

CS-E4070 — Computational learning theory Slide set 05 : weak and strong learning

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### reading material

• K&V, chapter 4

#### what we have seen so far

 strong learning: an algorithm A is a strong learner of a concept class C, if for every concept c ∈ C, every distribution D, and every ε > 0 and δ ∈ (0, 1), the algorithm A outputs a hypothesis h ∈ C that satisfies

 $error_{\mathcal{D}}(h) \leq \epsilon$ 

with probability at least  $1 - \delta$ .

### interesting to consider

weak learning: an algorithm A is a weak learner of a concept class C, if there exists a fixed ε<sub>0</sub> and δ<sub>0</sub>, such that for every concept c ∈ C and every distribution D, the algorithm A outputs a hypothesis h ∈ C that satisfies

 $error_{\mathcal{D}}(h) \leq \epsilon_0$ 

with probability at least  $1 - \delta_0$ .

• in other words,  $\epsilon_0$  and  $\delta_0$  are fixed, and not arbitrarily small

### weak learning

- learner can be just marginally better than random
- weak learning: an algorithm A is a weak learner of a concept class C, if there exists γ and τ, both greater than 1/poly(n), such that for every concept c ∈ C and every distribution D, the algorithm A outputs a hypothesis h ∈ C that satisfies

$$error_{\mathcal{D}}(h) \leq \frac{1}{2} - \gamma$$

with probability at least  $\tau$ .

• in other words, *A* has a non-negligible chance of doing non-negligably better than random guessing

## weak learning

- the requirement for weak learning is indeed very weak
- for instance, it is typically trivial to learn a concept class  $\ensuremath{\mathcal{C}}$  with accuracy

$$error_{\mathcal{D}}(h) \leq \frac{1}{2} - \frac{1}{e(n)}$$

where e(n) is an exponentially-increasing function

#### • how?

return the correct answer for instances in the training set (which has exponentially small size) and a random answer for all other instances

### a surprising result

 theorem : if a concept class C is efficiently weak PAC learnable, then C is efficiently strong PAC learnable

## turning weak learning to strong learning

#### proof idea

- transform a weak learner A<sub>w</sub> to a strong learner A<sub>s</sub>
- assume fixed parameters  $\epsilon_0$  and  $\delta_0$
- for desired accuracy and confidence parameters  $\epsilon$  and  $\delta$ show how to construct  $A_s$  from  $A_w$
- construction should be polynomial in 1/ $\epsilon$  and 1/ $\delta$

two parts; we will show separately

- how to boost confidence  $\delta_0$  to  $\delta$  (easy)
- how to boost accuracy  $\epsilon_0$  to  $\epsilon$  (difficult)

#### warm up exercise on boosting

- consider a randomized algorithm A for a problem P
- assume that the answer to P is binary
- assume that for a given problem instance /, the algorithm A returns the correct answer for / with probabity greater than  $\frac{1}{2} + \epsilon$ , for some  $\epsilon$

- i.e., A does only slightly better than random guessing

**task** : design an algorithm A' s.t., for any instance *I*, A' returns the correct answer with probability at least  $1 - \delta$ , for any  $\delta$ 

## warm up exercise on boosting

#### answer

- repeat A on I for a total of m times
- return the majority answer

#### analysis

- how large should *m* be?
- how to analyze?

# hint : apply the Chernoff bound

- extremely useful tool for tail inequalities
- many applications in analysis of randomized algorithms, machine learning, etc.
- there are many variants; useful in different scenarios

Chernoff bound (additive form known as Hoeffding bound)

let X<sub>1</sub>,..., X<sub>m</sub> by *m* independent Bernoulli trials, with probability of success E[X<sub>i</sub>] = p let S = X<sub>1</sub> + ... + X<sub>m</sub>, then E[S] = pm then, for any 0 ≤ γ ≤ 1 we have

$$\mathsf{Pr}[\mathcal{S} > (\mathcal{p} + \gamma) m] \leq e^{-2m\gamma^2}$$

and

$$\Pr[S < (p - \gamma)m] \le e^{-2m\gamma^2}$$

## part 1 : boosting the confidence

- suppose that a learner A<sub>w</sub> outputs a hypothesis h, such that error<sub>D</sub>(h) ≤ ε with probability at least δ<sub>0</sub>, for any ε and δ<sub>0</sub> ≥ 1/poly(n)
- we want to achieve confidence  $1 \delta$ , for any  $\delta > 0$

#### constructing a strong learner

- simulate A<sub>w</sub> a total of k times (k to be determined)
  each time by drawing new samples from EX(c, D)
- find *k* hypotheses  $h_1, \ldots, h_k$
- probability all k hypotheses have error  $> \epsilon$  is  $\leq (1 \delta_0)^k$
- set  $(1 \delta_0)^k \le \delta/2$ , or equivalently  $k \ge (1/\delta_0) \ln(2/\delta)$
- for such k at least one hypothesis has error less than  $\epsilon$

## boosting the confidence (cont'd)

- one hypothesis of *h*<sub>1</sub>,..., *h<sub>k</sub>* has error less than *ϵ* with probability at least 1 − δ/2
  - we want to find which one
- draw a "large enough" sample S using EX(c, D)
- output the hypothesis h<sub>i</sub> that makes less mistakes on S
- let *m* = |*S*|
  - how large should m be?
- consider any h<sub>i</sub> with error error(h<sub>i</sub>)
- we want to bound by δ/2k the probability that h<sub>j</sub>'s error on S is greater than error(h<sub>i</sub>) + γ
- by Chernoff bound it suffices to take  $m \ge (c_0/\gamma^2) \ln(2k/\delta)$

### boosting the confidence (cont'd)

- for each *h<sub>j</sub>*, the probability that *h<sub>j</sub>*'s error on *S* is greater than *error*(*h<sub>j</sub>*) + γ is bounded by δ/2k
- (A) by the union bound, the probability that any of the k hypotheses deviates its error by more than  $\gamma$  is bounded by  $k(\delta/2k) = \delta/2$
- (B) recall that with probability at least 1  $\delta/2$  there is a hypothesis having error less than  $\epsilon$ 
  - putting (A) and (B) together, we can find a hypothesis h<sub>i</sub> having error at most ε + γ
  - and the failure probability (applying union bound again) is bounded by  $\delta/2+\delta/2=\delta$
  - to achieve error  $\epsilon',$  set  $\epsilon=\epsilon'/2$  and  $\gamma=\epsilon'/2$

## boosting the confidence (algorithm recap)

constructing a strong learner  $A_s$  from a weak learner  $A_w$ 

1. simulate  $A_w$  a total of  $k \ge (1/\delta_0) \ln(2/\delta)$  times

- find *k* hypotheses  $h_1, \ldots, h_k$ 

- 2. draw a sample S of size  $|S| = m \ge (c_0/\epsilon^2) \ln(2k/\delta)$
- 3. output the hypothesis  $h_i$  that makes less mistakes on S

 note that the strong learner A<sub>s</sub> makes a polynomial (in 1/ε and 1/δ) number of calls to the weak learner A<sub>w</sub> (which is assumed polynomial)

### part 2 : boosting the accuracy

- suppose that a learner A<sub>w</sub> outputs a hypothesis h, such that error<sub>D</sub>(h) ≤ β with probability at least 1 − δ, for a fixed β < 1/2 and any δ > 0
- we want to achieve accuracy  $\epsilon$ , for any  $\epsilon > 0$

- it seems to be an almost impossible task
- learner may always return a hypothesis with large error
- not clear how repeated runs can help to boost accuracy

## boosting the accuracy

#### high-level idea

- take advantage of the fact that the learner  $A_w$  can find a hypothesis with large error  $\beta$ , but can do so for any input distribution
- run A<sub>w</sub> not only on the target distribution D, but also on *"regions"* of D in which the previously-learned hypothesis performs poorly

#### for instance

- first run  $A_w$  on  $\mathcal{D}$  and obtain h having error  $\beta$
- then run  $A_w$  on inputs from  $\mathcal{D}$  in which h errs
- we hope to learn "something new"

#### boosting the accuracy — a two-step process

#### step 1

- assume weak learner  $A_w$  with guaranteed error  $\beta$
- build a new learner A that uses A<sub>w</sub> as a subroutine and has error g(β)
- A invokes A<sub>w</sub> on three different distributions and learns three hypotheses h<sub>1</sub>, h<sub>2</sub>, h<sub>3</sub>
- learner A forms  $h = majority\{h_1, h_2, h_3\}$
- hypothesis *h* is guaranteed to have error  $g(\beta)$

#### step 2

- step 1 is repeated in a recursive manner
- overall accuracy is boosted to a desirable level

#### boosting the accuracy — step 1

- as usual, c is target concept, and  $\mathcal{D}$  target distribution
- weak learner  $A_w$  achieves error  $\beta$  on any distribution
- 1. we invoke learner  $A_w$  on instances sampled from EX(c, D)and find hypothesis  $h_1$
- we know that  $error_{\mathcal{D}}(h_1) \leq \beta$
- 2. we create a new distribution  $D_2$  by filtering D using  $h_1$
- w.p. 1/2 we draw  $(\mathbf{x}, c(\mathbf{x}))$  from  $\mathcal{D}$  such that  $c(\mathbf{x}) = h_1(\mathbf{x})$
- w.p. 1/2 we draw  $(\mathbf{x}, c(\mathbf{x}))$  from  $\mathcal{D}$  such that  $c(\mathbf{x}) \neq h_1(\mathbf{x})$
- notice  $error_{D_2}(h_1) = 1/2$ , i.e.,  $h_1$  on  $D_2$  is random guessing
- invoking  $A_w$  on  $D_2$  we get  $h_2$  with error  $\beta < 1/2$  (on  $D_2$ ) i.e.,  $h_2 \neq h_1$ , i.e.,  $h_2$  learns "something new"

### boosting the accuracy — step 1 (cont'd)

- we create a third distribution D<sub>3</sub> by filtering D using both h<sub>1</sub> and h<sub>2</sub>
- we sample from EX(c, D) until we find instance  $(\mathbf{x}, c(\mathbf{x}))$ for which  $h_1(\mathbf{x}) \neq h_1(\mathbf{x})$
- i.e.,  $\mathcal{D}_3$  focuses on the region of  $\mathcal{D}$  that  $h_1$  and  $h_2$  disagree
- invoking  $A_w$  on  $\mathcal{D}_3$  returns  $h_3$
- $h_3$  learns "something new" for the input instances in which  $h_1$  and  $h_2$  disagree
- 4. the learning algorithm returns  $h = \text{majority}\{h_1, h_2, h_3\}$

### boosting the accuracy — step 1 (analysis, sketch)

define

 $error_{\mathcal{D}_1}(h_1) = \beta_1$ ,  $error_{\mathcal{D}_2}(h_2) = \beta_2$ ,  $error_{\mathcal{D}_3}(h_3) = \beta_3$ 

- we want to show that although β<sub>1</sub>, β<sub>2</sub>, β<sub>3</sub> can be as large as β, the *error*<sub>D</sub>(h) will be significantly smaller than β
- it can be shown that *error*<sub>D</sub>(h) is maximized if β<sub>i</sub> = β (for details see K&V)
- hypothesis h makes two types of errors
- 1st type error : both  $h_1$  and  $h_2$  make an error
- 2nd type error :  $h_1$  and  $h_2$  disagree and  $h_3$  makes error

### boosting the accuracy — step 1 (analysis, sketch)

• thus,

$$error_{\mathcal{D}}(h) = \Pr_{\mathbf{x}\in\mathcal{D}}[h_{1}(\mathbf{x}) \neq c(\mathbf{x}) \land h_{2}(\mathbf{x}) \neq c(\mathbf{x})] \\ + \Pr_{\mathbf{x}\in\mathcal{D}}[h_{3}(\mathbf{x}) \neq c(\mathbf{x}) \mid h_{1}(\mathbf{x}) \neq h_{2}(\mathbf{x})] \\ \Pr_{\mathbf{x}\in\mathcal{D}}[h_{1}(\mathbf{x}) \neq h_{2}(\mathbf{x})] \\ = \Pr_{\mathbf{x}\in\mathcal{D}}[h_{1}(\mathbf{x}) \neq c(\mathbf{x}) \land h_{2}(\mathbf{x}) \neq c(\mathbf{x})] \\ + \beta_{3} \Pr_{\mathbf{x}\in\mathcal{D}}[h_{1}(\mathbf{x}) \neq h_{2}(\mathbf{x})]$$

l.h.s. is maximized when  $\beta_{\rm 3}=\beta$ 

with further algebraic derivations (see K&V) we can show

 $\textit{error}_{\mathcal{D}}(\textit{h}) \leq 3\beta^2 - 2\beta^3$ 

and thus,  $g(\beta) = 3\beta^2 - 2\beta^3$ , as desired

#### summary

- a weak learner can be transformed to a strong learner
- confidence can be boosted by iterative runs of the weak learner
- accuracy can be boosted by focusing on regions of the target distribution that are more difficult to learn
  - two step process:
    - 1. reduce error quadratically
    - 2. recursive application of 1. to reduce error to  $\epsilon$
- analysis is quite involved (in particular the recursive part)
- algorithm is not practical
- can we design a practical boosting algorithm? yes! AdaBoost