

Taylor series for $x \in \mathbb{R}$ at $x = \omega$

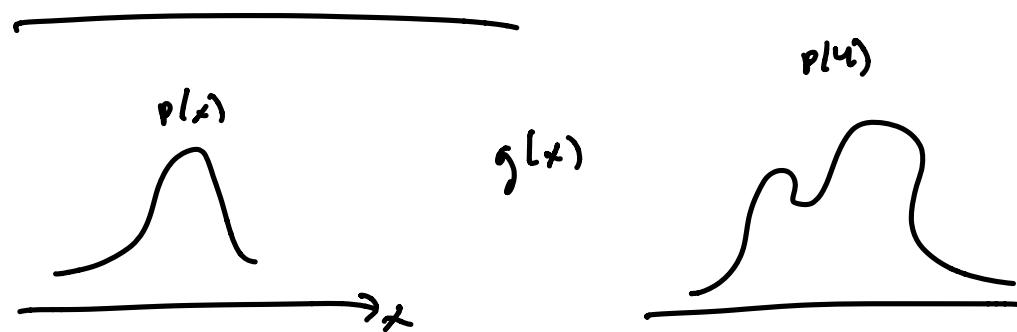
$$f(x) = f(\omega) + f'(\omega)(x - \omega) + \frac{1}{2!} f''(\omega)(x - \omega)^2 + \dots$$

Taylor series for $x \in \mathbb{R}^n$ $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $x = \omega$:

$$\tilde{f}(\vec{x}) = \tilde{f}_\omega(\vec{\omega}) + \underbrace{(\nabla f_\omega)^T(\vec{x} - \vec{\omega})}_{+ \frac{1}{2} (\vec{x} - \vec{\omega})^T (\nabla^2 f_\omega) (\vec{x} - \vec{\omega})} + \dots$$

Linear approximation: $\left\{ \begin{array}{l} \text{Jacobi matrix} \\ f_x = \begin{pmatrix} \nabla f_\omega^1 \\ \nabla f_\omega^2 \\ \vdots \\ \nabla f_\omega^m \end{pmatrix} \end{array} \right.$

$$\tilde{f}(\vec{x}) \approx \tilde{f}(\vec{\omega}) + F_x(\vec{\omega})(\vec{x} - \vec{\omega})$$



$x \sim N(\mu, \rho)$

$$g(x) \approx g(\omega) + C_x(\omega)(x - \omega)$$

$$\mathbb{E}[g(x)] \approx \mathbb{E}[g(\omega) + C_x(\omega)(x - \omega)]$$

$$\left. \begin{aligned} &= g(\omega) + G_x(\omega) \underbrace{E[g(x-\omega)]}_{=0} \\ &= g(\omega) \end{aligned} \right\}$$

$$\begin{aligned} \text{Cov}[g(x)] &= E[(g(x) - E[g(x)]) (\cdot)^T] \\ &\approx E[(g(x) - g(\omega)) (g(x) - g(\omega))^T] \\ &\approx E[(g(x) + G_x(\omega)(x-\omega) - g(\omega)) \\ &\quad (g(\omega) + G_x(\omega)(x-\omega) - g(\omega))^T] \\ &= E[G_x(\omega)(x-\omega)(x-\omega)^T G_x^T(\omega)] \\ \xrightarrow{x \sim N(\mu, P)} &= G_x(\omega) \underbrace{E[(x-\omega)(x-\omega)^T]}_P G_x^T(\omega) \\ &= G_x(\omega) P G_x^T(\omega) \end{aligned}$$

linear: $x \sim N(\mu, P)$

$$y = y_x + g, \quad g \sim N(0, Q)$$

non-linear:

$$\begin{aligned} x &\sim N(\mu, P) \\ g &\sim N(0, Q) \\ y_1 &= x \\ y_2 &= g(x) + g \end{aligned}$$

$$E[\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}] = E\left[\begin{pmatrix} x \\ g(x) + g \end{pmatrix}\right] \approx \begin{pmatrix} \mu \\ g(\mu) \end{pmatrix}$$

$$\text{Cov}\left(\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}\right) = E\left[\left(\frac{x - E(x)}{\sqrt{G_x(x) + g(x)}}\right)\left(\frac{x - E(x)}{\sqrt{G_x(x) + g(x)}}\right)^T\right]$$

$$\approx E \left[\begin{pmatrix} x - \omega \\ g(x) + q - g(\omega) \end{pmatrix} \begin{pmatrix} x - \omega \\ g(x) + q - g(\omega) \end{pmatrix}^T \right]$$

$$= E \left[\begin{pmatrix} (x - \omega)(x - \omega)^T & (x - \omega)(g(x) + q - g(\omega))^T \\ (g(x) + q - g(\omega))(x - \omega)^T & (g(x) + q - g(\omega))(\cdot)^T \end{pmatrix} \right]$$

$$\Rightarrow E[(x - \omega)(x - \omega)^T] = P$$

$$E[(g(x) + q - g(\omega))(x - \omega)^T]$$

$$\approx E[(g(x) + b_x(\omega)(x - \omega) + q - g(\omega))(x - \omega)^T]$$

$$= E[b_x(\omega)(x - \omega)(x - \omega)^T]$$

$$+ E[q(x - \omega)^T] = b_x E[(x - \omega)(x - \omega)^T]$$

$$= b_x P$$

$$E[(g(x) + q - g(\omega))(g(x) + q - g(\omega))^T]$$

$$\approx E[(g(x) + b_x(\omega)(x - \omega) + q - g(\omega))^T]$$

$$(g(x) + b_x(\omega)(x - \omega) + q - g(\omega))^T$$

$$= E[b_x(\omega)(x - \omega)(x - \omega)^T b_x^T(\omega) + q q^T]$$

$$= b_x P b_x^T(\omega) + Q$$

$$x_{k-1} \sim N(m_{k-1}, P_{k-1})$$

$$x_k = f(x_{k-1}) + q_{k-1}, \quad q_{k-1} \sim N(0, Q_{k-1})$$

$$\begin{pmatrix} x_{k-1} \\ x_k \end{pmatrix} \sim N \left(\begin{pmatrix} m_{k-1} \\ f(m_{k-1}) \end{pmatrix}, \begin{pmatrix} P_{k-1} & P_{k-1} F_x^T(m_{k-1}) \\ F_x(m_{k-1}) P_{k-1} & \downarrow \\ & F_x(m_{k-1}) P_{k-1} \\ & \cdot F_x^T(m_{k-1}) \end{pmatrix} \right)$$

marginal of x_k : $+ Q_{k-1}$

$$x_k \sim N \left(\underbrace{f(u_{k-1})}_{\bar{m}_k}, \underbrace{F_x(\cdot) P_{k-1} F_x^T(\cdot) + Q_{k-1}}_{P_k^-} \right)$$

$$x_k \sim N(\bar{m}_k, P_k^-)$$

$$y_k = h(x_k) + r_k, \quad r_k \sim N(0, R_k)$$

$$\begin{pmatrix} x_k \\ y_k \end{pmatrix} \sim N \left(\begin{pmatrix} \bar{m}_k \\ h(\bar{m}_k) \end{pmatrix}, \begin{pmatrix} P_k^- & P_k^- H_x^T(\bar{m}_k) \\ H_x(\bar{m}_k) P_k^- & H_x(\bar{m}_k) P_k^- H_x^T(\bar{m}_k) + R_k \end{pmatrix} \right)$$

\bar{m}_k

$$x_k | y_k \sim N \left(\bar{m}_k + P_k^- H_x^T(\bar{m}_k) \begin{pmatrix} -1 \\ (y_k - h(\bar{m}_k)) \end{pmatrix}, P_k^- - P_k^- H_x^T(\bar{m}_k) \begin{pmatrix} -1 \\ (y_k - h(\bar{m}_k)) \end{pmatrix} P_k^- \right)$$

$$S_k = H_x(\bar{m}_k) P_k^- H_x^T(\bar{m}_k) + R_k$$

$$K_k = P_k^- H_x^T(\bar{m}_k) S_k^{-1}$$

$$u_k = \bar{m}_k + K_k (y_k - h(\bar{m}_k))$$

$$P_k^- = P_k^- - K_k S_k K_k^T$$