## ELEC-E8101 Digital and Optimal Control

 Exercise 1The problems marked with an asterisk ( $\star$ ) are not discussed during the exercise session. The solutions are given in MyCourses and these problems belong to the course material.

1. Find the $z$-transform of the following sequences using the definition:
a) $y[k]=1, k=0,1,2,3, \ldots$.
b) $y[k]=a^{k}, k=0,1,2,3, \ldots$ and $a$ is a constant.
c) $y[k]=e^{-k h / T}, k=0,1,2,3, \ldots$, and $h$ and $T$ are constants. Is this the same result as in part b) of the exercise?
2. Given that

$$
Y(z)=\frac{0.792 z^{2}}{(z-1)\left(z^{2}-0.416 z+0.208\right)}
$$

a) Determine the value of $y[k]$ as $k \rightarrow \infty$.
b) Verify your result using MATLAB.
3. Find the inverse z -transform of the following expression

$$
Y(z)=\frac{\left(1-e^{-a h}\right) z}{(z-1)\left(z-e^{-a h}\right)}, a \text { is a constant. }
$$

4. Using $z$-transforms solve for $y[k]$ from the following difference equation:

$$
y[k+2]-1.5 y[k+1]+0.5 y[k]=u[k+1],
$$

where $u[k]$ is the unit step starting at $k=0$, i.e.,

$$
u[k]= \begin{cases}1 & \text { if } k \geq 0 \\ 0 & \text { if } k<0\end{cases}
$$

Initial conditions: $y[-1]=1, y[0]=0.5$.
*5. Prove that the following holds:

$$
\mathcal{Z}\left\{\frac{1}{2}(k h)^{2}\right\}=\frac{h^{2} z(z+1)}{2(z-1)^{3}} .
$$

Hint: Begin by transforming $\mathcal{Z}\{k h\}$.

