

(1)

Conservation laws: linear momentum conserved in the absence of forces

$$\dot{\vec{p}} = \vec{F} = 0 \Rightarrow \vec{p} = \text{constant}$$

Angular momentum: $\vec{L} = \vec{r} \times \vec{p}$ if $\vec{p} = m\vec{v}$

$$\Rightarrow \dot{\vec{L}} = m\vec{r} \times \vec{v} + m\vec{r} \times \vec{v} = \vec{r} \times \vec{v} - \vec{r} \times \vec{v} = 0$$

$$\Rightarrow \frac{d\vec{L}}{dt} = m\vec{r} \times \vec{v} = \vec{r} \times \vec{F} = \vec{\tau} \quad (\text{torque})$$

Component of \vec{L} conserved if corresponding comp. of torque vanishes.

Note: \vec{L} depends on frame. Shift origin by $\vec{r}_0 \rightarrow \vec{r} \Rightarrow \vec{L} + \vec{r}_0 \vec{p}$
and $\vec{L} \Rightarrow \vec{r} \times \vec{p} + \vec{r}_0 \times \vec{p}$

Energy and work: Force field $\vec{F}(r)$. Test particle moves from \vec{r}_1 to $\vec{r}_2 + d\vec{s}$. Work done is

$$dW = \vec{F}(\vec{r}) \cdot d\vec{s}$$

$$\text{and from } 1 \rightarrow 2 : W_{1 \rightarrow 2} = \int_1^2 d\vec{s} \cdot \vec{F}(\vec{r})$$

Starts at \vec{r}_1 and passes through \vec{r}_2 : $d\vec{s} = \vec{v} dt$

$$\text{also } \vec{F} = m \frac{d\vec{v}}{dt}$$

$$\Rightarrow W_{1 \rightarrow 2} = \int_1^2 m dt \frac{d}{dt} \frac{1}{2} \vec{v}^2 = \frac{1}{2} m \vec{v}_2^2 - \frac{1}{2} m \vec{v}_1^2 \text{ independent of path}$$

$$\vec{T} = \frac{1}{2} m \vec{v}^2 = \text{kinetic energy}$$

Work done = increase in kinetic energy

IF force is **conservative** there is a potential $U(\vec{r})$
such that

$$\vec{F}(\vec{r}) = -\nabla U(\vec{r})$$

In this case

$\int d\vec{s} \cdot \vec{F} = - \int d\vec{s} \cdot \nabla U(\vec{r}) \Rightarrow$ integrand is differential change in
 U in moving from \vec{r} to $\vec{r} + d\vec{s}$

$$-\int dU = -U_2 + U_1$$

$$\bar{T}_2 - \bar{T}_1 = -U_2 + U_1 \Leftrightarrow T_1 + U_1 = \bar{T}_2 + U_2 \quad \text{total energy } E = \bar{T} + U$$

Note: Force is conservative also if

$$\nabla \times \vec{F}(\vec{r}) = 0 \quad \forall \vec{r}$$

$\oint d\vec{s} \cdot \vec{F}(\vec{r}) = 0$ for all closed paths

Musings on radiation pressure vs. ablation pressure
as rocket engines

a) radiation pressure: $E = \text{pulse energy}$, $\hbar\omega = \text{photon energy}$

$$\#\text{photons} \sim E/\hbar\omega, P_{\text{Photon}} = h\nu = \hbar\omega/c$$

impulse from reflecting the pulse

$$\Delta P_{\text{rad}} = 2(\#\text{photons}) \cdot \frac{\hbar\omega}{c} = \frac{2E}{c}$$

$$1\text{MW laser for } 1s \Rightarrow E = 10^6 \text{J} \Rightarrow \Delta P_{\text{rad}} \sim 7 \cdot 10^{-3} \text{kgm/s}$$

b) boil water with 1MW laser pulse (for 1s)

\Rightarrow boil about 0.4 litres or $N_w = 10^{25}$ molecules

molecule leaves at energy $k_B T \sim 5 \cdot 10^{-21} \text{J} = \Delta P_w L / 2m$

$$\text{impulse} \sim \sqrt{2mk_B T} \cdot N_w \sim 120 \text{ kgm/s}$$

\Rightarrow even if only small fraction of pulse energy ends up in
molecules flying in right direction, ablation can beat radiation pressure

Newton II : muuttuva massa esimerkki

Suhdeellisuuksieniassa kappaleen massa ja nopeus ovat kaavassa nyt, eikä lähtömääriä.

$$P = \frac{mv}{\sqrt{1 - v^2/c^2}}, \quad m = \text{massa levoessa}, \\ c = \text{valon nopeus}$$

Kahdyt teetään hiilikasta vakiovormista F_0 laosta. Mikä on hiilidaiden nopeus ajan funktion?

$$\frac{df}{dt} = F_0 \Rightarrow \int \frac{dv}{\sqrt{1 - v^2/c^2}} = \int dt F_0$$

$$\Rightarrow \frac{mv}{\sqrt{1 - v^2/c^2}} = F_0 t$$

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$$\Rightarrow m^2 v^2 = (F_0 t)^2 (1 - v^2/c^2)$$

$F_0 \rightarrow F(t)$

$$\sqrt{v^2 (m^2 + (F_0 t/c)^2)} = (F_0 t)^2$$

$\left\{ \begin{array}{l} dt F(t) = I(t) \\ \text{eli impulssi} \end{array} \right.$

$$\Rightarrow v(t) = \frac{F_0 t}{\sqrt{m^2 + (F_0 t/c)^2}}$$

$\left\{ \begin{array}{l} \text{jälkimmäinen domino; neljännen sisällä} \\ \text{ei kohda saavutta valonnopeutta.} \end{array} \right.$

Kun $t \gg \frac{mc}{F_0}$, jälkimmäinen domino; neljännen sisällä

$$\Rightarrow \lim_{t \rightarrow \infty} v(t) = c \Rightarrow \text{ei kohda saavutta valonnopeutta.}$$