

EEN-1020 Heat transfer Week 1: Fourier's law, heat equation, Newton's law and numerical solution

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Understanding heat transfer and fluid dynamics is essential in design of energy efficient applications

Heating and cooling





Combustion

P.Peltonen



Peltonen, Vuorinen (2019)





Roof Vortex 2 Front Front Front Front SH 1B Vortex 1 Vort

Base design

Maakala, Järvinen, Vuorinen, Energy, 160, 361-377, (2018)

Heat exchangers



Positioning heat transfer in AEE program e.g. computational study path in SEC major





Lecture 1.1 Theory and analysis: Energy and mass conservation, Newton's cooling law, Fourier's law and conduction (1d heat equation)

ILO 1: <u>Student can derive and explain physical origin of the heat</u> <u>equation, describe solution behavior by example solutions and</u> <u>boundary conditions</u>, and solve the heat equation (1d) and Newton's cooling law (0d) numerically in Matlab.



Remarks on temperature, thermal energy and transport mechanisms

Temperature

- For gases or liquids: temperature is actually closely related to the speed of the molecules on the molecular scales (molecules bouncing around). Molecular speeds are much higher (e.g. 2000-10000 m/s) than macroscopic fluid flow velocities (e.g. 0.1-10 m/s) in cooling/heating applications.
- For solids: temperature is related to the vibrational motion (velocity around an average position) of molecules/atoms in a lattice structure.

Energy

- Fluid=gas or liquid
- Fluids have kinetic energy and thermal energy. On the course we assume that

kinetic energy does not change form and are typically only interested in thermal energy changes $dE = mc_p dT$

• Main mechanisms of thermal energy transport: convection, diffusion (conduction), radiation.





Propane Gas Tank

Molecules inside the gas tank

Mean squared molecule velocity relates to temperature.

$$\overline{{1\over 2}m\overline{v^2}}={3\over 2}k_BT$$



Energy conservation (the "J/s" thinking)

- Heat transfer course is largely involved with thermal energy balance considerations for a system.
- [Energy] = $J = kgm^2/s^2$ [Power] = W = J/s
- Typically we consider heating/cooling of fluid and/or solid
- Fluids = gas/liquid are assumed to be of constant density.





Thermal energy and mass conservation (assume here: losses small)

Mass conservation (kg/s):

 $\rho U_{\rm in} A_{\rm in} = \rho U_{\rm out} A_{\rm out} = \dot{m}$

• Energy conservation (J/s):

 $c_p \rho U_{out} A_{out} T_{out} - c_p \rho U_{in} A_{in} T_{in} = P_{heat}$

 $c_p \dot{m} \Delta T = P_{heat} = q$



Even convective heat transfer problems involve typically conduction: Thermal conductivity vs diffusivity





Some thermal properties for air, water, aluminum and copper

 Table: Some material property estimates
 close to NTP conditions (see: Inc.deWitt Appendix)

Substance	Density [kg/m³]	Specific heat [kJ/kgK]	Thermal conductivity [W/mK]	Thermal diffusivity [m²/s]
Air	1.2	1.007	0.026	~1.6·10 ⁻⁵
Water	1000	4.217	0.569	~10 ^{−6}
Aluminum	2700	0.900	237	~0.97.10-4
Copper	8933	0.385	401	~1.2.10-4
Iron	7870	0.447	80.2	~10 ⁻⁵



Water vs air as coolants

- By Fourier's law the heat flux depends on temperature gradient and thermal conductivity
- For a given temperature gradient, heat flux ratio and thermal capacitance ratios are:

$$\frac{k_{water}}{k_{air}} \approx 22 \qquad \qquad \frac{\rho_{water} c_{p, water}}{\rho_{air} c_{p, air}} \approx 3500$$

- These matters explain why water is much more efficient heat exchange fluid than air offering e.g. more compact heat exchanger (fin) design
- Air and water are by far the most common heat transfer fluids



Dimensional analysis – "light version" a useful tool to reason dependencies and eliminate redundant parameters

- **Example**: [Velocity] = m/s
 - \rightarrow velocity depends on [x]=m and [t]=s
 - \rightarrow We make an Ansatz: $u = x^a t^b$
 - $\rightarrow m/s = m^a s^b$
 - \rightarrow For the units on lhs and rhs to match, the only option is: a=1, b=-1
- **Example**: [Thermal energy flux of flowing fluid] = $[\phi] = J/m^2s = W/m^2$
 - \rightarrow energy flux depends on
 - [p]=kg/m³
 - [U]=m/s
 - $[c_p] = J/kgK$
 - [T] = K
 - \rightarrow We make an Ansatz: $\varphi = \rho^a U^b c_p^c T^d$
 - \rightarrow For the units on lhs and rhs to match, the only option is: a=b=c=d=1 and $\varphi = \rho Uc_p T$



Ordinary differential equations vs partial differential equations on the course

• Example ODE:



Initial condition:

 $y(t=0)=y_o$

• Example PDE:

ODE \rightarrow the unknown function y=y(t) which could represent at given time e.g. average radioactivity of an object, average temperature, average concentration, ...

PDE \rightarrow the unknown function $\varphi = \varphi(x,t)$ which could represent at given time and point *e.g. radioactivity, temperatur*, ...

Initial condition

 $\phi(x,t=0)=\phi_o(x)$

 $\frac{\partial \phi}{\partial t} + u \frac{\partial \phi}{\partial x} = v \frac{\partial^2 \phi}{\partial v^2}, 0 < x < L$

Boundary condition (here fixed values) $\phi(x=0,t)=\phi_1, \phi(x=L,t)=\phi_2$



Example ordinary differential equation

 A storage box is insulated at initial temperature T_o and heat escapes only through one side at rate q ([q]=W). Find the average box temperature T=T(t).







Example ordinary differential equation

 A storage box is insulated at initial temperature T_o and heat escapes only through one side at rate q ([q]=W). Find the average box temperature T=T(t).



Note: this is formally correct for T > 0.





Newton's cooling law – an engineering tool

• Newton's cooling law: Rate of change of heat (W=J/s) for an object is proportional to temperature difference between the object and its surroundings.

$$mc_{p}\frac{dT}{dt}=-hA_{s}(T-T_{\infty})$$

 $T_{\infty} = const.$



- The temperature T=T(t) could represent e.g. the average temperature of a beverage in the fridge.
- More generally, T=T_s i.e. the object surface temperature (either average/representative or even local but then we talk about PDE's as in HW3-4) and heat transfer (either average or local) typically is attempted to be cast in the form below

$$q = hA_s(T_s - T_\infty)$$

· Here h is the convective heat transfer coefficient

$$[q]=J/s, [m]=kg, [c_p]=J/kg \cdot K, [T]=K, [h]=W/m^2 K, [A_s]=m^2$$



Fourier's law – a physical law/principle

• Fourier's law: Heat flux results from a temperature gradient. $a'' = -k \nabla T$

 $[q''] = W/m^2, [T] = K, [k] = W/mK, [\nabla T] = K/m$

• Fourier in 1d:

$$q'' = -k \frac{\partial T}{\partial x} = -k \frac{\Delta T}{\Delta x}$$

Heat rate vs heat flux:





Heat Equation

- Heat equation is a partial differential equation describing heat diffusion
- Solution of heat equation offers temperature distribution in a solid or fluid (gas or liquid) as a function of space and time i.e. T=T(x,t)

$$\rho c_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right)$$

- Important: Heat equation represents simply 1d energy conservation and transport via diffusion.
- Note: If second space derivative is positive/negative, then function T has a local minimum/maximum and temperature changes towards positive/negative i.e. heat flows from hot to cold.
- To solve the heat equation, also <u>initial conditions</u> (IC's) and <u>boundary</u> <u>conditions</u> (BC's) are needed

Example solutions of heat equation with two different boundary conditions

- Diffusive processes are very slow in comparison to convective processes
- Below, two examples of heat diffusion in iron (profiles taken from different times)
- Simulation time is in the order of 0.03-0.1s





Derivation of the Heat Equation from Energy Conservation Principle

 Heat equation can be derived easily by considering energy balance for an infinitesimal element of fluid/solid and flow of energy through the sides of the element by conduction via Fourier's law

$$\rho c_p \Delta T(x,t) \Delta x \Delta y \Delta z = \left[k \frac{\partial T(x+\Delta x/2,t)}{\partial x} - k \frac{\partial T(x-\Delta x/2,t)}{\partial x}\right] \Delta y \Delta z \Delta t$$

Energy change in a short Power exiting/entering [W/m²] Power entering/exiting [W/m²]

• Dividing by $\Delta x \Delta y \Delta z \Delta t$ and taking the limit when all Δ -variables $\rightarrow 0$ gives the heat eqn.



Example: Time-Dependent Analytic Solution of the Heat Equation in a Periodic (Infinite) Domain

• Assuming constant properties, it is convenient to write:

$$\frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left(\alpha \frac{\partial T}{\partial x} \right)$$

- In a periodic domain of length *L* with trigonometric (sinusoidal) initial condition, $T(x,t=0)=T_o+T_1sin(kx)$ the equation can be easily solved for unknown temperature
- It is noted that a general solution is of the form

$$T(x,t) = T_o + T_1 \sin(kx) \exp(-k^2 \alpha t)$$

where the **wavenumber** $k=2\pi/L$.

• Exercise: show that the solution above fulfills the equation by inserting it to the heat eqn.

Example: Steady State Solution of the Heat Equation with Fixed Temperature BC's

• In steady state time approaches infinity and we can write:

$$0 = \frac{\partial}{\partial x} \left(\alpha \frac{\partial T}{\partial x} \right), 0 \le x \le L$$

T(x=0)=T₁ and T(x=L)=T₂

• Integrate twice to obtain:

$$T(x,t) = A + Bx$$

• The requirement to fulfill BC's gives:

$$T(x,t) = T_1 + (T_2 - T_1) x/L$$



How Long Time Would it Take for the Heat to Diffuse Across Distance L?

Insight by dimensional analysis:

- The transient heat eqn tells that essentially the only parameter affecting temperature diffusion is α having units m²/s
- *t* is unknown but obviously *t* increases as *L* having unit meter increases
- Dimensionally, we try to find an expression $t=t(L, \alpha)$
- We make an Ansatz $t_{diff} \sim L^a \alpha^b$
- Match dimensions: $s = m^a m^{2b} s^{-b}$. Thus: a+2b=0 and $b=-1 \rightarrow a=2$
- Thereby $t_{diff} \sim L^2/\alpha$
- For an iron plate of thickness L=1mm the diffusion time estimate would be t_{diff} ~ 1e-6/1e-5 s~ 0.1 s
- **Exercise:** Estimate diffusion time for iron plate of thickness L=4mm.



How Long Time Would it Take for the Heat to Diffuse Across Distance L?

Insight by Fourier series:

• The earlier considered periodic solution in an infinite domain is:

$$T(x,t) = T_o + T_1 \sin(kx) \exp(-k^2 \alpha t)$$

• The exponential damping timescale is seen to be:

$$\tau_{damping} = 1/k^2 \alpha = \frac{L^2}{4 \pi^2 \alpha}$$

- **Summary**: two different scalings $t_{diff} \sim L^2/\alpha$ and $t_{damping} = L^2/4\pi^2\alpha$ were obtained with similar looking characteristic timescale (with a constant pre-factor difference).
- The scaling $t_{diff} \sim L^2/\alpha$ is a famous relationship and a very useful concept in heat transfer analysis.



Lecture 1.2 Numerical approach: Newton's cooling law and 1d heat equation

ILO 1: Student can derive and explain physical origin of the heat equation, describe solution behavior by example solutions and boundary conditions, <u>and solve the heat equation (1d) and</u> <u>Newton's cooling law (0d) numerically in Matlab</u>.



Newton's cooling law applied for a soda-can example solved numerically in Matlab



Recall: Newton's cooling law

$$\frac{dT}{dt} = \frac{-hA_s}{c_p m} (T - T_{\infty})$$
$$T(t=0) = T_o \text{ initial condition}$$



$$T(t) = (T_o - T_\infty) \exp\left(\frac{-hA_s}{c_p m}t\right) + T_\infty$$

Analytical solution exists \rightarrow good starting point for the computer learning: how to numerically solve temperature development in the above equation? Solving temperature over a short time interval (timestep)



Solution proceeds in discrete timesteps

$$t_n = n \Delta t, n = 0, 1, 2, \dots$$



Pseudo-code

Step 1:
$$\Delta T_n = -\Delta t \frac{hA_s}{c_p m} (T_n - T_\infty)$$

Step 2:
$$T_{n+1} = T_n + \Delta T_n$$

Step 3: go to Step 1 until simulation time exceeded

Temperature of a cooling soda can computed by Newton's cooling law numerically and analytically





Matlab implementation

Program: /Example0d/cool0d.m

Execution: >> cool0d

What it does: Solves 0d Newton's cooling law for temperature of a "0d" drink can.

Snapshot of code that does the job:

```
cp = 4190;
                      % specific heat J/kqK
dt = 20;
                     % timestep in s
To = 273+20;
                     % initial temperature K
Tinf=273+4;
                      % fridge temperature K
simutime = 3*3600;
                     % simulation time s
simusteps = round(simutime/dt);
T = To;
                       % initial temperature
for(k=1:simusteps)
    dT = -(h*As/(m*cp))*dt*(T-Tinf);
    T = T+dT;
    Tcol(k) = T; % collect temperatures to Tcol
end
```

HOW TO IMPLEMENT THIS				
IN PRACTICE?				
→ open Matlab terminal				
→ open text editor				
\rightarrow create new file with				

some name e.g. cool0d.m

 \rightarrow add the text from the

left to file cool0d.m

 \rightarrow run by typing text

coolOd on terminal



Plotting the results 1) e.g. plot(x, y, 'k-') where x and y are vectors 2) Note: length(x)=length(y)
3) >> help plot figure(1), clf, box, hold on alltime = linspace(0, simutime/3600, simusteps); plot(alltime, Tcol, 'k-', 'Linewidth',2) plot(alltime, (To-Tinf)*(exp(-h*As*3600*alltime/(m*cp))) + Tinf, 'b--', 'Linewidth',2) plot(alltime, (273+7)*(ones(length(alltime),1)), 'r-', 'Linewidth',2) plot(alltime, (Tinf)*(ones(length(alltime),1)), 'q-', 'Linewidth',2) h=xlabel('Time (h)'); h=vlabel('Temperature (K)'); h=legend('Numerical solution', 'Analytical solution','T

```
= 7 deg C', 'T = 4 deg C'); set(h, 'Fontsize', 16)
```

```
print -dpng TcoolingCan
```



Heat equation solved in 1d by finite difference method in Matlab



"Numerical solution of heat equation" is a "solution at discrete data points"

- Heat equation is already quite challenging equation to solve by pen/paper even in simple cases
- Typically, even if it would be possible to obtain an analytical solution, one would need a computer to evaluate/visualize the solution (e.g. sum of infinite Fourier series)
- **Discretization of solution points** means that in numerics e.g. temperature is evaluated in a finite value of evaluation points in space and time e.g. $T(x,t) \rightarrow T(x_i,t_i)$ where $x_i = i\Delta x$ and $t_n = n\Delta t$
- **Discretization of partial derivatives** means that the continuous partial derivatives are replaced by the discrete counterparts obtained by Taylor series expansions





X



Numerical approximation of partial derivatives

- Practically all heat transfer phenomena involve PDE's
- Finite difference formulas offer a way to approximate partial derivatives
- Once partial derivatives are known in space and time, then one obtains a way to solve temperature distributions
- The following convection diffusion equation type appears commonly on this course.

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} = \alpha \frac{\partial^2 T}{\partial x^2}$$



1st order Euler formula for time derivative at fixed space point.







 2^{nd} order central difference for 2^{nd} space derivative at a fixed time.

Observation: if the solution points from time level n are known in each point I the new solution values at time level n+1 can be solved for.



Discretization of 1d Heat Equation by Finite Difference Method

Continuous PDE

Discretized PDE



Courant-Friedrichs-

stability).

(CFL<0.5 for





Now we have an explicit update scheme for T in each discrete grid point i. This is the explicit Euler scheme (most simple timestepping).



Boundary condition types

- The problem: some numerical value needs to be assigned to the "ghost cells"
- Otherwise: we can not calculate second derivative of T in cells i=2 and i=N+1
- Case 1: Boundary temperature fixed \rightarrow boundary heat flux follows
- Case 2: Boundary heat flux zero (insulated) \rightarrow zero temperature gradient through boundary
- Case 3: Boundary heat flux fixed \rightarrow boundary temperature follows.



 \rightarrow **Ghost cell:** we can imagine a virtual cell outside the domain where we enter a temperature value so that the desired BC becomes exactly fulfilled.



Update scheme for 1d heat equation

1) Set boundary conditions to cells 1 and N+2 using T from step n.

2) Update new temperature at timestep n+1 in the internal cells 2...N+1

3) Update time according to t = t + dt



 T_i^n

4) Go back to 1)

This update scheme is very easy to program in Matlab for-loop

riaht

Program: /Example1d/HeatDiffusion.m
Execution: >> HeatDiffusion

What it does: Solves 1d heat equation in equispaced grid, fixed T and T

Main for-loop:

```
for(t=1:K)
    % set boundary conditions
    T(1) = 2*Tleft - T(2); T(N+2) = 2*Tright - T(N+1);
    % update temperature in inner points
    T(in) = T(in) + (dt*kappa/dx^2)*(T(in+1)-2*T(in)+T(in-1));
end
```

Note: I use constantly the "trick" which makes Matlab-programs often very fast.

<pre>% define a table which refers to the 'inner points' in = 2:(N+1);</pre>	Example for N+1 = 5 Command Window (1) New to MATLAB? Watch this <u>Video</u> , see <u>Examples</u> , or read <u>Getting Started</u> . >> 2:5
	ans =
	2 3 4 5

4



Supplementary material: Cooling demo from a class experiment in 2018



The next experimental demo (15 min) is strongly influenced by a hot hotel room





Group A: Experimenting on energy conservation analysis of homemade air-conditioner (AC)

Acknowledgement: Mika Ahlgren and Kari Saari

Warm air T_{in} entering



Tasks:

- 1) Measure velocities of inflow and outflow. Is mass conservation fulfilled?
- 2) Measure temperature of inflow and outflow?
- 3) Measure the velocity also at different positions. What do you observe?



- It is quite clear that in watts the average energy absorption rate of the ice (in Watts):
- $dE/dt = P_{in} P_{out} = \rho U_{in} A_{in} c_p T_{in} \rho U_{in} A_{in} c_p T_{out}$
- For incompressible fluid (air is incompressible to very high precision at low speeds < 100m/s) and thus mass conservation would imply $\rho U_{in}A_{in} = \rho U_{out}A_{out} = const.$
- However, it is not so clear where T_{out} comes from
- Class room thinking tasks:
- 1) How does dE/dt depend on:
- ice mass
- other aspects ?
- 2) How does T_{out} and dE/dt depend on
- inflow velocity
- inflow temperature
- other factors
- dE/dt being a constant
- 3) What kind of 3d features would this problem have?