (D-T equivalent) of W/-X is an order of magnitude lower than that of ITER





Conceptually, scientists have already been planning for future stellarator reactors



Various extensions of helical devices toward reactors exist

FFHR: R=20 m, P_{th}=3 GW

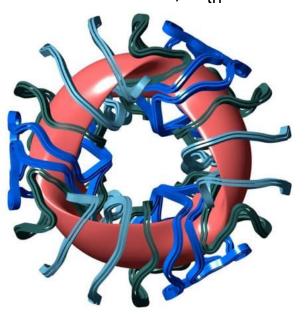
Super-conducting poloidal coils

Vacuum vessel

Support structure

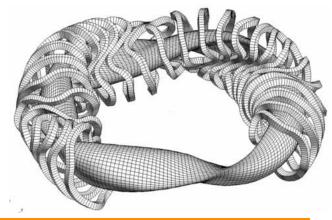
Super-conducting helical coils

ARIES-CS: R=8 m, Pth=4 GW



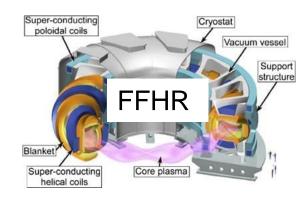
- FFHR = force free helical reactor (heliotron), based on LHD [Fus. Eng. Design 1995]
- HSR4/18: Helias reactor with four field periods, based on W7-X [Nucl Fusion 2001]
- ARIES-CS: compact stellarator [Fus. Sci and Tech. 2008]

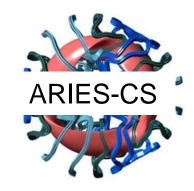
HSR4: R=18 m, P_{th}=3 GW



Stellarator specific reactor issues

- + Steady-state ⇒ reduced fatigue effects
- + No current drive ⇒ low recirculating power (CD, SC, pulse length, beta → net electricity)
- Mechanical forces between coils requiring heavy support structure
- Limited space between plasma edge and coil in certain locations for blanket and shielding
- **⇒** Going to larger R usually helps







Is a stellarator reactor better than a tokamak reactor? In other words, who's winning the race?

- Costs are significant why paying twice?
- ⇒ Total investment into W7-X (1997-2014) = 1.1 bn €, EU for ITER until 2022 = 8 bn €
- ⇒ EU fusion strategy for W7-X is not considered relevant for ITER, but for DEMO
- Will there be more than one DEMO?
- ⇒ ITER + JT60-SA + (Chinese study) are steps toward DEMO tokamak
- ⇒ Korea, Japan and China have built superconducting tokamaks

Is a stellarator reactor better than a tokamak reactor? In other workds, who's winning the race?

- ⇒ US government stopped National Compact Stellarator Experiment (NCSX), a quasi toroidal LN2 cooled device, but also terminated Alcator C-mod ⇒ focus on ITER
- ⇒ In Japan, there is not yet a decision on a follow-up device to LHD
- Can we gain from the synergy between tokamaks and stellarators?
- ⇒ Tokamak research is better organized, focus on ITER
- ⇒ Stellarator research need more devices to cover the many concepts
- **⇒ Will failure of ITER make way for stellarator?**

Cost of fusion power plant and electricity

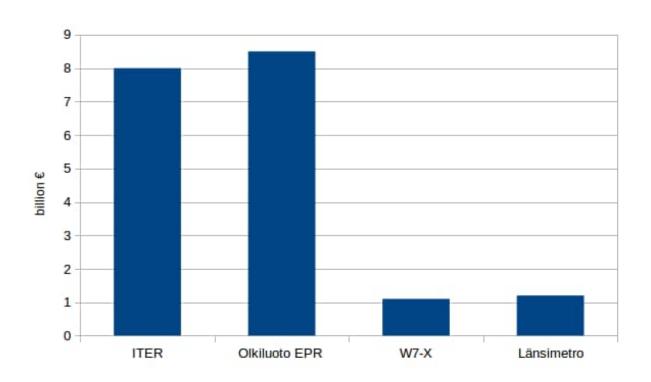
W7-X staff and funding profile



- W7-X team ~380 people, not including visitors and support personnel
- Total investment between 1997-2014 ~1.1 bn €(370 m€ device, 100 m€ buildings, 310 m€staff)
- 25% funding from EU, 75% German and regional government
- 2nd operational phase now ongoing (delay due to Covid-19)



Project costs: ITER and W7-X vs. Olkiluoto and Länsimetro





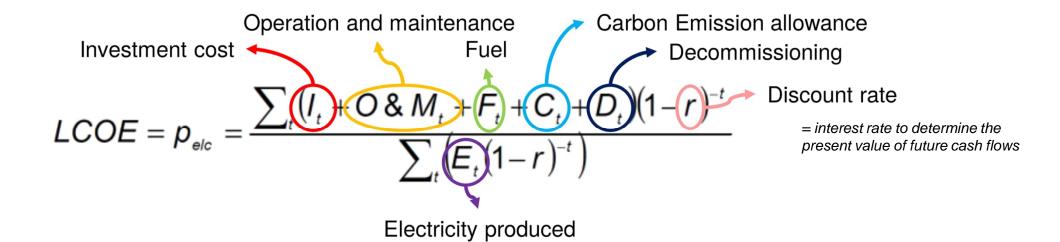
- a) EU for ITER until 2022 = 8 bn € (or: total constraction costs 20 bn\$ compared to original estimate 5 bn\$ and full power 2027 compared to original estimate 2016)
- b) Finland: Olkiluoto EPR fission power plant, "first of a kind": 8.5 billion €, starts 2020 (compare to original estimate 3.2 billion €, starts 2009)
- c) Total investment into W7-X (1997-2014) = 1.1 bn€ (0.37 bn€ device, 0.1 bn€ buildings, 0.31 bn€ staff; started 2015, not e.g. 2004)
- d) Finland: Länsimetro underground (via Otaniemi): first phase costed 1.2 bn€ (2008 accepted budget 0.7 bn€)



Cost of fusion electricity depends on...

- Investment cost depends on machine size expecially for large reactors
- for <r> ≈ plasma coil spacing further reduce of size does not help much (for a given P_{output})
 - a) higher loads on components
 - b) tighter spaces for maintenance
 - c) other engineering constraints
 - → a larger extrapolation from current technology required
- Cost of electricity also depends on the availability of power plant (→ replacement of components), learning factor, cost of materials and technological development

Cost of fusion electricity depends on...



In fusion ~ 70 % cost of capital, 3% O&M, 25% blanket and divertor replacement, ~ 1% Fuel, < 1% Decommissioning

Bustreo, ETSAP meeting 2013

Example: ARIES-CS Power-Plant Investment Cost

TABLE II

ARIES-CS Power Plant Economic Parameters (2004 \$)*

Account Number	Account Title	Million Dollars
20	Land and land rights	12.9
21	Structures and site facilities	336.1
22	Reactor plant equipment	1538.9
22.1.1	First wall/blanket/reflector	59.4
22.1.2	Shield	228.6
22.1.3	Magnets	222.9ª
22.1.4	Supplemental heating/current drive systems	66.4
22.1.5	Primary structure and support	73.1
22.1.6	Reactor vacuum systems (unless integral elsewhere)	137.1
22.1.7	Power supply, switching, and energy storage	70.6
22.1.8	Impurity control	6.6
22.1.9	Direct energy conversion system	0.0
22.1.10	Electron cyclotron resonance heating breakdown system	0.0
22.1	Reactor equipment	864.7
22.2	Main heat transfer and transport systems	474.8
23	Turbine plant equipment	314.6
24	Electric plant equipment	138.8
25	Miscellaneous plant equipment	71.0
26	Heat rejection system	56.1
27	Special materials	151.3
90	Direct cost (not including contingency)	2620.0
	Total COE (¢/kW·h)	7.76 ^b

^{*}No cost penalty has been assumed for manufacturing of complex components. For example, applying a 25% cost penalty to major components (blanket, shield, and coils) increases the COE by 0.37 ¢/kW·h.

Najmapadi et al, Fusion Science and Technology / Volume 54 / Number 3 / October 2008 / Pages 655-672



^aAssumes coil support structure is fabricated by advanced manufacturing techniques.

bAssumes an 85% availability (similar to ARIES-AT).

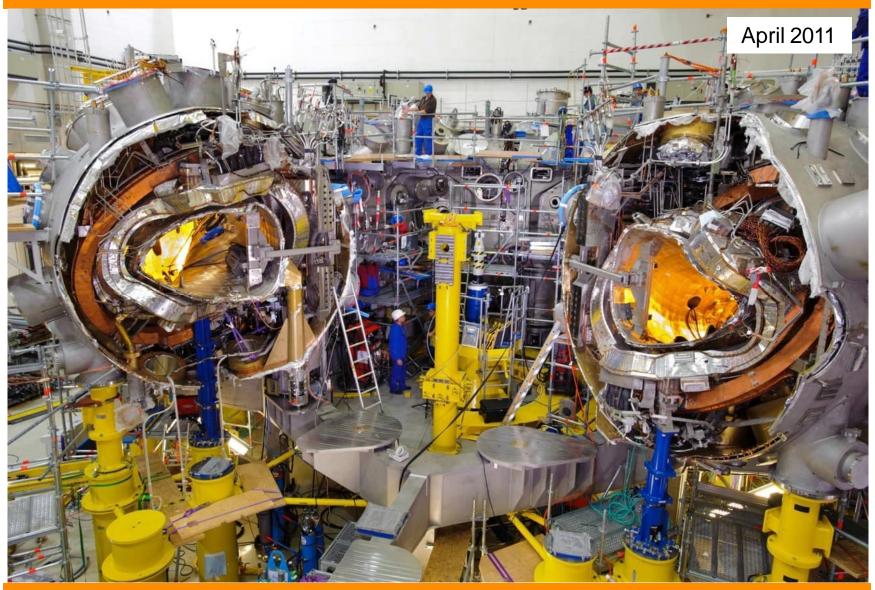
The Wendelstein 7-X project

The Wendelstein 7-X project at the Institute for Plasma Physics in Greifswald, Germany

Video of construction work for those who are interested (same information is in following slides): Construction W7-X (1.21 s)

Longer (5min) video will be shown later in this lecture

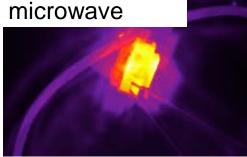
The Wendelstein 7-X project at the Institute for Plasma Physics in Greifswald, Germany





Long-pulse operation requires actively cooled wall elements in the divertor

Mirnov magnetic coil exposed to microwave



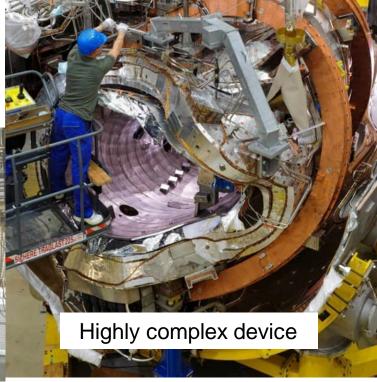
microwave launcher



1 MW gyrotron







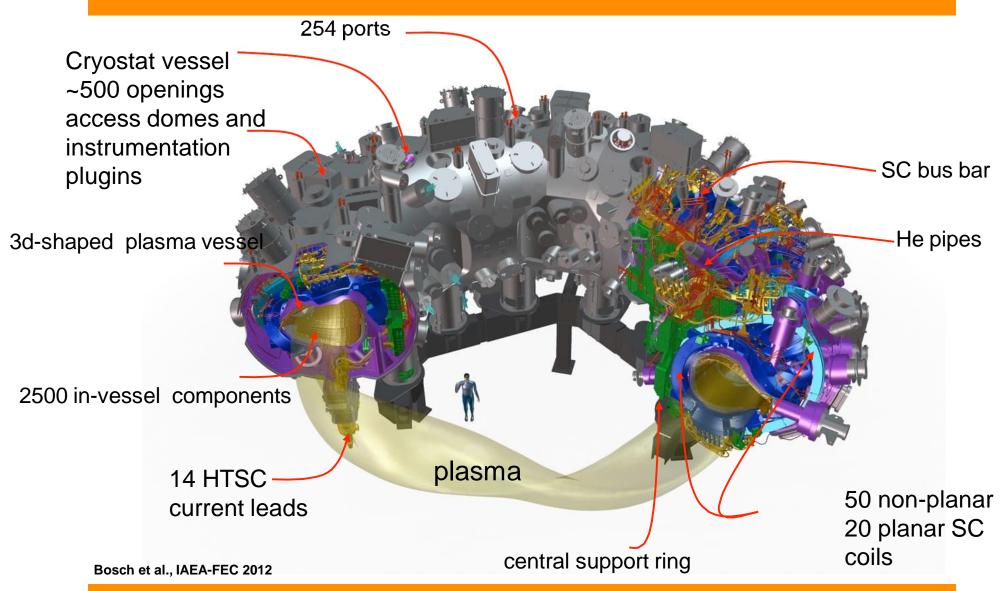
The vacuum vessel follows the twist of the desired plasma



Design, fabrication and testing of modular superconducting coils was a major challenge



Integration of the coil / vessel system into a cryostat is a significant engineering challenge



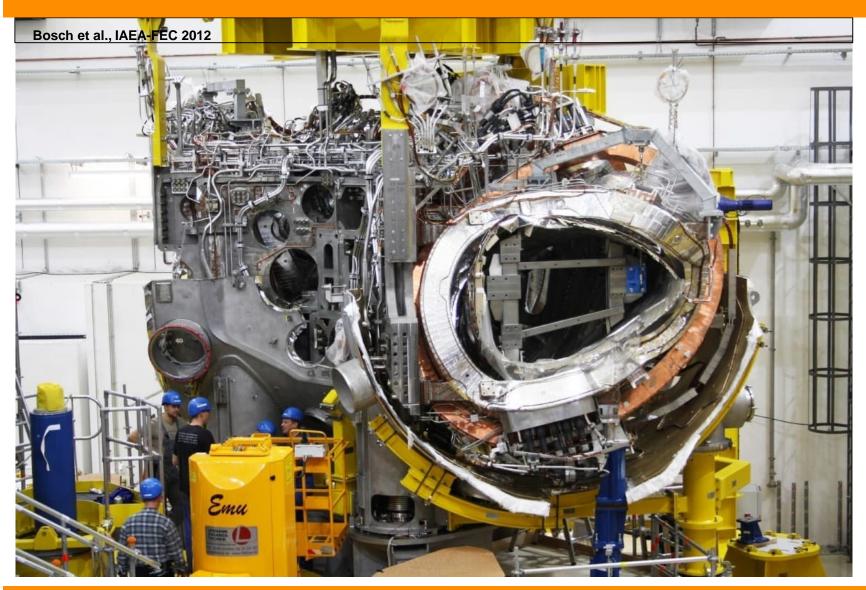


The Wendelstein 7-X hall in 2006

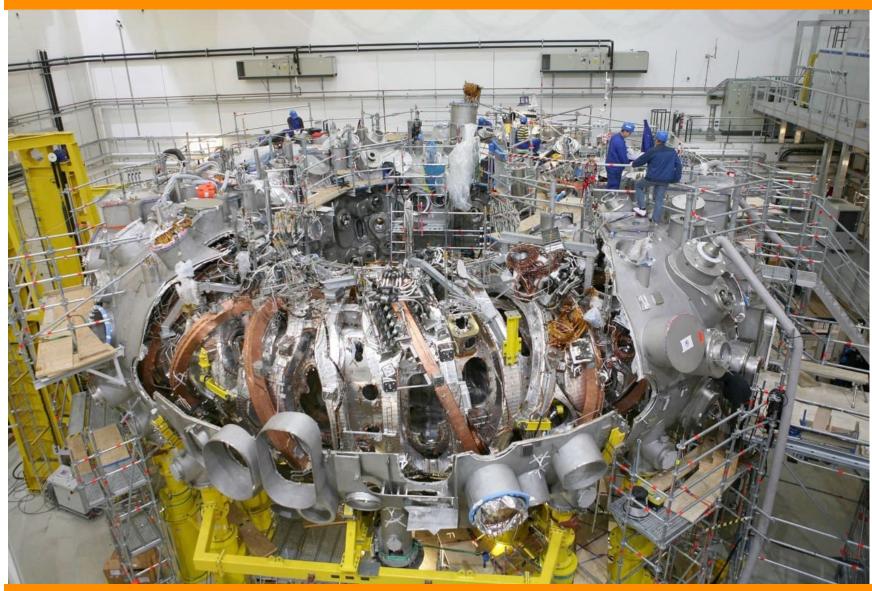




First magnetic assembly in cryostat of the W7-X stellarator started in October 2009



The Wendelstein 7-X hall in early 2013





The Wendelstein 7-X hall in August 2013

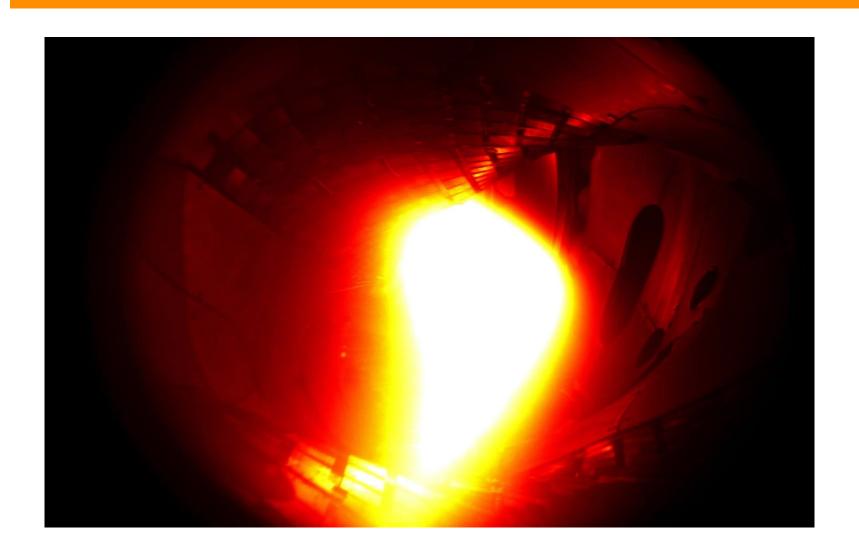




Assembly of Wendelstein 7-X completed in June 2014 → start of extensive commisioning



The first (He) plasma in Wendelstein 7-X was obtained on December 10, 2015 (100 ms long)

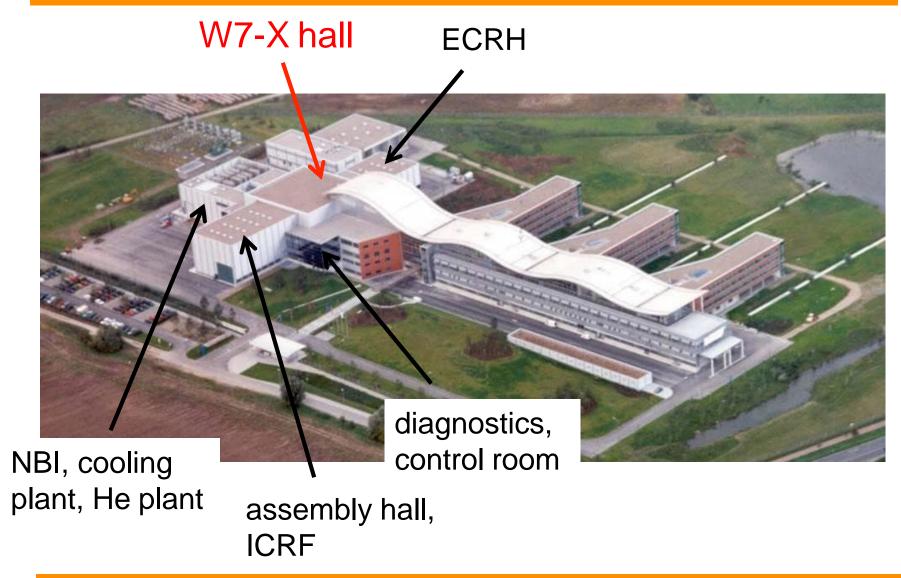


Angela Merkel switches on Wendelstein 7-X fusion device (first hydrogen plasma in Feb 2016)

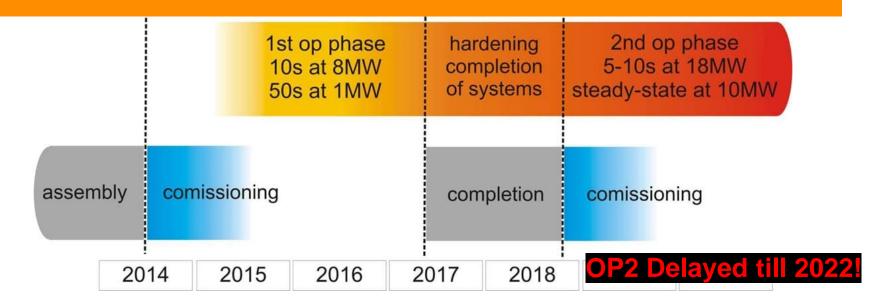




W7-X is hosted by the Institute for Plasma Physics in Greifswald, Germany (project since 1994)



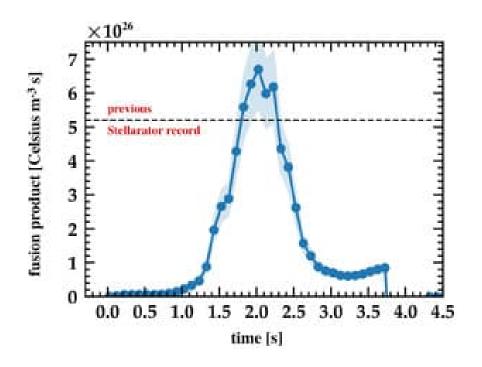
The 1st operation phase of W7-X is to verify the stellarator optimization and develop integrated high-density scenario

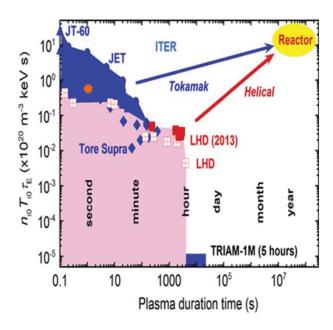


- Commissioning of vacuum vessel, magnetic field, field line tracing, plasma startup ⇒ first plasma Dec-2015
- 1st operation phase with inertially cooled divertor, some in-vessel components cooled
- No provision for D-T operation
- Last divertor plates installed June 2021



New world record in stellarator fusion product in W7-X (press release 25.6.2018)





Compare to LHD result (Takeiri, IEEE Trans. Plasma Science, 2018)

• Fusion product 6 x 10^{26} Celsius m⁻³ s ≈ 0.5 x 10^{20} keV m⁻³ s was received with at Ti = 40000000 K (> 3 keV) and n_i = 0.8 x 10^{20} m⁻³

Ongoing campaign OP.2 (press release 14.9.2022)

- 120 new divertor modules with a cooling system
 - → operation at significantly higher plasma energies possible
- New or upgraded heating systems more than doubling output power:
 - > the new ICRH system (up to P=1.5 MW)
 - ➤ NBI system with doubled heating power up to P=7 MW
 - ECRH system upgraded to 10 MW
- Injected energy (power × duration): so far max 75MJ, present OP.2 goal ≈1GJ, long term goal 18GJ (30 min discharge)

Video + Presemo quiz #2

Video: W7-X fusion device (5min 42s)

https://presemo.aalto.fi/fet/

Quiz questions are mainly about the video so you can do quiz during or after the video

Summary

- The equilibrium in a stellarator is established by external coils only (3D) ⇒ can naturally be operated in steady-state and no current-driven disruptions
- Good nested flux surfaces with small islands can be obtained, even at high plasma pressure ⇒ island divertor for heat exhaust
- Loss of axisymmetry results in additional loss mechanism for particles and energy (fast particles, alphas)
 - ⇒ potentially be reduced by field optimization
- Stellarators can be operated at high-density without impurity accumulation
- Wendelstein-7X started plasma operation in Dec-2015

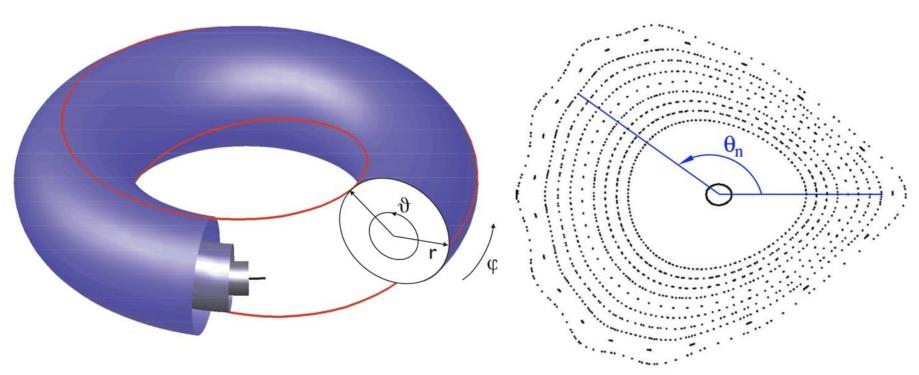


Reserve material

Rotational transform defines closed field lines (rational iota) and ergodic regions (irrational iota)

Tokamak

Stellarator (Poincare plot)



$$q(r) = \frac{r BT(r)}{R Bp(r)}$$

Inverse



$$\iota \equiv \lim_{n \to \infty} \frac{\theta_n}{2\pi n}$$

Parameterize magnetic geometry in a straightenout stellarator of pitch k

Assume helical symmetry:

$$B = B(r, \mathcal{G} - kz)$$

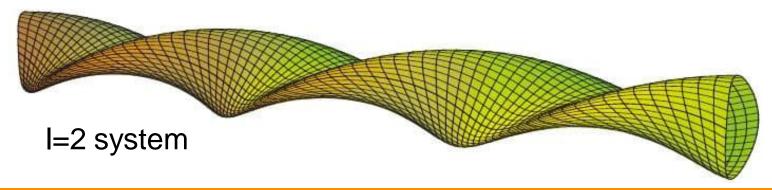
Vacuum field only: (pressure = 0)

$$\Phi = B_0 z + \frac{1}{k} \sum_{l=1}^{\infty} b_l I_l(\text{lkr}) \sin \left[I(\vartheta - \text{kz}) \right]$$

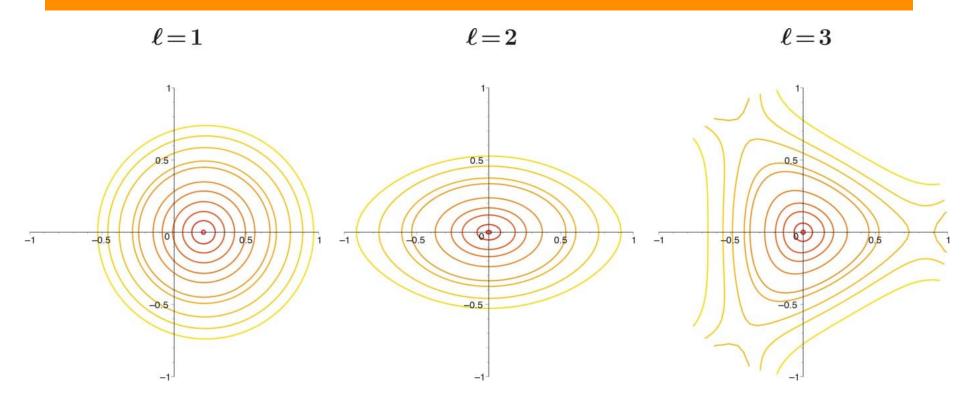
$$Mod. \ Bessel$$

$$function I_l(\text{lkr})$$

 $\Rightarrow Flux surfaces: \quad \Psi = B_0 \frac{kr^2}{2} - r \sum_{l=1}^{\infty} b_l I_l(lkr) \cos [l(9-kz)]$ = const



The Bessel function parameter I determines the dominant helical harmonic



- I=1 systems: shifted circles
- I=2 systems: elliptical with the center on-axis
- I=3 systems: triangular shape