

$$\begin{aligned}
 q_n(+) &= \sqrt{(r^x(+) - s_n^x)^2 + (r^y(+) - s_n^y)^2 + r_n} \\
 &= \sqrt{(r^x(0) + v^x \cdot t - s_n^x)^2 + (r^y(0) + v^y \cdot t - s_n^y)^2 + r_n}
 \end{aligned}$$

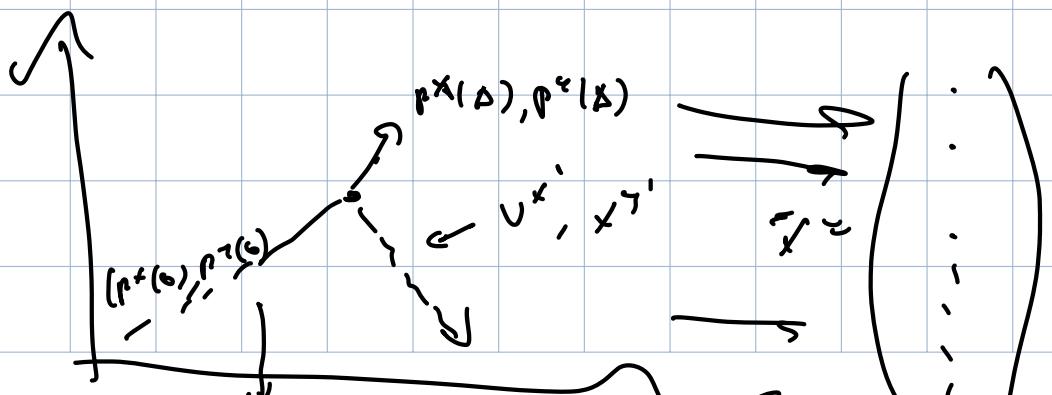
$q_n(t_i)$

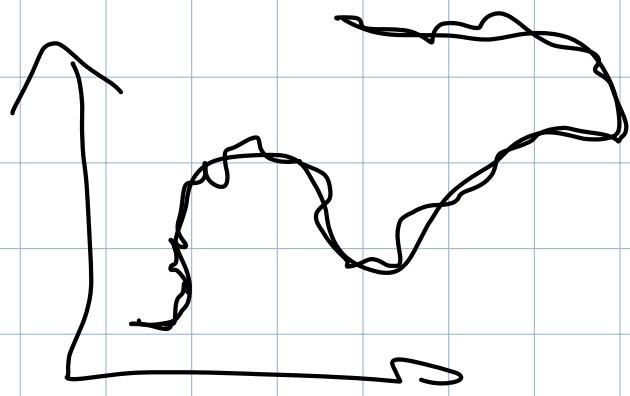
$q_n(t_{i+1})$

:

$g(\vec{x}; t)$

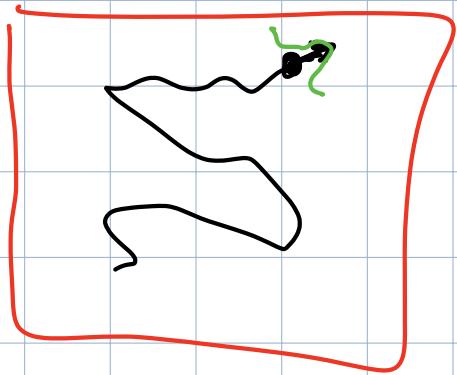
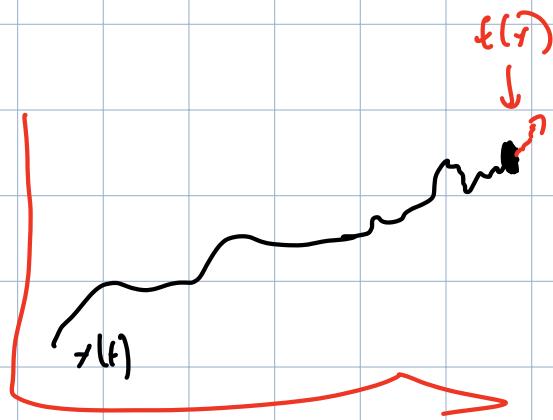
$$\vec{x} = \begin{pmatrix} r^x(0) \\ r^y(0) \\ v^x \\ v^y \end{pmatrix}$$

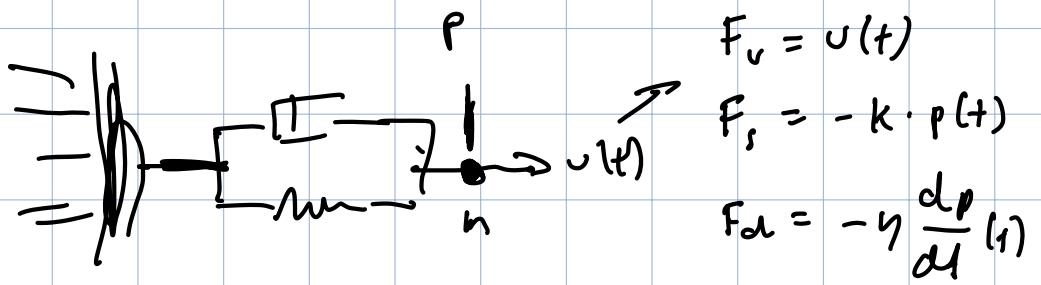




$$\frac{dx}{dt} = f(x) + w$$

$$dx = f(x) dt$$





$$m \cdot a(t) = F$$

$$\begin{aligned} &= F_s + F_d + F_v \\ &= -k \cdot p(t) - \eta \frac{dp(t)}{dt} + v(t) \end{aligned}$$

$$a = \frac{d^2 p}{dt^2}$$

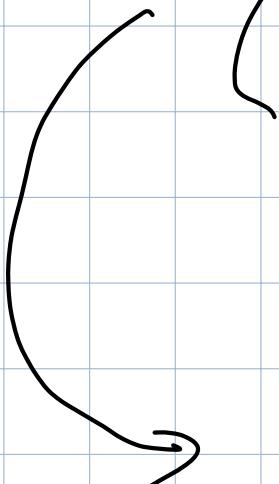


$$m \cdot \frac{d^2 p}{dt^2} = -k_p(t) - \eta \frac{dp(t)}{dt} + v(t)$$

$$\left\{ \begin{array}{l} \frac{dp}{dt} = \dot{p} \\ \frac{d^2 p}{dt^2} = \ddot{p} \end{array} \right.$$

$$\ddot{p} = -\frac{k}{m} p - \frac{\eta}{m} \frac{dp}{dt} + \frac{v(t)}{m}$$

$$\vec{x} = \begin{pmatrix} p \\ \frac{dp}{dt} \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \frac{d\vec{x}}{dt} = \begin{pmatrix} \dot{p} \\ \ddot{p} \end{pmatrix}$$



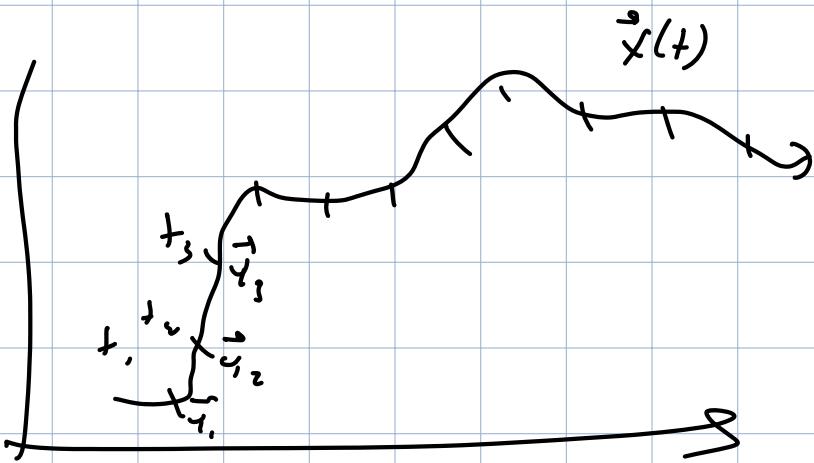
$$\frac{d\vec{x}}{dt} = \begin{pmatrix} \dot{p}/dt \\ -\frac{k}{m} p - \frac{\eta}{m} \frac{dp}{dt} + \frac{v}{m} \end{pmatrix}$$

$$= \begin{pmatrix} x_2 \\ -\frac{k}{m} x_1 - \frac{\eta}{m} x_2 \end{pmatrix} + \begin{pmatrix} 0 \cdot v \\ \frac{1}{m} \cdot v \end{pmatrix}$$

$$\ddot{x} = \begin{pmatrix} p \\ \frac{\partial p}{\partial x} \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & 1 \\ -k & -\frac{q}{m} \end{pmatrix}}_A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \underbrace{\begin{pmatrix} 0 \\ \frac{1}{m} \end{pmatrix}}_{B_0} u$$

$$\vec{r}_n = \underbrace{(1 \ 0)}_G \vec{x}_n + r$$

$$\frac{d\vec{x}}{dt} = A \vec{x} + B_0 \vec{u}$$



$$\vec{r}_n = G \vec{x}_n + \vec{r}_n$$

$$m=1 \quad \underbrace{\vec{a}}_{\vec{a}} = \frac{d^2 \vec{p}}{dt^2} = \begin{pmatrix} \frac{d^2 p^x}{dt^2} \\ \frac{d^2 p^y}{dt^2} \end{pmatrix}$$

$$\rightarrow m \vec{a} = \vec{f}$$

$$\frac{d^2 p^x}{dt^2} = F_p^x$$

$$\frac{d^2 p^y}{dt^2} = F_p^y$$

$$\frac{dp^x}{dt} = \frac{dp^x}{dt}$$

$$\frac{dp^y}{dt} = \frac{dp^y}{dt}$$

$$\vec{F} = \begin{pmatrix} F_p^x \\ F_p^y \end{pmatrix}$$

$$\vec{x} = \begin{pmatrix} p^x \\ p^y \\ \frac{dp^x}{dt} \\ \frac{dp^y}{dt} \end{pmatrix}$$

$$\frac{d\vec{x}}{ds} = \begin{pmatrix} x_3 \\ x_4 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ F_r^x \\ F_r^y \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} F_r^x \\ F_r^y \end{pmatrix}$$

$$= \underline{A\vec{x}} + \underline{B_0\vec{U}}$$

$$\begin{pmatrix} r_{1,n} \\ r_{2,n} \end{pmatrix} = \begin{pmatrix} x_{1,n} \\ x_{2,n} \end{pmatrix} + \begin{pmatrix} n_{1,n} \\ n_{2,n} \end{pmatrix}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

$$\vec{r} = G\vec{x} + \vec{r}$$

↓

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\frac{d^2 p}{dt^2} = -k_p - \gamma \frac{dp}{dt} + w(t)$$