

ELEC-E8101 Digital and Optimal Control

Solutions 1

1. a)

Let's do the transform of the sequence based on the definition of the Z-transformation. The definition is

$$F(z) = \sum_{k=0}^{\infty} f(k) z^{-k}.$$

Hence the transform of sequence

$$y(k) = 1, k = 0, 1, 2, 3, \dots$$

is

$$Y(z) = \sum_{k=0}^{\infty} y(k) z^{-k} = 1 + z^{-1} + z^{-2} + z^{-3} + \dots$$

If the equality for the geometric sums

$$\sum_{k=0}^{\infty} q^k = \frac{1}{1-q}, \text{ if } |q| < 1$$

is applied, we get

$$\begin{aligned} Y(z) &= \sum_{k=0}^{\infty} y(k) z^{-k} = 1 + z^{-1} + z^{-2} + z^{-3} + \dots \\ &= \frac{1}{1 - \frac{1}{z}} = \frac{z}{z-1} \end{aligned}$$

b)

In a similar way as in part a) we set

$$\begin{aligned} Y(z) &= \sum_{k=0}^{\infty} e^{-ak} z^{-k} = 1 + e^{-a} z^{-1} + e^{-2a} z^{-2} + e^{-3a} z^{-3} + \dots \\ &= 1 + (e^a z)^{-1} + (e^a z)^{-2} + (e^a z)^{-3} + \dots = \frac{1}{1 - e^{-a} z^{-1}} = \frac{z}{z - e^{-a}} \end{aligned}$$

You can verify both results by using the z-transform tables.

2. a) $F(z) = Z\{f(k)\} = \sum_{k=0}^{\infty} a^k z^{-k} = 1 + az^{-1} + a^2 z^{-2} + \dots = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$ The geometric series

converges for $|az^{-1}| < 1$. However, here we do not calculate the expression for any special value of z . Therefore, the convergence condition is not a matter of concern. Compare to Laplace transformation and its convergence region in the continuous time case.

b) $Z[e^{-kh/T}] = \frac{z}{z - e^{-h/T}}$ holds because $e^{-\frac{kh}{T}} = \left(e^{-\frac{h}{T}}\right)^k$. But $e^{-h/T}$ is always ≥ 0 . So this expression is more restrictive than that in part a).

3.

Define the value of $y(kh)$, when $k \rightarrow \infty$, using the final-value theorem.

Final-value theorem: If $\lim_{k \rightarrow \infty} y(kh)$ exists, then it holds

$$\lim_{k \rightarrow \infty} y(kh) = \lim_{z \rightarrow 1} (1 - z^{-1})Y(z),$$

A sufficient (but not necessary) condition for the existence of $\lim_{k \rightarrow \infty} y(kh)$ is that $(1 - z^{-1})Y(z)$ has no poles on or outside the unit circle.

$$Y(z) = \frac{0,792z^2}{(z-1)(z^2 - 0,416z + 0,208)}$$

Let's check whether $(1 - z^{-1})Y(z)$ has poles on or outside the unit circle.

$$\begin{aligned} (1 - z^{-1})Y(z) &= (1 - z^{-1}) \frac{0,792z^2}{(z-1)(z^2 - 0,416z + 0,208)} \\ &= \frac{0,792z}{(z^2 - 0,416z + 0,208)} \end{aligned}$$

which has the poles :

$$z^2 - 0,416z + 0,208 = 0$$

$$z = 0,208 \pm 0,406i$$

The absolute values of the complex poles (see also MATLAB-command *roots*) are about 0,46

⇒ they are inside the unit circle, and the final-value theorem can be used.

$$\begin{aligned} \lim_{k \rightarrow \infty} y(kh) &= \lim_{z \rightarrow 1} (1 - z^{-1}) Y(z) = \lim_{z \rightarrow 1} \frac{0,792z}{(z^2 - 0,416z + 0,208)} \\ &= \frac{0,792}{1 - 0,416 + 0,208} = \frac{0,792}{0,792} = 1 \end{aligned}$$

For verification in Matlab the signal y can be constructed by letting a unit step function $\frac{z}{z-1}$ go through the system with a pulse transfer function $H(z) = \frac{0.792z}{z^2 - 0.416z + 0.208}$. The following commands can be used.

```
H=0.792*tf([1 0],[1 -0.416 0.208],1); % Note the last "1" which tells Matlab that we
consider a discrete-time system with discretization interval 1. If left out, Matlab would
consider H as a continuous time transfer function.
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```
step(H) % Plots the response and shows that it indeed approaches 1.
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Note: for defining H we could also write

```
z=tf('z');
H=0.792*z/(z^2-0.416*z+0.208)
```

4.

Take the inverse-transform of the following equation

$$Y(z) = \frac{(1 - e^{-ah})z}{(z-1)(z - e^{-ah})}$$

If Z-transformation tables are studied, it is noted that in every transform z is in the numerator. Therefore, for convenience, we first divide the previous equation with z ,

$$\frac{Y(z)}{z} = \frac{(1 - e^{-ah})}{(z-1)(z - e^{-ah})} = \frac{A}{z-1} + \frac{B}{z - e^{-ah}}$$

Let's solve A and B with Heaviside's method. (The partial fraction method could as well be used)

$$A = \lim_{z \rightarrow 1} (z-1) \frac{(1-e^{-ah})}{(z-1)(z-e^{-ah})} = 1$$

$$B = \lim_{z \rightarrow e^{-ah}} (z-e^{-ah}) \frac{(1-e^{-ah})}{(z-1)(z-e^{-ah})} = -1$$

Then

$$\begin{aligned} \frac{Y(z)}{z} &= \frac{1}{z-1} - \frac{1}{z-e^{-ah}} \\ \Rightarrow Y(z) &= \frac{z}{z-1} - \frac{z}{z-e^{-ah}} \end{aligned}$$

and this can be inverse-transformed with the transformation tables.

$$y(kh) = 1 - e^{-akh}$$

***5.**

Prove the following Z-transformation

$$Z\left\{\frac{1}{2}(kh)^2\right\} = \frac{h^2 z(z+1)}{2(z-1)^3}$$

Let's do what the hint says and transform $Z\{kh\}$.

$$y(kh) = kh, \quad k = 0, 1, 2, 3, \dots$$

$$\Rightarrow Y(z) = \sum_{k=0}^{\infty} khz^{-k} = 0 + hz^{-1} + 2hz^{-2} + 3hz^{-3} + \dots$$

This is not a geometric series. But let's multiply with $(z-1)$

$$\begin{aligned} \Rightarrow (z-1)Y(z) &= h[1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + \dots - z^{-1} - 2z^{-2} - 3z^{-3} - \dots] \\ &= h[1 + z^{-1} + z^{-2} + z^{-3} + \dots] \end{aligned}$$

Now it can be seen that this is a geometric sum with ratio of z^{-1} between the consecutive terms. Hence we get

$$\begin{aligned} (z-1)Y(z) &= \frac{h}{1-z^{-1}} = \frac{hz}{z-1} \\ \Rightarrow Y(z) &= \frac{hz}{(z-1)^2} \end{aligned}$$

Let's use the same trick into the actual problem and see what happens.

$$\begin{aligned}
Z\left\{\frac{1}{2}(kh)^2\right\} &= \frac{1}{2}h^2 [0 + z^{-1} + 4z^{-2} + 9z^{-3} + 16z^{-4} + \dots] = Y(z) \\
(z-1)Y(z) &= \frac{1}{2}h^2 [1 + 4z^{-1} + 9z^{-2} + 16z^{-3} + \dots - z^{-1} - 4z^{-2} - 9z^{-3} - 16z^{-4}] \\
&= \frac{1}{2}h^2 [1 + 3z^{-1} + 5z^{-2} + 7z^{-3} + \dots] \underset{\text{arrangements}}{=} \frac{1}{2}h^2 [(1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + \dots) \\
&\quad + \underbrace{(z^{-1} + 2z^{-2} + 3z^{-3} + \dots)}_{z\{kh\}}] = \frac{1}{2}h^2 \left[\frac{z}{z} (1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + \dots) + \frac{z}{(z-1)^2} \right] \\
&= \frac{1}{2}h^2 \left[z(z^{-1} + 2z^{-2} + 3z^{-3} + \dots) + \frac{z}{(z-1)^2} \right] = \frac{1}{2}h^2 \left[z \frac{z}{(z-1)^2} + \frac{z}{(z-1)^2} \right] = \frac{h^2 z(z+1)}{2(z-1)^2}
\end{aligned}$$

By dividing by $(z - 1)$ the final result can be obtained:

$$Y(z) = \frac{h^2 z(z+1)}{2(z-1)^3}$$

6.

Define $y(k)$ of the following difference equation by using the Z-transformation

$$y(k+2) - 1.5y(k+1) + 0.5y(k) = u(k+1)$$

$u(k)$ is the unit step at $k = 0$, $y(0) = 0.5$ and $y(-1) = 1$

Let us take the Z-transformation of the above equation:

$$z^2 Y(z) - z^2 y(0) - zy(1) - 1.5[zY(z) - zy(0)] + 0.5Y(z) = zU(z) - zu(0).$$

The initial value $y(1)$ of time domain is yet unknown, but it can be solved with the difference equation:

$$y(1) = 1.5y(0) - 0.5y(-1) + u(0) = 0.75 - 0.5 + 1 = 1.25.$$

By substituting the initial values to the z -transformed equation we get:

$$\Rightarrow [z^2 - 1.5z + 0.5]Y(z) = 0.5z^2 + 1.25z - 0.75z + z \frac{z}{z-1} - z$$

$$\Rightarrow [(z-1)(z-0.5)]Y(z) = 0.5z^2 + 0.5z + \frac{z}{z-1}.$$

Let us solve $Y(z)$:

$$\begin{aligned} Y(z) &= \frac{0.5z^2 + 0.5z + \frac{z}{z-1}}{(z-1)(z-0.5)} = \frac{(z-1)(0.5z^2 + 0.5z) + z}{(z-1)^2(z-0.5)} = \\ &= \frac{0.5z^3 + 0.5z^2 - 0.5z^2 - 0.5z + z}{(z-1)^2(z-0.5)} = \frac{0.5z(z^2 + 1)}{(z-1)^2(z-0.5)} \end{aligned}$$

and by the partial fractions this is:

$$\frac{0.5z(z^2 + 1)}{(z-1)^2(z-0.5)} = z \left[\frac{A}{z-0.5} + \frac{B}{(z-1)^2} + \frac{C}{z-1} \right]$$

$$\Rightarrow A = 2.5, B = 2 \text{ ja } C = -2.$$

$$\Rightarrow Y(z) = \frac{2.5z}{z-0.5} + \frac{2z}{(z-1)^2} - \frac{2z}{z-1}.$$

Inverse-transformation:

$$y(k) = 2.5 \cdot 0.5^k + 2k - 2 = 2(k - 1) + 2.5 \cdot 0.5^k.$$