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# Using MATLAB in Audio and Acoustics

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# Using Matlab

- ▶ Mathematical simulator (Algorithms, plots, programs, measurements, ...)
- ▶ It works better for matrix operations
- ▶ Vectors and Matrices can represent whatever we want (signals, scores, frequency/time axes, ...)
- ▶ Continuous functions and polynomials are represented as vectors in Matlab

$$\mathbf{a} = \{a(1) \ a(2) \ \cdots \ a(n) \ \cdots \ a(N)\};$$

# Using Matlab

- ▶ Vector/Matrix conjugate transpose (Hermitian)

$$\mathbf{b} = \mathbf{a}'; \quad \mathbf{a}^{M,N}, \mathbf{b}^{N,M}$$

- ▶ Vector/Matrix transpose

$$\mathbf{b} = \mathbf{a}.'; \quad \mathbf{a}^{M,N}, \mathbf{b}^{N,M}$$

- ▶ Vector/Matrix product

$$\mathbf{c} = \mathbf{a} * \mathbf{b}; \quad \mathbf{a}^{M,N}, \mathbf{b}^{N,M}, \mathbf{c}^{M,M}$$

- ▶ Vector/Matrix element-wise product

$$\mathbf{c} = \mathbf{a} .* \mathbf{b}; \quad \mathbf{c}(n) = \mathbf{a}(n) * \mathbf{b}(n) \quad \mathbf{a}^{M,N}, \mathbf{b}^{M,N}, \mathbf{c}^{M,N}$$

- ▶ Vector/Matrix division

$$\mathbf{c} = \mathbf{a}/\mathbf{b}; \quad \mathbf{c} = \mathbf{a} * \mathbf{b}^{-1}$$

$$\mathbf{c} = \mathbf{a} \backslash \mathbf{b}; \quad \mathbf{c} = \mathbf{a}^{-1} * \mathbf{b}$$

- ▶ Vector/Matrix element-wise division

$$\mathbf{c} = \mathbf{a} ./ \mathbf{b}; \quad \mathbf{c}(n) = \mathbf{a}(n) / \mathbf{b}(n)$$

# Parseval's theorem

- General form:

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} |X(f)|^2 df$$

- For Discrete Fourier Transform: (if  $N=N_{fft}$ )

$$X = \text{fft}(x);$$

$$\sum_{n=0}^{N-1} |x(n)|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X(k)|^2$$

- In a more general way: ( $N \leq N_{fft} \equiv$  zero-padding)

$$X = \text{fft}(x, N_{fft});$$

$$\sum_{n=0}^{N-1} |x(n)|^2 = \frac{1}{N_{fft}} \sum_{k=0}^{N_{fft}-1} |X(k)|^2$$

# Filtering

$$H(z) = \frac{b_0 + b_1(z^{-1}) + \cdots + b_n(z^{-N})}{1 + a_1(z^{-1}) + \cdots + a_n(z^{-L})}$$

$$H(z) = \frac{B(z)}{A(z)}$$

$$y(n) = \sum_{i=0}^N b_i x(n-i) - \sum_{j=1}^L a_j x(n-j)$$

## Filtering: Example

$$H(z) = \frac{-0.5 + z^{-1}}{1 + 0.5z^{-1}}$$

```
b = [-0.5 1];  
a = [1 0.5];  
y = [0 b(1).*x];  
for i=2:size(x,1)  
y(i) = sum(b(end:-1:1).*x(i-1:i))-a(2)*y(i-1);  
end;
```

or

```
y = filter(b,a,x);
```

To design filters check `fdesign()` command in Matlab or whatever other implemented method (`fir1()`, `firpm()`,...).

## Processing in frequency domain

In the frequency domain, calculations are the same for each frequency bin (element-wise)

$$U(f) = \frac{P(f)}{Z(f)} \quad ; \quad Z(f) = Z_o \frac{1}{\tanh(\gamma L)} \quad ; \quad \gamma = j\frac{\omega}{c} = j\frac{2\pi f}{c}$$

% Particle velocity at the entrance of a lossless  
% closed-end tube of length L

```
P = fft(p,Nfft);  
w = 2*pi.*(0:Nfft/2+1)/Nfft*fs;  
c = 343;  
L = 0.010;  
Z0 = 413;  
gamma = 1i.*w./c;  
Zaux = Z0./tanh(gamma);  
Z = [Zaux.'; Zaux(end-1:-1:2)'];  
U = P./Z;
```