

INTEGRATION BY PARTS

Product rule:

$$\frac{d}{dx} [u(x)v(x)] = u'(x)v(x) + u(x)v'(x)$$

Integrate both sides and rearrange terms:

$$\int u'(x)v(x) dx = u(x)v(x) - \int u(x)v'(x) dx$$

Example $\int x^2 e^x dx = I$

$$\int \underbrace{x^2}_v \underbrace{e^x}_{u'} dx = \underbrace{x^2}_v \underbrace{e^x}_u - \underbrace{\int \underbrace{2x}_{v'} \underbrace{e^x}_u dx}_{2xe^x - \int 2e^x dx}$$

$$= x^2 e^x - 2xe^x + 2e^x + C$$

$$= e^x (x^2 - 2x + 2) + C = I$$

Derivative: $e^x x^2 + \underbrace{2xe^x - 2xe^x}_{0} - \underbrace{2e^x + 2e^x}_{2e^x}$
 $= x^2 e^x$

Example $\int \ln x \, dx = I$

$$\int \ln x \, dx = \int \underbrace{1}_{u'} \cdot \underbrace{\ln x}_v \, dx$$

$$= x \ln x - \int \underbrace{\frac{1}{x}}_{v'} \underbrace{x}_u \, dx$$

$$= x \ln x - x + C$$

Let us check again by taking the derivative:

$$\underbrace{x \cdot \frac{1}{x}}_{=1} + \ln x - 1 = \ln x$$

Theorem Every rational function can be integrated in closed form.

$$H(x) = \frac{P(x)}{Q(x)}, \quad P(x), Q(x) \text{ polynomials.}$$

Example $\int \frac{dx}{x(x^6+1)^2} = I$

Substitution: $x^6 = t, \quad 6x^5 dx = dt$

$$\int \frac{dx}{x(x^6+1)^2} = \frac{1}{6} \int \frac{6x^5 dx}{x^6(x^6+1)^2}$$

$$= \frac{1}{6} \int \frac{dt}{t(t+1)^2}$$

Partial fraction decomposition:

$$\frac{1}{t(t+1)^2} = \frac{A}{t} + \frac{B}{(t+1)^2} + \frac{C}{t+1}$$

$$= \frac{A(t+1)^2 + Bt + Ct(t+1)}{t(t+1)^2}$$

Set the numerators to be equal:

$$t^2: A + C = 0$$

$$t^1: 2A + B + C = 0$$

$$t^0: A = 1$$

$$\Rightarrow A = 1, C = -1, B = -1$$

Now we can integrate:

$$I = \frac{1}{6} \left(\ln |t| + \frac{1}{t+1} - \ln |t+1| \right) + C$$

$$= \frac{1}{6} \left(\ln \frac{x^6}{x^6+1} + \frac{1}{x^6+1} \right) + C$$

Example

$$\int \frac{x^4 + 1}{x^3 - x^2 + x + 1} dx = \int \left(x + 1 + \frac{2}{x^3 - x^2 + x - 1} \right) dx$$
$$= \frac{1}{2}x^2 + x + \int \frac{2}{(x-1)(x^2+1)} dx$$

$$\frac{2}{(x-1)(x^2+1)} = \frac{A}{x-1} + \frac{Bx+C}{x^2+1}$$

Solve:

$$A(x^2+1) + (Bx+C)(x-1) = 2$$

$$\Leftrightarrow \begin{cases} A + B = 0 \\ -B + C = 0 \\ A - C = 2 \end{cases}$$

$$\Leftrightarrow \begin{cases} A = 1 \\ B = -1 \\ C = -1 \end{cases} \quad \text{Integrate:}$$
$$\int \frac{dx}{x-1} - \int \frac{x+1}{x^2+1} dx$$

$$\int \frac{x+1}{x^2+1} dx = \int \frac{x dx}{x^2+1} + \int \frac{dx}{x^2+1}$$

Everything together :

$$I = \frac{1}{2}x^2 + x + \int \frac{dx}{x-1} - \int \frac{x+1}{x^2+1} dx$$

$$= \frac{1}{2}x^2 + x + \ln|x-1| - \frac{1}{2} \ln(x^2+1) - \arctan x + C$$

For rational functions the integral function always is a sum of polynomials, logarithms, or arctans.

Example $I_n = \int x^n e^x dx \quad (n \in \mathbb{N})$

Recursion:

$$\int x^n e^x dx = x^n e^x - \int n x^{n-1} e^x dx$$

$$I_n = x^n e^x - n I_{n-1}$$

It terminates, since $I_0 = \int e^x dx = e^x + C$

Example

$$\begin{aligned} I &= \int \sin^2 x \, dx = -\sin x \cos x + \int \cos^2 x \, dx \\ &= -\sin x \cos x + \int (1 - \sin^2 x) \, dx \\ &= -\sin x \cos x + \int dx - I \end{aligned}$$

We get : $I = \frac{x - \sin x \cos x}{2} + C$

Example $I = \int e^{kx} \sin nx \, dx \quad (k \neq 0)$

$$I = \frac{1}{k} e^{kx} \sin nx - \int \frac{n}{k} e^{kx} \cos nx \, dx$$

$$\left[\int e^{kx} \cos nx \, dx = \frac{1}{k} e^{kx} \cos nx + \int \frac{n}{k} e^{kx} \sin nx \, dx \right]$$

$$= \frac{1}{k} e^{kx} \sin nx - \frac{n}{k^2} e^{kx} \cos nx - \frac{n^2}{k^2} I$$

Again, solve for I !

ORDINARY DIFFERENTIAL EQUATIONS (ODE)

General 1st order ODE: $\frac{dy(x)}{dx} = f(x, y(x))$

The solution curve: $y(x)$

At every point (x, y) the slope of the solution curve $y(x)$ is $f(x, y(x))$.

Equation: $y' = f(x, y)$

→ we have information only up to a constant

Terminology:

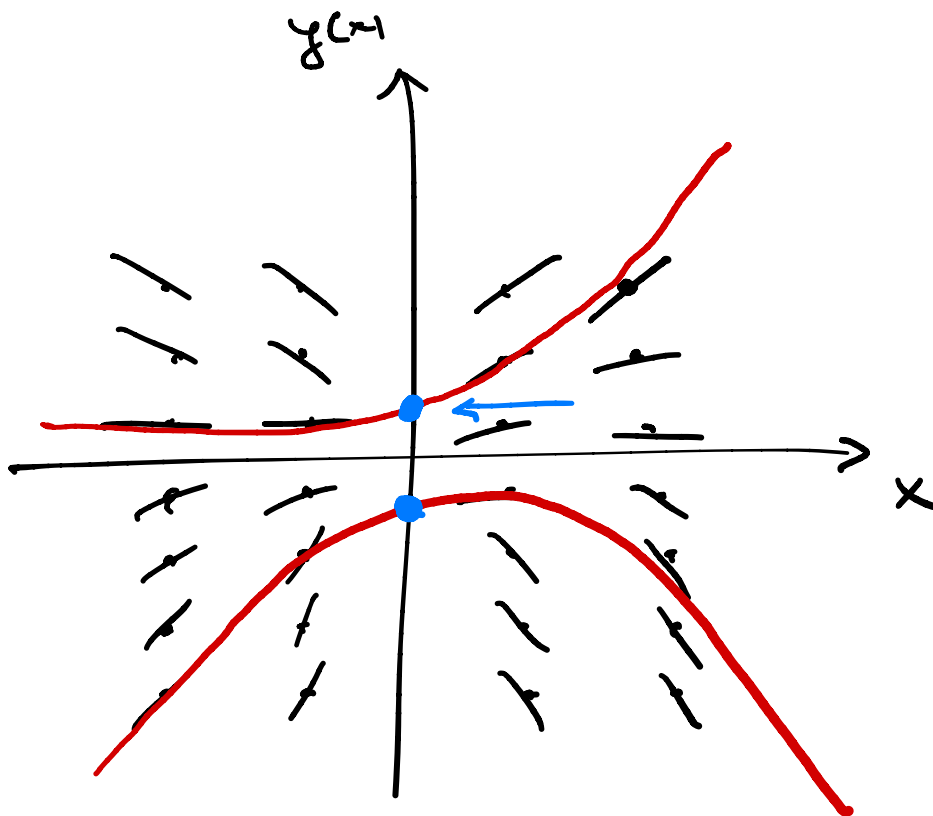
- the general solution includes all possible solutions
- the initial conditions lead to particular solutions
- the order of the ODE: the value of the highest derivative in the equation

Newton's Law: $F = ma$

$$\Leftrightarrow F = m \frac{d^2 s}{dt^2}$$

is a 2nd order ODE.

PHASE PORTRAIT



The ODE connects every x to some $y(x)$.

At every point (x, y) we can indicate the slope of $y(x)$ since we know how to compute the derivative.

Initial conditions fix particular solutions.

SEPARABLE EQUATIONS : $\frac{dy}{dx} = f(x)g(y)$

Formal equation : $\frac{dy}{g(y)} = f(x) dx$

By integrating $\int \frac{dy}{g(y)} = \int f(x) dx + C$

Example $\frac{dy}{dx} = \frac{x}{y}$

Here $f(x) = x$, $g(y) = \frac{1}{y}$

Thus, $\int y dy = \int x dx + \tilde{C}$

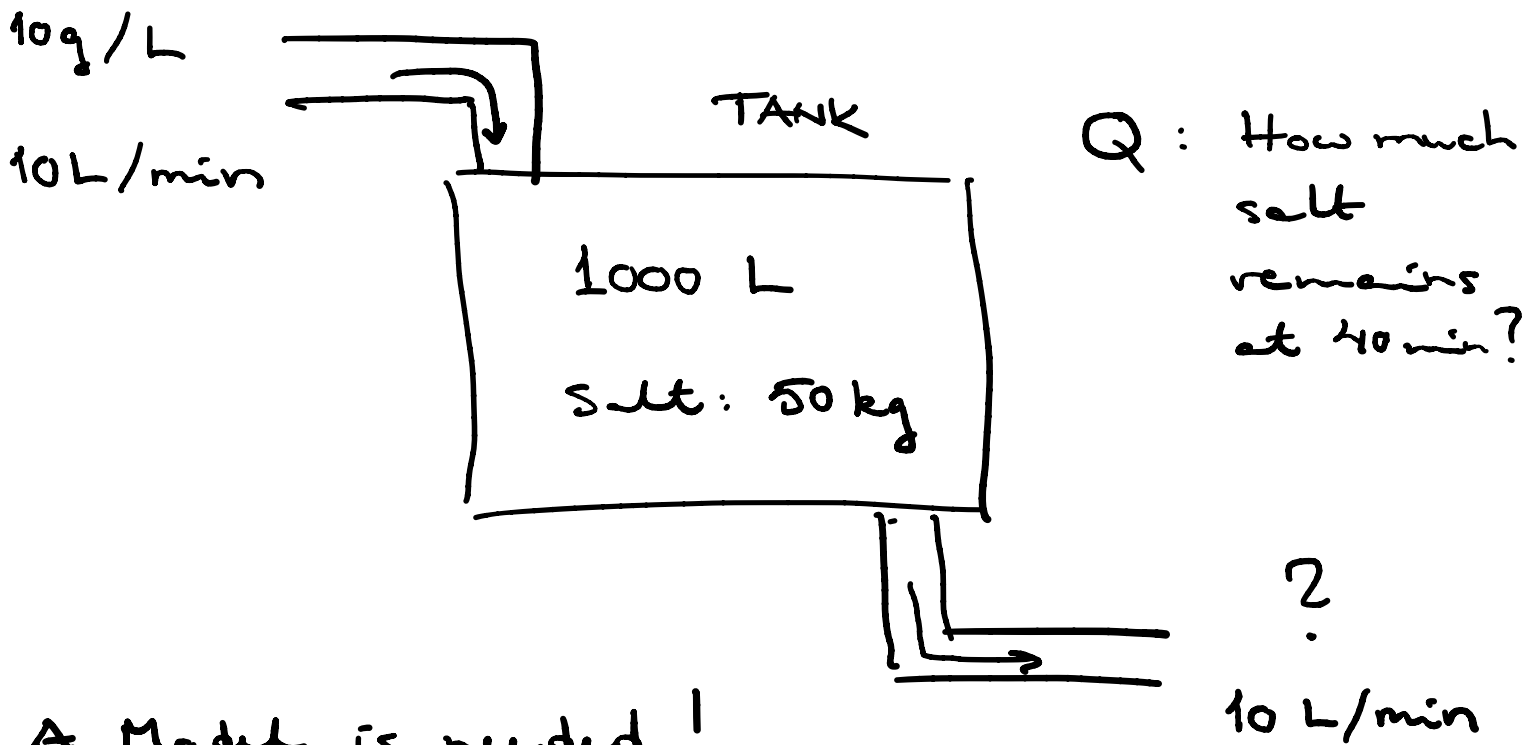
$$\Rightarrow \frac{1}{2} y^2 = \frac{1}{2} x^2 + \tilde{C}$$

Setting $2\tilde{C} = C$ we get $y^2 - x^2 = C$.

Hyperbolae, with asymptotes : $y = x$, $y = -x$

corresponding to $C = 0$.

A SOLUTION CONCENTRATION PROBLEM



A Model is needed!

$x(t)$ is the amount of salt ; $x(0) = 50$ kg

Salt entering the system :

$$10 \text{ g/L} \cdot 10 \text{ L/min} = \frac{1}{10} \frac{\text{kg}}{\text{min}}$$

Exiting :

$$\frac{x}{1000} \frac{\text{kg}}{\text{L}} \cdot 10 \text{ L/min} = \frac{x}{100} \frac{\text{kg}}{\text{min}}$$

The rate of change : $\frac{dx}{dt} = \text{rate in} - \text{rate out}$

$$= \frac{1}{10} - \frac{x}{100} = \frac{10 - x}{100}$$

$$\frac{dx}{10-x} = \frac{dt}{100}$$

$$\Rightarrow -\ln \underbrace{|x-10|}_{x > 10} = \frac{t}{100} + C$$

$$\Rightarrow \ln(x-10) = -\frac{t}{100} - C$$

$$\Rightarrow x(0) = 50 \text{ i.e. } -C = \ln 40$$

We get : $x = x(t) = 10 + 40e^{-t/100}$

After 40 minutes :

$$x(40) = 10 + 40e^{-0.4} \approx 36.8 \text{ kg}$$

LINEAR 1ST ORDER ODE :

$$\frac{dy}{dx} + p(x)y = q(x)$$

If $q(x) = 0$, homogeneous,
 $q(x) \neq 0$, non homogeneous.

$\frac{dy}{dx} + p(x)y = 0$ is separable :

$$y = K e^{-\mu(x)}, \quad \mu(x) = \int p(x) dx ;$$

$$\frac{d\mu}{dx} = p(x)$$

Formally : $L = \frac{d(\cdot)}{dx} + p(x)(\cdot)$

so that

$$L(y) = q(x)$$

If $L(y_h) = 0$, then surely

$$L(y) + L(y_h) = q(x)$$

or
$$L(y + y_h) = q(x)$$

A: Integrating factor

$$\begin{aligned}\frac{d}{dx} \left(e^{\mu(x)} y(x) \right) &= e^{\mu(x)} \frac{dy}{dx} + e^{\mu(x)} \frac{d\mu}{dx} y(x) \\ &= e^{\mu(x)} \left(\frac{dy}{dx} + p(x) y(x) \right) = e^{\mu(x)} q(x)\end{aligned}$$

$$\text{Integrate: } e^{\mu(x)} y(x) = \int e^{\mu(x)} q(x) dx$$

$$\Rightarrow y(x) = e^{-\mu(x)} \int e^{\mu(x)} q(x) dx$$

B: Variation of the parameter: $K = K(x)$

$$\frac{d}{dx} \left(K(x) e^{-\mu(x)} \right) + p(x) K(x) e^{-\mu(x)} = q(x)$$

$$\begin{aligned}\Rightarrow K'(x) e^{-\mu(x)} - K(x) \mu'(x) e^{-\mu(x)} \\ + K(x) p(x) e^{-\mu(x)} = q(x)\end{aligned}$$

$$\Rightarrow K'(x) = e^{\mu(x)} q(x)$$