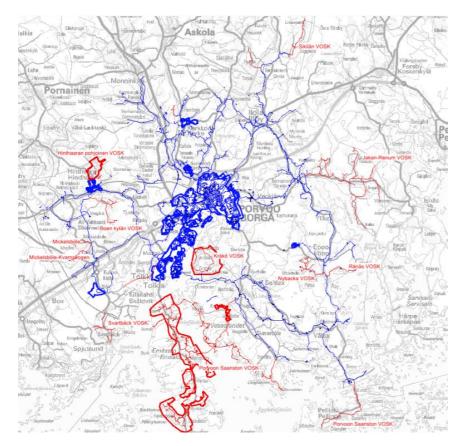


Risk-based optimization of pipe inspections in large underground networks with imprecise information

Hilkka Hännikäinen Presentation *21 20.11.2020*

> MS-E2191 Graduate Seminar on Operations Research Fall 2020

The document can be stored and made available to the public on the open internet pages of Aalto University. All other rights are reserved.



Porvoon kaupungin vesihuollon kehittämissuunnitelma 2015-2020



Buried Pipe Element (Undergroung piping) from https://www.passuite.com/kbase/doc/start/WebHelp_en/pipesoil.htm



Renovation planning

- Identify an optimal set of inspections of network items so that possible renovation actions are expected to decrease the risks and the cost of negative consequences
- ii. Determine the degradation state of the network items in the selected portfolio and plan the maintenance actions for the network



Risk-based methodology





Likelihood and severity evaluation (1/2)

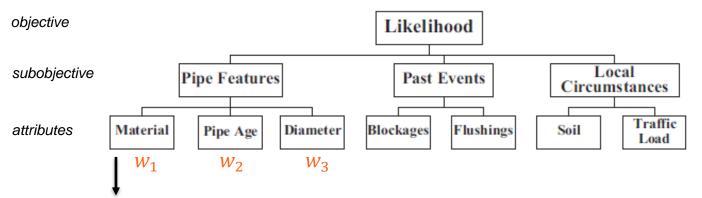
Risk = combination of the likelihood of the failure and the severity of the failure

The risk of every network item is quantified from value intervals for likelihood and severity determined using methods from MAVT



Likelihood and severity evaluation (2/2)

Mancuso et al. (2016)



- quality classes e.g. PVC, polyethene, cast iron and concrete
 → for every quality class, assign an interval valued score describing its contribution to the (sub)objective relative to the other classes
- for network item x^{j} , determine a value interval based on its quality v_{i} class w.r.t to attribute i
 - $v_i\left(x_i^j\right) = [\underline{v}_i\left(x_i^j\right); \ \overline{v}_i(x_i^j)]$

• aggregate the attribute values using weight information to obtain new value interval

$$V_L(x^j) = [\underline{v}_L(x^j); \ \overline{v}_L(x^j)]$$

= $[\min_{w} \sum_i w_i v_i(x_i^j); \ \max_{w} \sum_i w_i v_i(x_i^j)]$



Risk assessment

Identify the most critical components by constructing a frontier of Pareto-optimal solutions through dominance relation

$$\boldsymbol{x^{j}} \succ \boldsymbol{x^{k}} \leftrightarrow \left\{ \frac{\underline{v}_{L}(x^{j}) \geq \overline{v}_{L}(x^{k})}{\underline{v}_{C}(x^{j}) \geq \overline{v}_{C}(x^{k})} \lor \frac{\underline{v}_{L}(x^{j}) \geq \overline{v}_{L}(x^{k})}{\underline{v}_{C}(x^{j}) \geq \overline{v}_{C}(x^{k})} \right\}$$

$$L = likelihood$$

$$C = severity$$



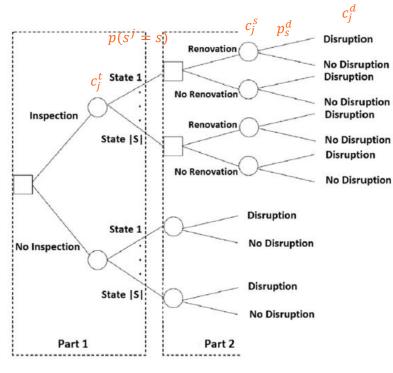
20.11.2020

MS-E2191 Graduate Seminar on Operations Research: "Decision-Making under Uncertainty"

Likelihood Quantify the risk using value intervals V_L and V_C Step 1 and severity for likelihood and severity Risk Identify the riskiest network items assessment Decision tree Step 2 analysis Select optimal portfolio of Portfolio deciitems to be sion analysis inspected



Decision tree analysis (1/2)





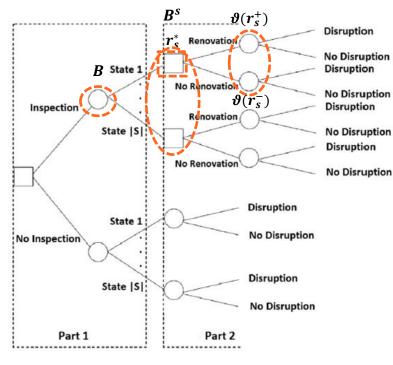


Quantify the benefit of inspection and possible maintenance

Information required:

- i. State probabilities $p(s^j = s)$
- ii. Disruption probabilities $p_s^d = [\underline{p}_s^d, \overline{p}_s^d]$
- iii. Inspection costs $c_j^t = [\underline{c}_j^t, \overline{c}_j^t]$
- iv. Renovation costs $c_j^s = [\underline{c}_j^s, \overline{c}_j^s]$
- v. Disruption consequences $c_j^d = [\underline{c}_j^d, \overline{c}_j^d]$

Decision tree analysis (2/2)



Mancuso et al. (2016)

- Calculate the expected costs of two alternatives:
 - Renovate r^+ : $\vartheta(r_s^+) = \left[\underline{\vartheta}(r_s^+); \overline{\vartheta}(r_s^+)\right]$
 - Do not renovate $r^-: \vartheta(r_s^-) = \left[\underline{\vartheta}(r_s^-); \overline{\vartheta}(r_s^-)\right]$

Calculate the optimal decision:

$$r_{s}^{*} = \begin{cases} r^{+}, if \ \overline{\vartheta}(r_{s}^{+}) < \underline{\vartheta}(r_{s}^{-}) \\ r^{-}, otherwise \end{cases}$$

- For each state *s*, calculate the benefit $B^s = [\underline{B}^s; \overline{B}^s]$ of possible renovation
- Aggregate the values to get the expected benefit $B = [\underline{B}; \overline{B}]$



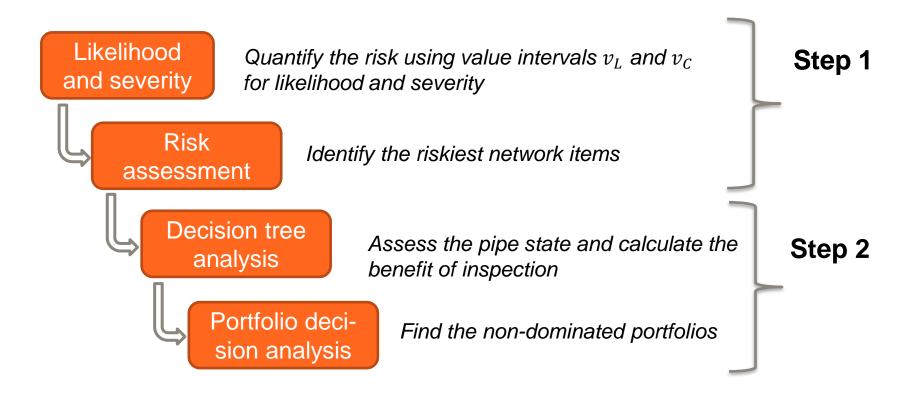
Portfolio decision analysis

Identify cost efficient portfolios of item inspections with two objectives of cost minimization and benefit maximization

Robust portfolio modeling (RPM): find non-dominated solutions to problem of maximizing portfolio value

 $\max_{p} V(p, w, v) = \max_{z(p)} \{z(p)vw \mid Az(p) \leq U, z(p) \in \{0, 1\}^m\}$ which items belong to the portfolio $\max_{v \in [n]} \{z(p)vw \mid Az(p) \leq U, z(p) \in \{0, 1\}^m\}$ budget constraint, portfolio balance, project dependencies etc. objective weights $\max_{v \in [n]} \{z(p)vw \mid Az(p) \leq U, z(p) \in \{0, 1\}^m\}$







References

A. Mancuso, M. Compare, A. Salo, E. Zio, and T. Laakso. *Risk-based* optimization of pipe inspections in large underground networks with imprecise information, pages 228-238. Reliability Engineering and System Safety 152, 2016.

J. Liesiö, P. Mild, and A. Salo. *Robust portfolio modeling with incomplete cost information and project interdependencies*, pages 679-695. European Journal of Operational Research 190, 2008.

J. Liesiö, A. Punkka, A. Salo, and E. Vilkkumaa. *Course: Decision Making and Problem Solving*, lecture notes, Aalto University, delivered April 2019.



Homework (1/2)

- a) Consider the four items given in the template. The value intervals for the likelihood and severity and the disruption costs of the items are given in a table. Using the dominance relation on slide 7, determine the non-dominant alternative.
- b) Using the formulas given in the next slide and the decision tree in the template, calculate the aggregated inspection benefit $B = [\underline{B}; \overline{B}]$ for that item.

Return your solution by 27.11. at 9.15 to hilkka.hannikainen@aalto.fi



Homework (2/2)

The benefit $B^s = [\underline{B}^s; \overline{B}^s]$ in state *s* is

$$\underline{B}^{s} = \begin{cases} 0, & r_{s}^{*} = r^{-} \text{ (don't renovate)} \\ \underline{\vartheta}(r_{s}^{-}) & -\overline{\vartheta}(r_{s}^{+}), r_{s}^{*} = r^{+} \text{ (renovate)} \end{cases}$$

$$\overline{B}^{s} = \begin{cases} 0, & r_{s}^{*} = r^{-} \text{ (don't renovate)} \\ \overline{\vartheta}(r_{s}^{-}) & -\underline{\vartheta}(r_{s}^{+}), r_{s}^{*} = r^{+} \text{ (renovate)} \end{cases}$$

The aggregated benefit $B = [\underline{B}; \overline{B}]$ is

$$\underline{B} = \sum_{s} p(s) \underline{B}^{s}$$
, $\overline{B} = \sum_{s} p(s) \overline{B}^{s}$

where p(s) is the probability of state s

