

Diagonalisation

Theorem Let $S = (x_1 \ x_2 \ \dots \ x_n)$, where x_i are the $n \times n$ linearly independent eigenvectors of A . Then

$$S^{-1} A S = \Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n).$$

Naturally, $AS = S\Lambda$ and $A = S\Lambda S^{-1}$.

This has a remarkable consequence:

$$\begin{aligned} A^k &= \underbrace{A \cdot A \cdot \dots \cdot A}_{k \text{ times}} = S\Lambda S^{-1} S\Lambda S^{-1} \dots S\Lambda S^{-1} \\ &= S\Lambda^k S^{-1} \end{aligned}$$

But, when exactly are the eigenvectors linearly independent?

Theorem If (λ_i, v_i) are the eigenpairs of A and $\lambda_i \neq \lambda_j$, $i \neq j$, then $\{v_i\}$ are linearly independent.

If A has n such eigenvalues, it is diagonalisable.

Proof

$$(i) \quad c_1 v_1 + c_2 v_2 = 0$$

$$\begin{cases} c_1 A v_1 + c_2 A v_2 = 0 \\ c_1 \lambda_2 v_1 + c_2 \lambda_2 v_2 = 0 \end{cases} \iff \begin{cases} c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 = 0 \\ c_1 \lambda_2 v_1 + c_2 \lambda_2 v_2 = 0 \end{cases}$$

$$\Rightarrow c_1 (\lambda_1 - \lambda_2) v_1 = 0 \Rightarrow c_1 = 0$$

Similarly $c_2 = 0$. Hence $\{v_1, v_2\}$ are linearly independent.

(ii) $\sum_{i=1}^n c_i v_i = 0$; Using the same trick as above

$$c_1 (\underbrace{\lambda_1 - \lambda_2}_{\neq 0}) (\underbrace{\lambda_1 - \lambda_3}_{\neq 0}) \dots (\underbrace{\lambda_1 - \lambda_j}_{\neq 0}) v_1 = 0$$

That is, $S = (v_1 \ v_2 \ \dots \ v_n)$ can be constructed. \square

Example $A = \begin{pmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{pmatrix}$; $\lambda_1 = 1, \lambda_2 = 0.5$

$$A = S \Lambda S^{-1} = \begin{pmatrix} 0.6 & 1 \\ 0.4 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0.5 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0.4 & -0.6 \end{pmatrix}$$

Remember to maintain the order of λ_i 's and x_i 's!

$$A^k = S \Lambda^k S^{-1} \Rightarrow \lim_{k \rightarrow \infty} A^k = S \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} S^{-1} = \begin{pmatrix} 0.6 & 0.6 \\ 0.4 & 0.4 \end{pmatrix}$$

Side note: $A^k \xrightarrow{k \rightarrow \infty} 0$, if $|\lambda_i| < 1$ for all $i=1, \dots, n$.

Example $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$; $\lambda_{1,2} = 1$, $x_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$\dim N(A - 1 \cdot I) = 1$ (geometric order)

$\lambda = 1$ is a double eigenvalue (algebraic order)

\Rightarrow Orders do not match, A is defective.

Example $A = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 1 & 0 & 2 \end{pmatrix}$, $B = \begin{pmatrix} 2 & 0 & 0 \\ -1 & 4 & 0 \\ -3 & 6 & 2 \end{pmatrix}$

Same eigenvalues : i.e. the same spectra.

However, $\dim N(A - 2I) = 1 \Rightarrow A$ defective

$\dim N(B - 2I) = 2 \Rightarrow B$ diagonalisable

Symmetric Matrices

Theorem Spectral Theorem

Every symmetric matrix is diagonalisable:

$$A = Q \Lambda Q^T, \quad \lambda_i \in \mathbb{R}, \quad Q \text{ orthogonal.}$$

Theorems:

(A) The eigenvalues of a real symmetric matrix are real.

(B) If $\lambda_i \neq \lambda_j$, $i \neq j$, then corresponding eigenvectors are orthogonal.

Not (C) The algebraic and geometric orders are equal for all λ_i .

Proof (A) $\lambda \in \mathbb{C}$. $Ax = \lambda x$ or $A\bar{x} = \bar{\lambda}\bar{x}$ or transposed $\bar{x}^T A = \bar{x}^T \bar{\lambda}$.

$$\text{Inner products: } \begin{cases} \bar{x}^T Ax = \bar{x}^T \lambda x \\ \bar{x}^T Ax = \bar{x}^T \bar{\lambda} x \end{cases} \Rightarrow \lambda \bar{x}^T x = \bar{\lambda} \underbrace{\bar{x}^T x}_{\|x\|^2}$$

$$\Rightarrow \text{Im } \lambda = 0 \quad \square$$

(B) Let $Ax = \lambda_1 x$ and $Ay = \lambda_2 y$; $A = A^T$, $\lambda_1 \neq \lambda_2$.

$$(\lambda_1 x)^T y = (Ax)^T y = x^T A^T y = x^T Ay = x^T (\lambda_2 y)$$

$$\Rightarrow x^T y = 0$$

\square

Singular Value Decomposition (SVD)

$$A_{m \times n} = U \Sigma V^T \quad ; \quad \Sigma \text{ diagonal, } U, V \text{ orthogonal}$$

Left singular vectors: $AA^T = U \Sigma V^T V \Sigma U^T = U \Sigma^2 U^T$
 $\Rightarrow (AA^T)U = U \Sigma^2$

Right singular vectors: $A^T A = V \Sigma U^T U \Sigma V^T = V \Sigma^2 V^T$
 $\Rightarrow (A^T A)V = V \Sigma^2$

Multiply by A: $AA^T A v_j = \sigma_j^2 A v_j$
 $\underbrace{\hspace{1.5cm}} \quad \underbrace{\hspace{1.5cm}}_{\text{eigenvector of } AA^T}$

$$v_j^T A^T A v_j = \sigma_j^2 v_j^T v_j \quad \Rightarrow \|A v_j\|^2 = \sigma_j^2$$

Therefore we get a unit eigenvector $A v_j / \sigma_j = u_j$.

We conclude with a remarkable identity:

$$AV = U \Sigma$$

Compression: $A_{m \times n} = U_{m \times m} \Sigma_{m \times n} V^T_{n \times n} = U_{m \times r} \Sigma_{r \times r} V^T_{r \times n}$, where r is the rank.

$$= \sum_{i=1}^r \sigma_i u_i v_i^T$$

If $\sigma_1 \geq \sigma_2 \geq \dots$ decreases rapidly, then the sum can be a reasonable approximation even with a small number of terms.