





$$Y = A \cdot K^\alpha L^{1-\alpha}$$

$$0 < \alpha < 1$$

\Rightarrow

$$\frac{Y}{L} = A \cdot K^\alpha \cdot L^{-\alpha}$$

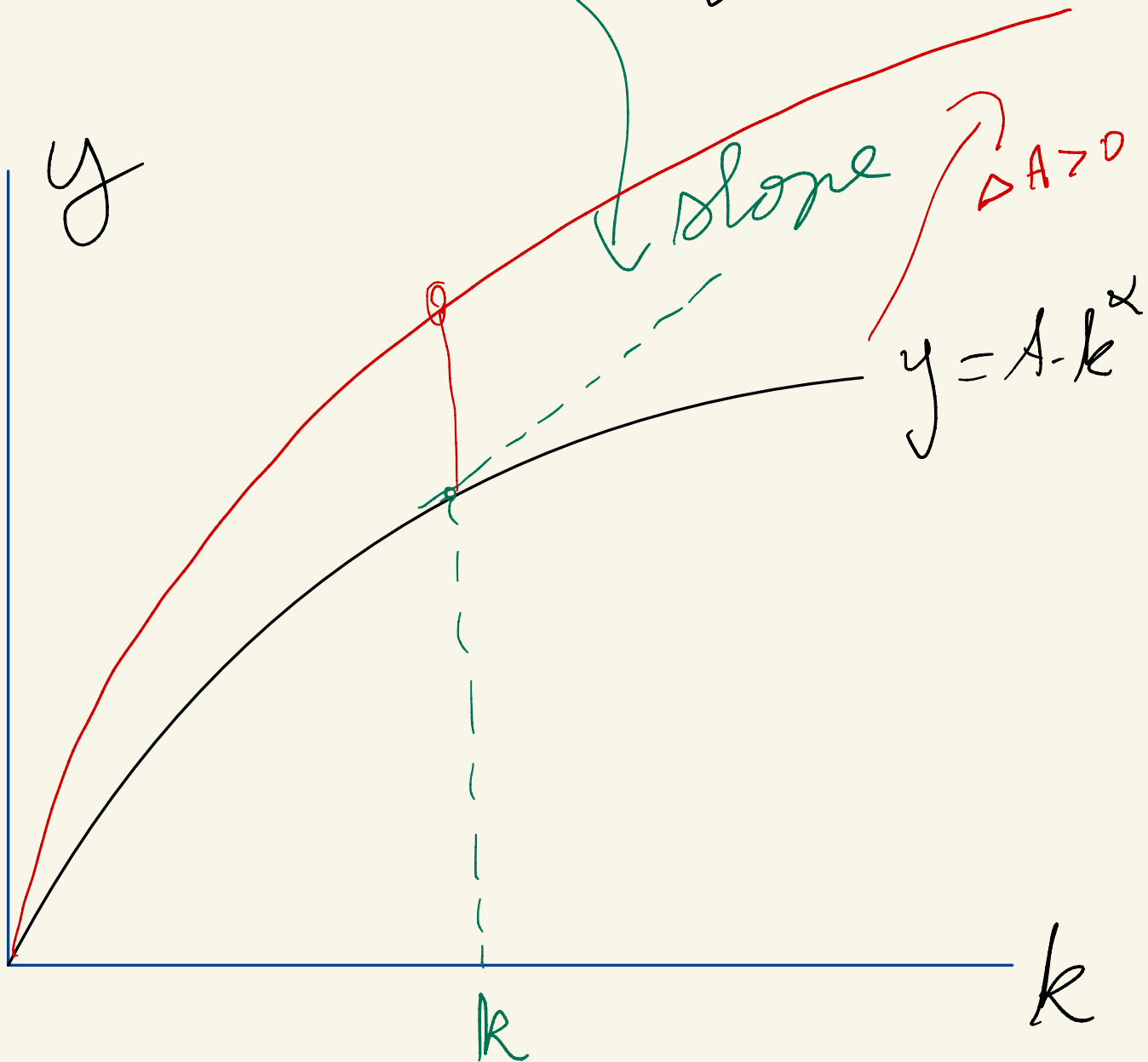
\Rightarrow

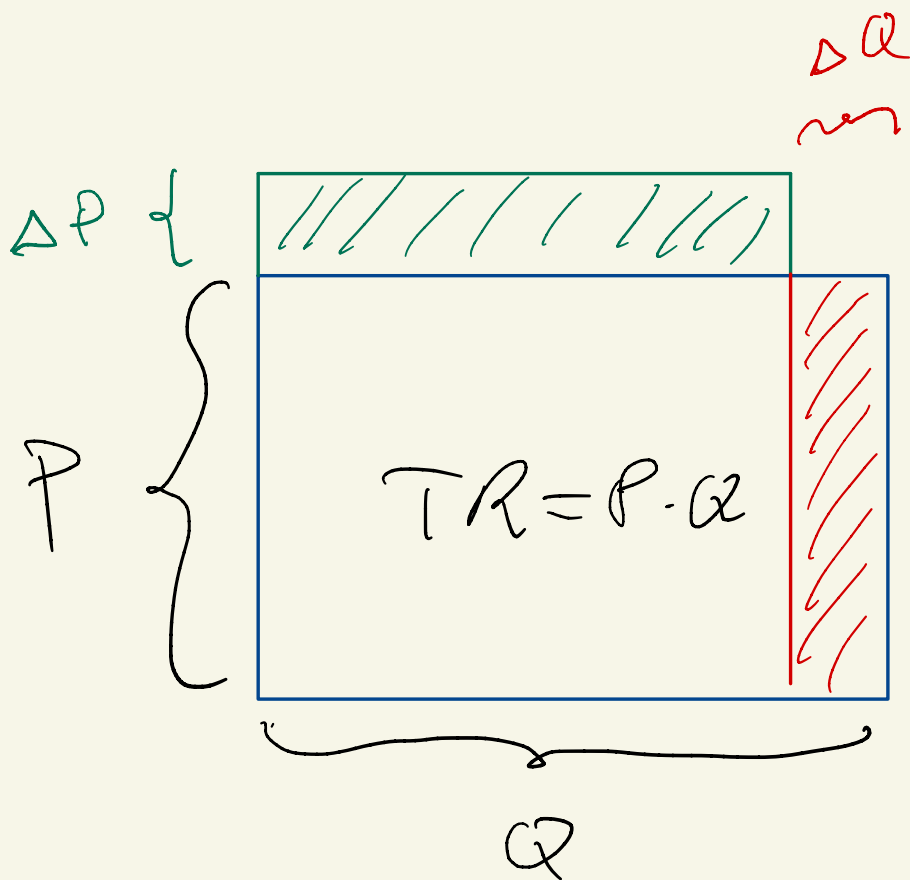
$$y = A \cdot \left(\frac{K}{L} \right)^\alpha = A \cdot k^\alpha$$

\Rightarrow

$$y = A \cdot k^\alpha$$

$$MPK = \frac{\partial y}{\partial k} = \alpha \cdot A k^{\alpha-1}$$





$$\Delta TR = \Delta P \cdot Q + P \cdot \Delta Q$$

\Rightarrow

$$\frac{\Delta TR}{\Delta Q} = P \cdot \left[\frac{\Delta P}{P} \cdot \frac{Q}{\Delta Q} + 1 \right]$$

$$= \frac{1}{\epsilon}$$

$$= P \cdot \left[1 + \frac{1}{\epsilon} \right]$$

$$TR = (P - C) \cdot Q$$

$$\frac{\Delta TR}{\Delta Q} = \frac{\Delta P \cdot Q}{\Delta Q} + (P - C) \cdot \cancel{Q}$$

$$= P \cdot \left[\underbrace{\frac{\Delta P}{P} \cdot \frac{Q}{\Delta Q}}_{= \frac{1}{\epsilon}} + \underbrace{\frac{P - C}{P}} \right]$$

Optimum:

$$\frac{P - C}{P} = -\frac{1}{\epsilon}$$