

Robotic Manipulation Exercise Practicalities

Exercise session overview

- Exercise sessions every Wednesday 08:15-10:00 and Thursday 10:15-12:00 via Zoom.
- Voluntary presence.
- Teacher assistants (TAs) present to help you.

Requirements

- A Linux system (we provide and support Ubuntu 18.04 with installed ROS on that)
- ROS Melodic (<http://wiki.ros.org/melodic/Installation/Ubuntu>)
- Catkin tools <https://catkin-tools.readthedocs.io/en/latest/installing.html>
- MoveIt! For Melodic: <https://moveit.ros.org/install/>
- The MuJoCo simulator *mujoco200 linux*: <https://www.roboti.us/>
- The MuJoCo license found in MyCourses under “For Aalto users”. **IMPORTANT:** The license is for **personal use only** and cannot be redistributed!
- You can download an already configured virtual machine including the above programs except MuJoCo → vdi.aalto.fi → **Ubuntu ROS** machine
- You can also find a virtual box image on MyCourses
<https://mycourses.aalto.fi/course/view.php?id=28594§ion=2>

Communication

- The preferred means of communication is the course slack channel and not email:
<https://mycourses.aalto.fi/course/view.php?id=28594§ion=2>
- When you sign up to the slack workspace use your **aalto username** as the **Nick name** as we will link this to your gitlab repository.
- If you have specific problems with your code do not send it over email or slack. Instead, tell us that you have some problems and push your latest commits to the gitlab repository and we will pull it from there and start investigating.
- Usually more than one student have similar problems and thus we advocate asking questions in the exercise slack channels to enable students to help each other out.
- TAs and the lecturer will, per default, not answer emails or slack messages during the weekends.

Exercises

In total six problems:

- Introduction to ROS.
- Simple pick and place with MoveIt
- Planning algorithms benchmark in MoveIt
- Visual perception
- roscntrol
- Dual-arm manipulation

Tentative exercise schedule

The exercises are introduced on the following exercise sessions :

- 20th of January intro to exercise 1
- 27nd of January intro to exercise 2
- 10th of February intro to exercise 3
- 24th of February intro to exercise 4
- 10th of March intro to ROS control
- 24th of March tutorial on exercise 6

The deadline would be two weeks after releasing each assignment.

Submissions

- Each solution include at least source code written in C++ that solves the problem and for most of the exercises you also need to submit a report written in English.
- The report (saved as PDF) should answer the questions posed in the assignment which can, for example, be the following 1 Which planner is fastest and why? Plot the running times and answer the questions by comparing the algorithms
- If the exercise requires you to submit both a report and code you need to submit both. Otherwise, you will not get the score for that part.
- Each student forks the exercise into their own gitlab subgroup, solves the exercise there, and finally upload everything to the respective repository before deadline

Grading

- If the exercise requires both code and a report the report accounts for 50% and the code for 50% of all points awarded for that exercise. Otherwise, one or the other accounts for 100% of the points.
- The code is graded based on correctness (0-100%).
- The report is graded based on:
 - Correctness (0-100%),
 - How well it is written (satisfactory, good, excellent).
 - We will grade both language and structure of the report. For example, the report should be easy to read and coherent, and you need to refer to all figures, tables etc. Think of every single report as a part of your future MSc. thesis

Exercise rules

- Exercises are handed in and done **individually**
- You are allowed to discuss the problems but not share solutions. No copying of exercises (neither code nor report). If we notice plagiarism it is reported and consequences follow.
- No late submissions are accepted.