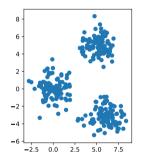
CS-E4075 - Special Course in Machine Learning, Data Science and Artificial Intelligence D: Signed graphs: spectral theory and applications

Spectral clustering

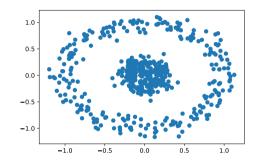
Bruno Ordozgoiti

Aalto University 2021

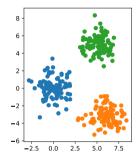
Algorithms for *k*-means will do well on these data.

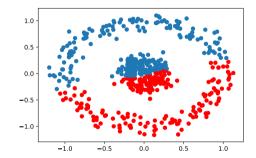


But how about this?



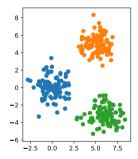


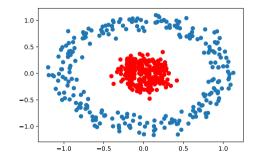




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Let's talk about spectral clustering.





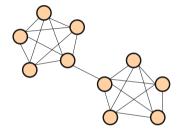
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Derivation

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Let us try to cluster the graph on the right. There are two "obvious" clusters, but can we use a clustering algorithm to discover them?

We will try to represent the graph vertices in a way that is suitable for an algorithm such as k-means.

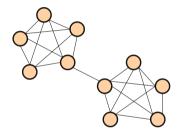


Let us try to cluster the graph on the right. There are two "obvious" clusters, but can we use a clustering algorithm to discover them?

We will try to represent the graph vertices in a way that is suitable for an algorithm such as k-means.

We will consider the adjacency matrix:

 w_{ij} is the weight of the edge connecting v_i and v_j .



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One way to make sure we can use *k*-means is by:

- being able to compute distances between vertices: $d(v_i, v_j)$,
- being able to compute the mean of a cluster of vertices: μ_i .

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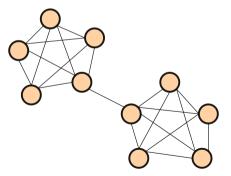
One way to accomplish this is to assign a real number y_i to each vertex v_i , so that

•
$$d(v_i, v_j) = |y_i - y_j|$$
 and
• $\mu_j = \frac{1}{|C_j|} \sum_{i \in C_j} y_j.$

Thus, our goal is to find a mapping of each vertex $v_i \mapsto y_i \in \mathbb{R}$ so that (intuitively) similar vertices are in the same cluster and different vertices are in different clusters.

In order to ensure that connected vertices are close, we can try to choose the y_i 's so that the following is small:

$$cost(y) = \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij}(y_i - y_j)^2.$$



$$cost(y) = \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij}(y_i - y_j)^2 = 2 \sum_{i=1}^{n} y_i^2 \sum_{j=1}^{n} w_{ij} - 2 \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} y_i y_j.$$

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Let
$$y = (y_1, \ldots, y_n)^T$$
. Note that $cost(y) = 2y^T Dy - 2y^T Wy = 2y^T Ly$.

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• We define L = D - W and show that minimizing $y^T L y$ is equivalent.

1. *L* is symmetric and positive semidefinite (all eigenvalues are real and \geq 0).

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Remember we want to minimize $y^T L y$.

▶ By property 1, the minimum is at least 0. $y = (0, 0..., 0)^T$ is a trivial solution, so we impose the constraint $y^T y = 1$.

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Remember we want to minimize $y^T L y$.

- ▶ By property 1, the minimum is at least 0. $y = (0, 0..., 0)^T$ is a trivial solution, so we impose the constraint $y^T y = 1$.
- If the graph is connected, the vector **1** = (1, 1, ..., 1)^T is a solution with 1^TL1 = 0. We impose the constraint y^T1 = 0.

Objective

$$\begin{array}{ll}
\min_{y} & y^T L y \\
\text{subject to} & y^T y = 1 \\
& y^T \mathbf{1} = 0
\end{array}$$

Since the vector $\mathbf{1} = (1, 1, ..., 1)^T$ is an eigenvector corresponding to the smallest eigenvalue, the above is solved (in a connected graph) by the **eigenvector** corresponding to the second smallest eigenvalue.

Spectral clustering protoalgorithm for 2-way connected graph partitioning.

Input: Graph G = (V, E) with adjacency matrix W.

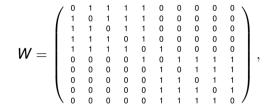
- 1. Compute the Laplacian L = D W.
- 2. Compute *y*, the eigenvector of *L* corresponding to the second smallest eigenvalue.
- 3. Run k-means treating the entries of y as one-dimensional data points.

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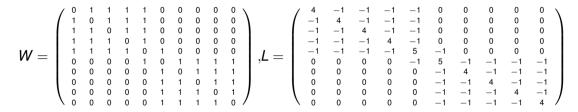


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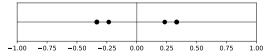
Eigenvalues: $(0, \sim 0.3, 5, 5, 5, 5, 5, 5, 5, -6.7)$.

Second smallest eigenvector: $(0.33, 0.33, 0.33, 0.33, 0.23, -0.23, -0.33, -0.33, -0.33, -0.33)^{T}$.



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Second smallest eigenvector: $(0.33, 0.33, 0.33, 0.33, 0.23, -0.23, -0.33, -0.33, -0.33, -0.33)^{T}$.

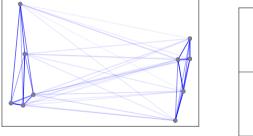


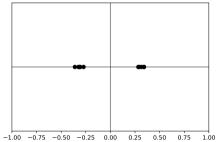
 \leftarrow We can cluster this with *k*-means.

Another example

Fully connected weighted graph.

Eigenvector: (0.32, 0.34, 0.28, 0.34, 0.29, -0.32, -0.27, -0.31, -0.36, -0.31)^T





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Optimizing graph cuts

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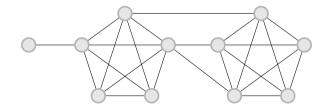
Given a graph G = (V, E), and a vertex subset $S \subseteq V$, with adjacency matrix A,

$$\operatorname{cut}(S,\overline{S}) = E(S,\overline{S}) = \sum_{i \in S, j \in \overline{S}} A_{ij}.$$

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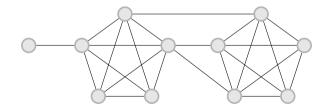
Given a graph G = (V, E), and a vertex subset $S \subseteq V$, with adjacency matrix A,

$$\mathsf{RatioCut}(S,\overline{S}) = \left(\frac{1}{|S|} + \frac{1}{|\overline{S}|}\right)\mathsf{cut}(S,\overline{S})$$

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Optimizing RatioCut

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Optimizing RatioCut

Define a vector x as

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$$x_i = egin{cases} \sqrt{|\overline{S}|/|S|} & ext{if } v_i \in S, \ -\sqrt{|S|/|\overline{S}|} & ext{if } v_i \in \overline{S}. \end{cases}$$

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We have

•
$$x^T L x = |V| \cdot \text{RatioCut}(S),$$

• $x^T 1 = 0,$

$$||x||_2 = \sqrt{|V|}.$$

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$$\begin{array}{ll} \min_{x} & x^{T}Lx\\ \text{subject to} & x^{T}\mathbf{1} = \mathbf{0},\\ & \|x\|_{\mathbf{2}} = \sqrt{|V|},\\ & x_{i} \text{ as defined above.} \end{array}$$

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Optimizing RatioCut

k clusters:

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Define k vectors (x_1, \ldots, x_k) as

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$$x_i^T x_j = 0, i \neq j,$$

$$\|x_i\|_2 = 1.$$

Objective:

$$\begin{array}{ll} \min_{X} & \textit{Tr}(X^{T}LX)\\ \text{subject to} & X^{T}X = I,\\ & X_{ij} = x_{ij} \text{ as defined above.} \end{array}$$

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Optimizing NCut

$$\begin{split} \mathsf{NCut}(S,\overline{S}) &= \left(\frac{1}{\mathsf{vol}(S)} + \frac{1}{\mathsf{vol}(\overline{S})}\right) \mathsf{cut}(S,\overline{S}).\\ \mathsf{vol}(S) &= \sum_{v \in S} d(v). \end{split}$$

Optimizing NCut

Define a vector x as

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We have

x^TLx = vol(V) · NCut(S),
 (Dx)^T1 = 0,
 x^TDx = vol(V).

Optimizing NCut

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 (Dx)^T1 = 0,
 x^TDx = vol(V).

 $\min_{x} \quad x^{T} D^{-1/2} L D^{-1/2} x$ subject to $(D^{1/2} x)^{T} 1 = 0,$ $x^{T} D x = \text{vol}(V),$ x_{i} as defined above.

Note: $D^{-1/2}LD^{-1/2}$ is known as the normalized Laplacian.

Optimizing NCut

k clusters:

$$\operatorname{NCut}(S_1,\ldots,S_k) = \sum_{i=1}^k \frac{\operatorname{cut}(S_i,\overline{S}_i)}{\operatorname{vol}(S_i)}.$$

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$$x_{ij} = \begin{cases} \frac{1}{\sqrt{\operatorname{vol}(S_i)}} & \text{if } v_j \in S_i, \\ 0 & \text{if } v_j \in \overline{S}_i. \end{cases}$$

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Objective:

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Unnormalized spectral clustering .

Input: Graph G = (V, E) with adjacency matrix W, number of clusters k.

- 1. Compute the Laplacian L = D W.
- 2. Compute the eigenvectors v_1, \ldots, v_k of *L* corresponding to the *k* smallest eigenvalues.

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- 3. Consider a matrix X whose columns are v_1, \ldots, v_k .
- 4. Run *k*-means on *X*.

Normalized variants:

Spectral clustering using normalized Laplacian.

Input: Graph G = (V, E) with adjacency matrix W, number of clusters k.

- 1. Compute the **normalized** Laplacian $L_{sym} = D^{-1/2}(D W)D^{-1/2}$.
- 2. Compute the eigenvectors v_1, \ldots, v_k of L_{sym} corresponding to the k smallest eigenvalues.
- 3. Consider a matrix X whose columns are v_1, \ldots, v_k . Normalize the rows of X to unit norm.
- 4. Run *k*-means on *X*.

Note:
$$L_{sym} = D^{-1/2}LD^{-1/2} = I - D^{-1/2}WD^{-1/2}$$
.

Further reading:

▶ Von Luxburg, Ulrike. "A tutorial on spectral clustering." Statistics and computing 17.4 (2007)

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Ng, Jordan, and Weiss. "On spectral clustering: Analysis and an algorithm." NIPS 2002.

Normalized variants:

Spectral clustering using random walk Laplacian.

Input: Graph G = (V, E) with adjacency matrix W, number of clusters k.

- 1. Compute the **random walk** Laplacian $L_{rw} = D^{-1}(D W)$.
- 2. Compute the **right** eigenvectors v_1, \ldots, v_k of L_{rw} corresponding to the *k* smallest eigenvalues.
- 3. Consider a matrix X whose columns are v_1, \ldots, v_k . Normalize the rows of X to unit norm.
- 4. Run *k*-means on *X*.

Note: $L_{rw} = D^{-1}L = I - D^{-1}W$. This is related to the random walk matrix.

Further reading:

- Von Luxburg, Ulrike. "A tutorial on spectral clustering." Statistics and computing 17.4 (2007)
- Dhillon, Inderjit S., Yuqiang Guan, and Brian Kulis. "Kernel k-means: spectral clustering and normalized cuts." KDD 2004.

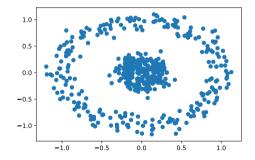
Recommended read: "A tutorial on spectral clustering." by Ulrike Von Luxburg.

As a rule of thumb, use the random walk variant.

Spectral clustering in practice

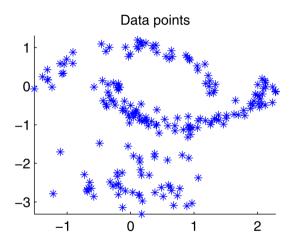
We have seen how to use spectral clustering on graphs.

But can we use it on any type of data? E.g. points in \mathbb{R}^d .

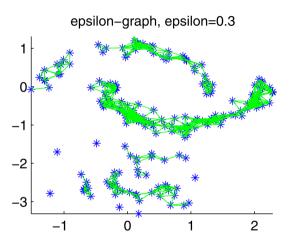


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We can create a graph based on these data.



epsilon-graph: there is an edge between *x* and *y* if and only if $||x - y||_2 \le \epsilon$.

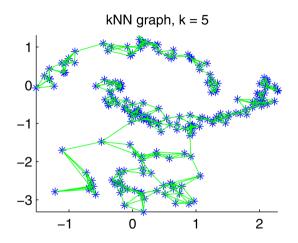


k-nearest-neighbours: there is an edge between x and yif and only if

x is one of the k nearest neighbours of y

or

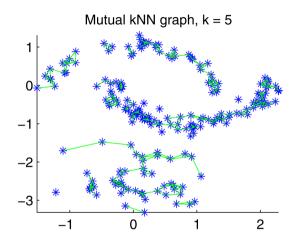
y is one of the k nearest neighbours of x.



mutual k-nearest-neighbours: there is an edge between x and yif and only if

x is one of the k nearest neighbours of y and

y is one of the k nearest neighbours of x.



Alternatively, we can consider a fully-connected weighted graph, by using a similarity function.

We will use the Gaussian (or RBF) kernel, defined as follows:

$$\kappa : \mathbb{R}^d \times \mathbb{R}^d o \mathbb{R}$$

 $x, y \mapsto \kappa(x, y) = \exp\left(\frac{-\|x - y\|_2^2}{2\sigma^2}\right).$

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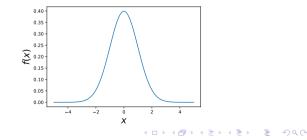
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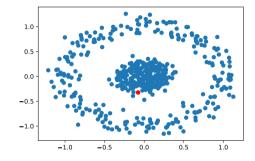
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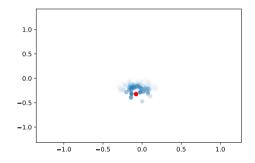
$$: \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}$$
$$x, y \mapsto \kappa(x, y) = \exp\left(\frac{-\|x - y\|_2^2}{2\sigma^2}\right).$$

Recall density for $\mathcal{N}(\mu, \sigma) : f(\mathbf{x}) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(\frac{-(\mathbf{x}-\mu)^2}{2\sigma^2}\right)$

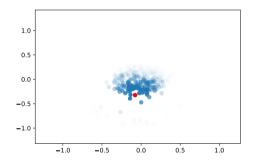
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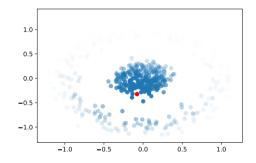


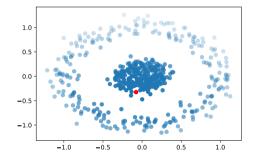


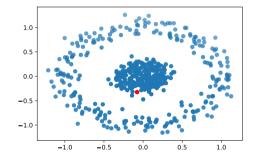
σ = 0.2



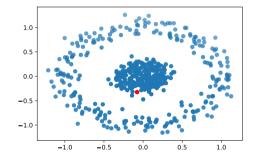
σ = 0.4







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σ = 1.6

Note: the matrix of a fully connected graph might be too large to store. Consider thresholding or using nearest neighbours.

Scalability: the similarity (adjacency) matrix is of size n × n. Thus, spectral clustering requires at least O(n²) computations just for the preliminary phase. The spectral decomposition requires O(n³) work in general. Always use sparse matrices if possible.

²https://en.wikipedia.org/wiki/LOBPCG

³Yan, Donghui, Ling Huang, and Michael I. Jordan. "Fast approximate spectral clustering." KDD 2009.

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- Use a nearest neighbour graph to avoid storing the $n \times n$ matrix.

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- Sample random subgraphs.
- Read more³

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Take-aways from this lecture:

- Derivation of spectral clustering from first principles.
- Derivation of spectral clustering from cut objectives:

- RatioCut
- NCut
- Spectral clustering algorithms.
- Building a graph from vector data.
- Practical considerations.