

$$\text{Ex } \mathbf{F}(x, y, z) = (xy, y^2 - z^2, yz)$$

$$\operatorname{div} \mathbf{F} = \frac{\partial}{\partial x}(xy) + \frac{\partial}{\partial y}(y^2 - z^2) + \frac{\partial}{\partial z}(yz) =$$

$$= y + 2y + y = 4y$$

$$\operatorname{curl} \mathbf{F} = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & y^2 - z^2 & yz \end{vmatrix} =$$

$$= \left(\frac{\partial}{\partial y}(yz) - \frac{\partial}{\partial z}(y^2 - z^2), \frac{\partial}{\partial z}(xy) - \frac{\partial}{\partial x}(yz), \frac{\partial}{\partial x}(y^2 - z^2) - \frac{\partial}{\partial y}(xy) \right) =$$

$$= (z + 2z, 0, -x) = (3z, 0, -x)$$

Interpretation of the divergence

Let \vec{F} be a smooth vector field and \vec{N} be the unit outward normal vector field of S_ϵ , the sphere with radius ϵ centered at P. Then

$$\operatorname{div} \vec{F}(P) = \lim_{\epsilon \rightarrow 0^+} \left(\frac{3}{4\pi\epsilon^3} \oint_{S_\epsilon} \vec{F} \cdot \vec{N} dS \right)$$

\downarrow

$\frac{1}{\text{volume of } S_\epsilon}$

"Proof": Let $\vec{P} = \vec{O}$. Then $\vec{N} = \frac{1}{\varepsilon} (x, y, z)$

Taylor expansion of (F_1, F_2, F_3) \vec{F}_{x_0}

$$\vec{F}(x, y, z) = \underbrace{\vec{F}_0(0, 0, 0)}_{\vec{F}_{y_0}} + \underbrace{\left(\frac{\partial F_1}{\partial x}, \frac{\partial F_2}{\partial x}, \frac{\partial F_3}{\partial x}\right)}_{\vec{F}_{x_0}} x +$$

$$+ \underbrace{\left(\frac{\partial F_1}{\partial y}, \frac{\partial F_2}{\partial y}, \frac{\partial F_3}{\partial y}\right)}_{\vec{F}_{y_0}} y + \underbrace{\left(\frac{\partial F_1}{\partial z}, \frac{\partial F_2}{\partial z}, \frac{\partial F_3}{\partial z}\right)}_{\vec{F}_{z_0}} z +$$

+ higher order terms

$$\begin{aligned} \vec{F} \cdot \vec{N} &= \frac{1}{\varepsilon} (\vec{F}_0 \cdot (x, y, z) + \vec{F}_{x_0} x^2 \cdot \vec{e}_1 + \vec{F}_{x_0} xy \cdot \vec{e}_2 \\ &\quad + \vec{F}_{x_0} xz \cdot \vec{e}_3 + \vec{F}_{y_0} yx \cdot \vec{e}_1 + \vec{F}_{y_0} y^2 \cdot \vec{e}_2 + \\ &\quad + \vec{F}_{y_0} yz \cdot \vec{e}_3 + \vec{F}_{z_0} xz \cdot \vec{e}_1 + \vec{F}_{z_0} yz \cdot \vec{e}_2 + \\ &\quad + \vec{F}_{z_0} z^2 \cdot \vec{e}_3 + \dots) \end{aligned}$$

Now integrate termwise

$$\oint_{S_\varepsilon} x dS = \oint_{S_\varepsilon} y dS = \oint_{S_\varepsilon} z dS = 0$$

$$\iint_{S_\varepsilon} xy \, dS = \iint_{S_\varepsilon} xz \, dS = \iint_{S_\varepsilon} yz \, dS = 0$$

$$\begin{aligned} \iint_{S_\varepsilon} x^2 \, dS &= \iint_{S_\varepsilon} y^2 \, dS = \iint_{S_\varepsilon} z^2 \, dS = \\ &= \frac{1}{3} \iint_{S_\varepsilon} x^2 + y^2 + z^2 \, dS = \frac{1}{3} \varepsilon^2 \cdot 4\pi \varepsilon^2 = \frac{4\pi}{3} \varepsilon^4 \end{aligned}$$

Higher order terms involve ε^k , $k \geq 5$

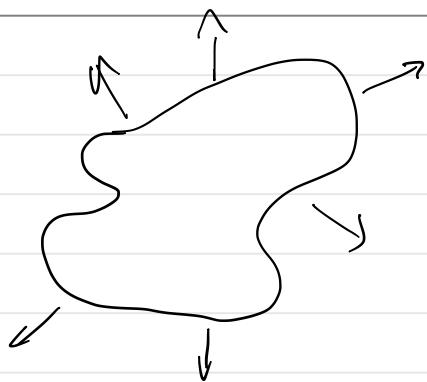
$$S_0 \frac{3}{4\pi \varepsilon^3} \iint_{S_\varepsilon} \vec{F} \cdot \vec{N} \, dS =$$

$$= \frac{3}{4\pi \varepsilon^3} \cdot \frac{1}{\varepsilon} \left(\iint_{S_\varepsilon} (F_{x0} \cdot \vec{e}_1) x^2 + (F_{y0} \cdot \vec{e}_2) y^2 + (F_{z0} \cdot \vec{e}_3) z^2 \, dS + O(\varepsilon^5) \right)$$

$$\text{and } \lim_{\varepsilon \rightarrow 0^+} \frac{3}{4\pi \varepsilon^3} \iint_{S_\varepsilon} \vec{F} \cdot \vec{N} \, dS = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = \operatorname{div} \vec{F}.$$

⊗

That is $\operatorname{div} \vec{F}$ measures "how much fluid is created or destroyed in each point".



Flow = "sum" of $\operatorname{div} \mathbf{F}$
in the interior.

Interpretation of Curl

Ex Consider the vector field

$$\vec{v} = (-\omega y, \omega x, 0)$$

Calculate the circulation counter clockwise around the circle C_ϵ centered at (x_0, y_0) with radius ϵ in the xy -plane

$$C_\epsilon(t) = (x_0 + \epsilon \cos t, y_0 + \epsilon \sin t, 0) \quad 0 \leq t \leq 2\pi$$

$$\begin{aligned} \oint_{C_\epsilon} \vec{v} \cdot d\vec{r} &= \int_0^{2\pi} -\omega(y_0 + \epsilon \sin t)(-\epsilon \cos t) + \\ &\quad + \omega(x_0 + \epsilon \sin t)(\epsilon \cos t) dt = \\ &= \int_0^{2\pi} \omega \epsilon (y_0 \sin t + x_0 \cos t) + \omega \epsilon^2 dt = 2\pi \omega \epsilon^2 \end{aligned}$$

Also $\text{Curl } \vec{v} = \nabla \times \vec{v} = \left(\frac{\partial}{\partial x} (\omega_x) - \frac{\partial}{\partial y} (-\omega_y) \right) \vec{e}_3$

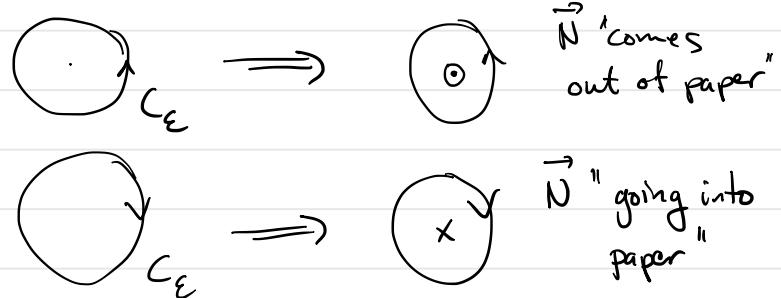
$$= 2\omega \vec{e}_3$$

Note that $\oint_{C_\epsilon} \vec{v} \cdot d\vec{r} = \text{Area}(C_\epsilon) (\text{Curl } \vec{v} \cdot \vec{e}_3)$

Theorem: If \vec{F} is a smooth vector field in \mathbb{R}^3 and C_ϵ is a circle of radius ϵ centered at P and bounding a disk D_ϵ with unit normal \vec{N} (orientation inherited from C_ϵ) then

$$\lim_{\epsilon \rightarrow 0^+} \frac{1}{\pi \epsilon^2} \oint_{C_\epsilon} \vec{F} \cdot d\vec{r} = \vec{N} \cdot \text{Curl } \vec{F}(P)$$

Orientation inherited from C_ϵ ?



Identities involving div , grad and curl

ϕ, ψ functions, \vec{F}, \vec{G} vector fields

$$a) \nabla(\phi\psi) = \phi\nabla\psi + \psi\nabla\phi$$

$$b) \text{div}(\phi\vec{F}) = \nabla \cdot (\phi\vec{F}) = (\nabla\phi) \cdot \vec{F} + \phi(\nabla \cdot \vec{F})$$

$$c) \nabla \times (\phi\vec{F}) = (\nabla\phi) \times \vec{F} + \phi(\nabla \times \vec{F})$$

$$d) \nabla \cdot (\vec{F} \times \vec{G}) = (\nabla \times \vec{F}) \cdot \vec{G} - \vec{F} \cdot (\nabla \times \vec{G})$$

$$e) \nabla \times (\vec{F} \times \vec{G}) = (\nabla \cdot \vec{G})\vec{F} + (\vec{G} \cdot \nabla)\vec{F} - (\nabla \cdot \vec{F})\vec{G} - (\vec{F} \cdot \nabla)\vec{G}$$

$$f) \nabla(\vec{F} \cdot \vec{G}) = \vec{F} \times (\nabla \times \vec{G}) + \vec{G} \times (\nabla \times \vec{F}) + (\vec{F} \cdot \nabla)\vec{G} + (\vec{G} \cdot \nabla)\vec{F}$$

$$g) \nabla \cdot (\nabla \times \vec{F}) = 0 \quad \text{div curl} = 0$$

$$h) \nabla \times (\nabla \phi) = 0 \quad \text{curl grad} = 0$$

$$i) \nabla \times (\nabla \times \vec{F}) = \nabla(\nabla \cdot \vec{F}) - (\nabla \cdot \nabla)\vec{F}$$

$\nabla^2 = \Delta = \text{Laplace operator}$

$$\text{curl curl} = \text{grad div} - \text{Laplace}$$

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \dots + \frac{\partial^2}{\partial x_n^2}$$

A function satisfying $\Delta f = 0$ is called harmonic.

Proof g) (Do the rest by yourself)

$$\nabla \times \vec{F} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)$$

$$\begin{aligned} \nabla \cdot (\nabla \times \vec{F}) &= \frac{\partial}{\partial x} \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) + \\ &+ \frac{\partial}{\partial z} \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) = 0 \end{aligned}$$



Green's Theorem in the plane

This can be seen as a higher-dimensional version of the Fundamental Theorem of Calculus.

- Classical version $\int_a^b \frac{d}{dx} f(x) dx = f(b) - f(a).$