

# CS-C3240 – Machine Learning D

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Understand the concepts of

- unsupervised learning
- clustering
- k-means
- DBSCAN







Introduction

k-means

DBSCAN

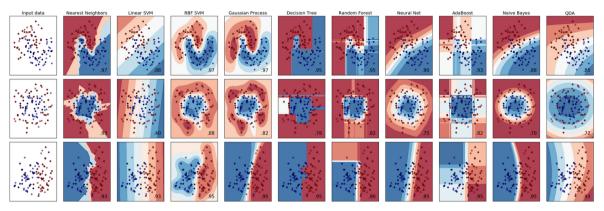
Gaussian Mixture Models





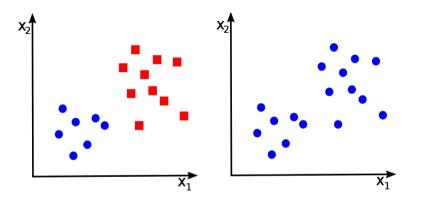
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## Summary supervised classification algorithms



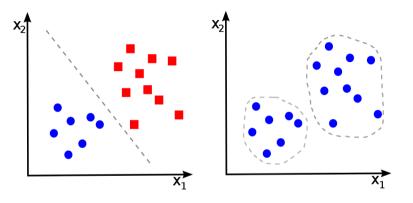
QDA: Quadratic Discriminant Analysis AdaBoost: combine 'weak learners'; subsequent learners trained in favor of previous misclassified instances BBE: Badial Basis Function





Supervised:  $\{(x_{1,1}, x_{1,2}) \rightarrow y_1, (x_{2,1}, x_{2,2}) \rightarrow y_2, \dots, (x_{n,1}, x_{n,2}) \rightarrow y_n\}$ Unsupervised:  $\{(x_{1,1}, x_{1,2}), (x_{2,1}, x_{2,2}), \dots, (x_{n,1}, x_{n,2})\}$ 





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k-means algorithm

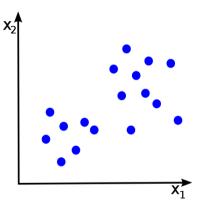
## k-means algorithm

Iteratively find k clusters in the data

## Init Randomly choose *k* points as initial cluster centroids

Repeat :

- → Assign data points  $x_i$ ,  $i \in \{1..n\}$  to these cluster centroids conditioned on distance:  $C_i = \{x_i | c_i \text{ is nearest centroid to } x_i\}$
- $\rightarrow\,$  Move cluster centroids to the center weight of the points associated to them

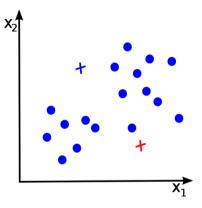






k-means algorithm

#### Init: k cluster centroids $c_i$ chosen randomly

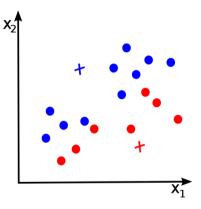






k-means algorithm

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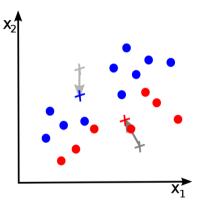




k-means algorithm

Init: k cluster centroids *c<sub>i</sub>* chosen randomly Repeat:

2: 
$$c_j(t+1) = \frac{1}{|C_j|} \sum_{i=1}^{|C_j|} x_i$$



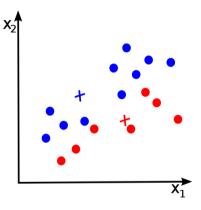




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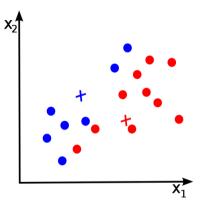




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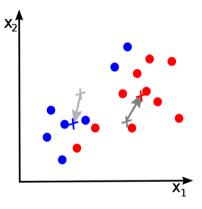




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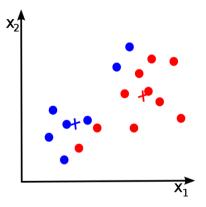




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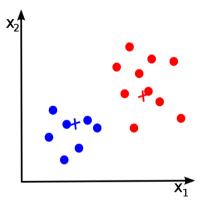




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k-means algorithm

#### How to randomly initialise the k-means algorithm

- The k-means algorithm may compute different solutions for different initial choice of cluster centroids
- With respect to the overall distance of the samples to their cluster centroids, k-means might run into local optima





k-means algorithm

#### How to randomly initialise the k-means algorithm

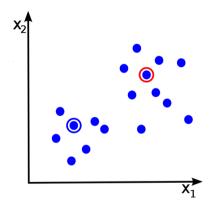
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With respect to the overall distance of the samples to their cluster centroids, k-means might run into local optima

Common choice of the initial *k* cluster centroids Choose the initial *k* cluster centroids randomly from the set of training samples

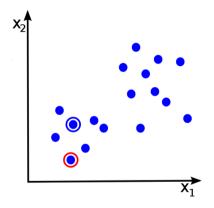






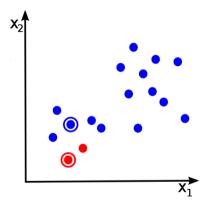






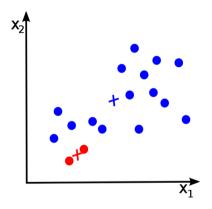






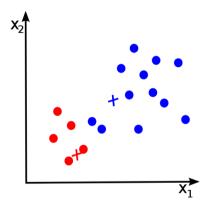






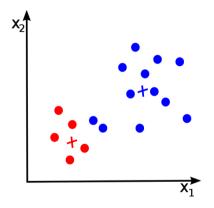






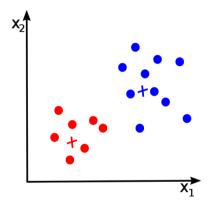








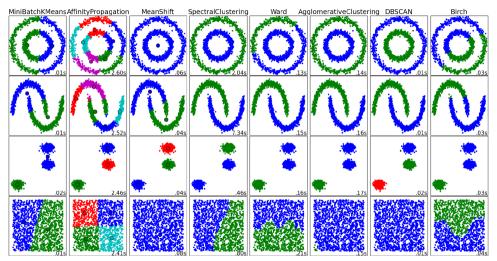








## **Overview clustering algorithms**









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# Density-Based Spatial Clustering of Applications with Noise (DBSCAN)

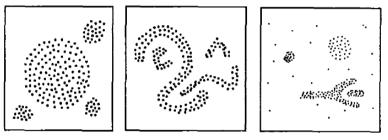
## Requirements for a clustering algorithm

- Minimal required domain knowledge
- Discovery of clusters with arbitrary shape
- Good efficiency on large data sets



#### Define cluster:

Each cluster has a typical density of points which is considerably higher than outside of the cluster<sup>1</sup>



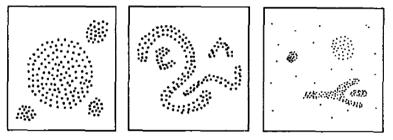
<sup>1</sup>Ester et al.: A Density-Based Algorithms for Discovering Clusters, AAAI





#### Define cluster:

Each cluster has a typical density of points which is considerably higher than outside of the cluster<sup>1</sup>



Concept: Density in the neighbourhood has to exceed some threshold such that a point is considered inside a cluster

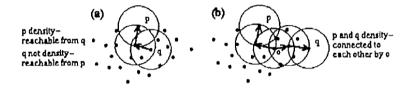
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#### Density-reachable

Given a Neighbourhood  $\mathcal{N}(x)$  and a density function  $\mathcal{D}(\mathcal{N}(x))$ , a point  $p_1$  is *density-reachable* from a point  $p_n$  if there is a chain of points  $p_1, \ldots, p_n$  such that  $p_{i+1} \in \mathcal{N}(p_i)$  and  $\mathcal{D}(\mathcal{N}(p_i))$  exceeds a certain threshold  $\tau^2$ 



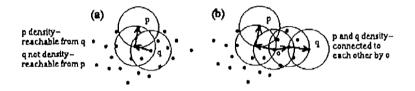
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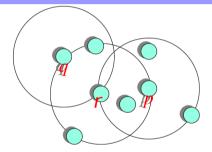
#### Density-connected

Two points  $p_1$  and  $p_n$  are *density-connected*, if there is a point  $r \in C$  such that both  $p_1$  and  $p_n$  are density-reachable from r

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#### Density-reachable and density-connected

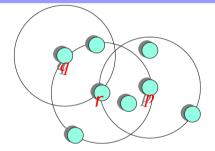






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#### Density-reachable and density-connected

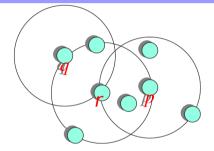


• *q* is density-reachable from *p* 





#### Density-reachable and density-connected

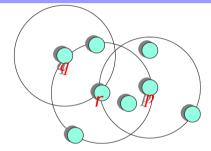


- *q* is density-reachable from *p*
- *p* is <u>not</u> density-reachable from *q* (low density around *q*)





#### Density-reachable and density-connected



- *q* is density-reachable from *p*
- *p* is <u>not</u> density-reachable from *q* (low density around *q*)
- *q* and *p* are density-connected via *r*



#### DBSCAN algorithm

- Start with an arbitrary point *p*
- Retrieve all points density-reachable from p
  - If p is an inner point, this procedure yields a cluster
  - If *p* is a border point, no points are density-reachable from *p* visit the next point in the data.





#### **DBSCAN** algorithm

- Start with an arbitrary point *p*
- Petrieve all points density-reachable from p
  - If p is an inner point, this procedure yields a cluster
  - If *p* is a border point, no points are density-reachable from *p* visit the next point in the data.

#### Need for recalculation with lower density for found clusters

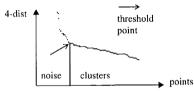
Since the density  $\Delta$  has to be chosen beforehand, it might happen that two clusters  $C_1$  and  $C_2$  with density higher than  $\Delta$  are detected as one cluster (if for  $c_1 \in C_1$  and  $c_2 \in C_2$  it is  $c_2 \in \mathcal{N}(c_1)$ 





#### Manually detect density of lowest density cluster:

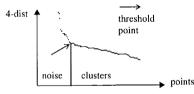
Plot the *k*-distance graphs for various values of *k* 





#### Manually detect density of lowest density cluster:

Plot the *k*-distance graphs for various values of *k* 



#### k-distance graph

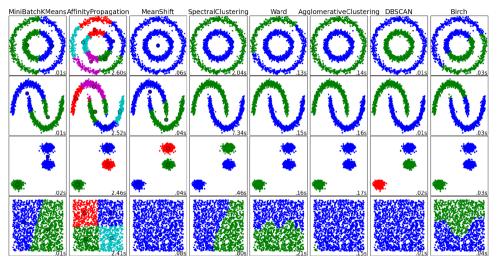
A k-distance graph is an ordered mapping of each point to the distance from its k-th nearest neighbour.

Points in clusters will achieve similar values while there is a threshold point that indicates points outside all clusters.





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## **Gaussian Mixture Models**





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## **Questions?**

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## Literature

- C.M. Bishop: Pattern recognition and machine learning, Springer, 2007.
- R.O. Duda, P.E. Hart, D.G. Stork: Pattern Classification, Wiley, 2001.

