Lecture 9 - part 1

Topic: Newton's method

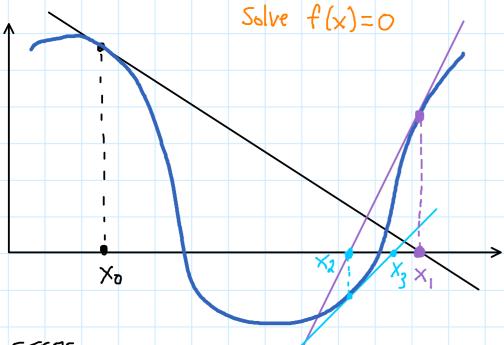
- Newton's method is a numerical method for solving (systems of) equations.
- Let's first look at one equation in one variable. We want to solve f(x) = 0. That is, we want to find where the graphs crosses the x-axis. The idea of the method is to guess an initial point x_0 (approximate solution). Approximate f(x) at x_0 by its tangent line y = f(x_0) + f'(x_0)(x-x_0). We can find where this tangent line crosses the x-axis. Putting y = 0 and solving for x gives x_1 = x = x_0 f(x_0)/f'(x_0) which we hope is a better approximation to f(x) = 0. Iterate this procedure, with the general expression x_{i+1} = x_i f(x_i)/f'(x_i).
- For many example this algorithm works efficiently. In general there is a great deal to be said to investigate the subtitles of such numerical methods. Aalto offers many courses related to computational mathematics and numerical analysis.
- Now let us look at the case of n-equations in n unknowns. Let n = 2 just for easy of writing, but there is no difference for larger numbers. We want to solve f(x,y) = 0 and g(x,y) = 0. Put these together as a column vector. Let F = [f g]^T (where T denoted transpose). Let z = [x y]^T. So the system of equations is now written F(z) = 0. The analogue to the tangent line or plane is L(z) = F(z_0) + J_F(z_0) (z z_0). Letting L = 0 and solving for z gives z_1 = z = z_0 J_{F}^(-1)(z_0) F(z_0). Here the (-1) means matrix inverse.
- Showed an example of implementing this on Maple. The code and output can be found in "materials".

Where to find this material

Adams and Essex. 13.7 (see "materials" for a copy of this section.)

Newton's method

This is a numerical method for finding zeros of a function.



STEPS

- O choose an initial guess Xo
- 2) draw the tangent line
- (3) X, is where this tangent intersects
- the x-axis (our new approximation)

 (4) Repeat . X2, X3, ...

Formula:

Tangent line at
$$x_0$$
 is $y = f(x_0) + f'(x_0)(x-x_0)$
Intercept is when $y = 0$, so

Solving for x gives
$$x = x_0 - \frac{f(x_0)(x-x_0)}{f'(x_0)}$$

So the next approximation, x_1 , is

$$x_{i} = x_{o} - \underbrace{f(x_{o})}_{f'(x_{o})}$$

Repeating this:
$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

The iterative formula is

$$X_{n+1} = X_n - \frac{f(x_n)}{f'(x_n)}$$

Newton's methos - 2 variables	As long as JF(Xo, yo) is invertible,
We deal the case of a function $F\colon \mathbb{R}^2 o \mathbb{R}^2$	
Let $F(x,y) = \begin{bmatrix} f(x,y) \\ g(x,y) \end{bmatrix}$ $F(x,y) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ Initial guess $\vec{X}_0 = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$ \vec{B} $\vec{A} = 0$	$(\vec{x} - \vec{x}_{\delta}) = -\vec{J}_{F}(x_{\delta}, y_{\delta}) \vec{F}(\vec{x}_{\delta})$ $\vec{X}_{1} = \vec{X}_{\delta} - \vec{J}_{F}(x_{\delta}, y_{\delta}) \vec{F}(\vec{x}_{\delta})$
To get the next I terate we solve	$ \frac{\partial R}{\partial y} = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} - \overline{J}_F(x_0, y_0) \begin{bmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{bmatrix} $
$\vec{y} - F(\vec{x_0}) = J_F(\vec{x_0})(\vec{x} - \vec{x_0})$ for \vec{x} when $\vec{y} = \vec{0}$	This all works in any chinension: F: IR" - IR"
$-F(\vec{x}_0) = J_F(\vec{x}_0)(\vec{x} - \vec{x}_0)$	$X_{n+1} = X_n - \overline{J}_{\varepsilon}(X_n y_n) F(X_n)$
In components	
$-\left[f(x_0,y_0)\right] = \left[\frac{\partial f}{\partial x}(x_0,y_0), \frac{\partial f}{\partial y}(x_0,y_0)\right] \left[x - x_0\right]$ $= \left[\frac{\partial g}{\partial x}(x_0,y_0), \frac{\partial g}{\partial y}(x_0,y_0)\right] \left[y - y_0\right]$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

