



Power systems

a) Derive the following equation for the voltage drop over a transmission line

 $U_{loss} \approx IR \cdot \cos \varphi + IX \cdot \sin \varphi$

b) Can this equation be applied in all situations?

c) Draw the phasor diagrams related to the equation in cases where the reactive power is inductive and capacitive.

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Transmission line is mostly inductive reactance

$$\overline{Z} = R + jX \quad \overline{I} = I_p - jI_q$$

$$\Delta \underline{U}_{phase} = \underline{U}_{loss}$$

Question 1 a) Derive the following equation $\underline{U_{loss}} \approx IR \cdot \cos \varphi + IX \cdot \sin \varphi$



$$\Delta \underline{U}_{phase} = \underline{U}_{loss} = \underline{ZI} = (R + jX) \cdot (I_p - jI_q) \qquad ; I_p \text{ is active current, } I_q \text{ is reactive current}$$
$$\underline{U}_{loss} = RI_p - jRI_q + jIX_p - j^2XI_q = (RI_p + XI_q) + j(IX_p - RI_q) \qquad i^2 = i \times i = -1.$$

longitunal

transverse

Question 1 a) Derive the following equation $\underline{U_{loss}} \approx IR \cdot \cos \varphi + IX \cdot \sin \varphi$

The voltage drop is typically considered as the difference between the absolute values of the phase voltage $(U_{1,ph} - U_{2,ph})$. A good **approximate** for this can be attained by projecting the voltage phasor with the larger magnitude onto the smaller voltage phasor.

→ We can approximate that the imaginary part of \underline{U}_{loss} is zero (projection onto the smaller voltage phasor with angle of zero).

Also, knowing that

$$I_{p} = I \cdot \cos \varphi , I_{q} = I \cdot \sin \varphi$$

We get: $\underline{U}_{loss} = \left(RI_{p} + XI_{q}\right) + \underbrace{j\left(IX_{p} - RI_{q}\right)}_{\approx 0}$
 $\Rightarrow U_{loss} \approx IR \cdot \cos \varphi + IX \cdot \sin \varphi$,
where φ is the phase angle at the end of the line

Question 1 b) Can this equation be applied in all situations

The equation $U_{loss} \approx IR \cdot \cos \varphi + IX \cdot \sin \varphi$

is <u>only approximate and can be applied in a case with inductive</u> <u>current</u>.

For capacity current, q-component is positive:

$$\overline{I} = I_p + jI_q$$

The equation in this case is

$$\underline{U}_{loss} = (R + jX) \cdot (I_p + jI_q) = RI_p + jRI_q + jIX_p + j^2 XI_q = (RI_p - XI_q) + j(RI_q + IX_p)$$

Question 1 c) Draw the phasor diagrams



Note: the figure is out of perspective

Question 1 c) Draw the phasor diagrams

$$\overline{U}_{phase,1} = \overline{U}_{phase,2} + \overline{IZ} = \overline{U}_{phase,2} + \overline{I}(R + jX)$$

Capacitive load:

 $\overline{I} = I_p + jI_q$



Note: the figure is out of perspective



10 MW of active power is transferred using a three-phase line shown in the picture. Line-to-line voltages in the both ends of the line are 110 kV. **Calculate the power factor (cos\phi) of the load.**



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- In transmission system X >> R





$$Note: P = 3 \times \frac{U_{phase,1}U_{phase,2}}{X} \sin \delta = 3 \times \frac{\frac{U_{line,1}}{\sqrt{3}} \cdot \frac{U_{line,2}}{\sqrt{3}}}{X} \sin \delta = \frac{U_{line,1} \cdot U_{line,2}}{X} \sin \delta$$

The voltage amplitudes are now kept constant with voltage control: U_{phase,1} = U_{phase,2} The angle difference (power angle) between the voltages is:

$$\delta = \arcsin\left(\frac{PX}{U_1U_2}\right) = \arcsin\left(\frac{10 \text{ MW} \cdot 168 \Omega}{110 \text{ kV} \cdot 110 \text{ kV}}\right) \approx 7.98^{\circ}$$

Calculate the power factor of the load.



To calculate the power factor of the load, we need to know P_{load} and Q_{load} .

Now, the resistive losses are neglected: P1=P2=Pload=P

In order to keep the voltage level constant, a certain amount of reactive power has to flow into the line from point 2 and the shunt capacitance

Reactive power angle equation for the three phase system (between voltage U1 and U2 with a reactance between) and reactive power produced by shunt capacitance (lecture 6):

$$Q_2 = \frac{U_1 U_2}{X} \cos \delta - \frac{U_2^2}{X}$$
$$Q_c = Y U^2 = B U^2$$

$$Q_{load} = Q_2 + \frac{Q_c}{2} = \frac{U_1 U_2}{X} \cos \delta - \frac{U_2^2}{X} + \frac{B}{2} U_2^2$$

\$\approx 4.57 Myar



Calculate the power factor of the load.

$$\cos \varphi = \frac{P_{load}}{S_{load}} = \frac{P}{\sqrt{P^2 + Q_{load}^2}} = \frac{10 \text{MW}}{\sqrt{(10 \text{MW})^2 + (4.57 \text{MVAr})^2}}$$
$$\underbrace{\cos \varphi \approx 0.91_{\text{ind}}}_{\text{inductive since } Q_{\text{load}}} > 0$$

Another way:

Question 2

$$\underbrace{\underline{U}_{\text{phase,1}}}_{\text{Ix} \rightarrow} \underbrace{\underline{X}}_{\text{Ix} \rightarrow} \underbrace{\underline{U}_{\text{phase,2}}}_{\text{Ix} \rightarrow} \underbrace{\underline{I}}_{\frac{1}{2}} \underbrace{\underline{I}}_{\frac{1}{2}} \underbrace{\underline{J}}_{\frac{1}{2}} \underbrace$$

A turbine generator is delivering 20MW at 50Hz to a local load; it is not connected to the grid.

The load suddenly drops to 15MW; and the turbine governor starts to close the steam valve after a delay of 0.5s.

The stored energy in the rotating parts is 80MJ at 3000rev/min. What is the generated frequency at the end of the 0.5s delay?

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Question 3

1. $W_k = \frac{1}{2} J \omega^2$

What is the generated frequency at the end of the 0.5s delay?

Generated steady-state power = 20 MW.

Power usage drops to 15 MW.

Excess power of 20-15 = 5 MW accelerates the generator (frequency is increased)

Rotational energy is thus increased by:

$$\Delta Energy = P \times t = 5 \times 10^6 \,\mathrm{W} \times 0.5 \mathrm{s} = 2.5 \mathrm{MJ}$$

Rotational energy now:

$$E_{2} = E_{1} + \Delta E = 80 + 2.5 = 82.5 \text{MJ}$$

$$\frac{f_{1}^{2}}{f_{2}^{2}} = \frac{E_{1}}{E_{2}} \implies f_{2} = \sqrt{\frac{f_{1}^{2} \times E_{2}}{E_{1}}}$$
and
$$f_{2} = \sqrt{\frac{50^{2} \times 82.5}{80}} = \underline{50.775 \text{Hz}}$$

A 625-kVA 2.4 kV generator with $X_d^* = 0.20$ per unit is connected to a bus through a circuit breaker, as shown in the figure below. Connected through circuit breakers to the same bus are three synchronous motors rated 250 hp, 2.4 kV, 1.0 power factor, 90% efficiency, with $X_d^* = 0.20$ per unit. The motors are operating at full load, unity power factor, and rated voltage, with the load equally divided among the machines.

For interrupting current, presume that transient reactance for the synchronous motors is 1.5 times the subtransient reactance. For the generator, apply the subtransient reactance.





(c) Repeat part (b) for a three-phase fault at point P.

Question 4 General thoughts

Circuit breakers typically become active around 100ms after the fault. This equals around 5 cycles (50Hz \rightarrow 20ms per cycle). In this case, we are in a transient state rather than in the substransient state.



Question 4 (a) Draw the impedance diagram marked in per unit on a base of 625kVA, 2.4kV.

Base of 625kVA. Motors: Output 250hp, 2.4kV, 1.0 power factor, 90% efficiency.

Motor input:

$$S = \frac{P}{\cos(\varphi)} = \frac{\frac{250\text{hp}}{0.9} \times 746\frac{\text{W}}{\text{hp}}}{1} = 207.22\text{kVA.}$$
Motor subtransient reactance:

$$x''_{m} = X''_{d,m} \frac{S_{b}}{S} = j0.2 \times \frac{625\text{kVA}}{207.22\text{kVA}} = j0.603pu$$

Motor reactance in transient state: $x'_m = 1.5 \times x''_m = 1.5 \times j0.603 pu = j0.905 pu$



Question 4 b)

Let's calculate the transient current in Q using the Thevenin's theorem

Any possible fault occurs between the generator and the motors. One phase diagram (one generator, three motors):



Question 4 b

Let's calculate the transient current in Q (symmetrical short-circuit current) using the Thevenin's theorem

We can calculate the value of base current and absolute value of transient current:

Sb=625kVA
Ub=2.4kV

$$|I_B| = \frac{S_B}{\sqrt{3} \times U_B} = \frac{625}{\sqrt{3} \times 2.4} = 150.35A$$

$$|I'_f| = 8.315 \times 150.35 = 1250.2A$$
This is current in
Fault location Q
Current of breaker A:

$$I'_g = I'_f \frac{Z_{motors}}{Z_g + Z_{motors}} = -j8.315 \times \frac{0.302}{0.502} = -j5.0pu$$
 $\Leftrightarrow 752A$

Zg=j0.2

Zmotors=j0.302

Current of breaker B:

$$I_m = -j\frac{8.315 - 5.0}{3} = -j1.105 pu \iff 1.105*150.35A = 166A$$





Fault at P:

In this case breaker A carries the current fed by generator as in b) Breaker B carries currents of generator and the other two motors



Currents to be interrupted:

Breaker A:
$$I = I_g = -j5.0 pu = 752A$$

Breaker B: $I = I_g + 2 \times I_m = -j5.0 + 2(-j1.105) = -j7.21 pu = 1084A$