Prediction and Time Series AnalysisIlmonen/ Shafik/ Voutilainen/ Lietzén/ MellinDepartment of Mathematics and Systems AnalysisFall 2020Aalto UniversityExercise 1.

## 1. Theoretical exercises

## Demo exercises

1.1 Let A be a real valued  $2 \times 2$ -matrix and let  $x, b \in \mathbb{R}^2$ ,

$$oldsymbol{A} = egin{bmatrix} a_{11} & a_{12} \ a_{21} & a_{22} \end{bmatrix}, \quad oldsymbol{x} = egin{bmatrix} x_1 \ x_2 \end{bmatrix}, \quad oldsymbol{b} = egin{bmatrix} b_1 \ b_2 \end{bmatrix}$$

(a) Write explicitly  $A^{\top}$ ,  $A^{\top}A^{\top}A^{\top}A^{\top}x$ ,  $x^{\top}A^{\top}A$  and  $x^{\top}Ax$ . Solution.

$$\boldsymbol{A}^{\top} = \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix}, \qquad \boldsymbol{A}^{\top} \boldsymbol{A} = \begin{bmatrix} a_{11}^2 + a_{21}^2 & a_{11}a_{12} + a_{21}a_{22} \\ a_{11}a_{12} + a_{21}a_{22} & a_{12}^2 + a_{22}^2 \end{bmatrix}$$
$$\boldsymbol{A} \boldsymbol{x} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 \\ a_{21}x_1 + a_{22}x_2 \end{bmatrix}, \qquad \boldsymbol{x}^{\top} \boldsymbol{A} = \begin{bmatrix} a_{11}x_1 + a_{21}x_2 & a_{12}x_1 + a_{22}x_2 \end{bmatrix}$$
$$\boldsymbol{x}^{\top} \boldsymbol{A} \boldsymbol{x} = a_{11}x_1^2 + (a_{12} + a_{21})x_1x_2 + a_{22}x_2^2$$

(b) Verify that  $\frac{\partial(\boldsymbol{b}^{\top}\boldsymbol{x})}{\partial\boldsymbol{x}} = \frac{\partial(\boldsymbol{x}^{\top}\boldsymbol{b})}{\partial\boldsymbol{x}} = \boldsymbol{b}^{\top}$ . Solution. Since,

$$\boldsymbol{b}^{\top}\boldsymbol{x} = \boldsymbol{x}^{\top}\boldsymbol{b} = b_1x_1 + b_2x_2,$$

and

$$\begin{bmatrix} \frac{\partial}{\partial x_1}(b_1x_1+b_2x_2) & \frac{\partial}{\partial x_2}(b_1x_1+b_2x_2) \end{bmatrix} = \begin{bmatrix} b_1 & b_2 \end{bmatrix} = \boldsymbol{b}^{\top},$$

which proves the claim. Note that the result can be generalized for  $\mathbb{R}^n$ -vectors.

(c) Verify that  $\frac{\partial (\boldsymbol{x}^{\top} \boldsymbol{x})}{\partial \boldsymbol{x}} = 2\boldsymbol{x}^{\top}$ Solution. The claim follows by taking the derivatives from,

$$\boldsymbol{x}^{\top}\boldsymbol{x} = x_1^2 + x_2^2.$$

Note that the result can be generalized for  $\mathbb{R}^n$ -vectors.

(d) Verify that  $\frac{\partial (Ax)}{\partial x} = A$ . Solution.

$$\frac{\partial(\boldsymbol{A}\boldsymbol{x})}{\partial\boldsymbol{x}} = \frac{\partial}{\partial\boldsymbol{x}} \begin{bmatrix} a_{11}x_1 + a_{12}x_2\\ a_{21}x_1 + a_{22}x_2 \end{bmatrix} = \begin{bmatrix} \frac{\partial}{\partial x_1}(a_{11}x_1 + a_{12}x_2) & \frac{\partial}{\partial x_2}(a_{11}x_1 + a_{12}x_2)\\ \frac{\partial}{\partial x_1}(a_{21}x_1 + a_{22}x_2) & \frac{\partial}{\partial x_2}(a_{21}x_1 + a_{22}x_2) \end{bmatrix} = \boldsymbol{A}.$$

Note that the result can be generalized for  $\mathbb{R}^n$ -vectors and  $\mathbb{R}^{m \times n}$ -matrices.

(e) Verify that  $\frac{\partial(\boldsymbol{x}^{\top}A)}{\partial \boldsymbol{x}} = \boldsymbol{A}^{\top}$ . Solution.

$$\frac{\partial(\boldsymbol{x}^{\top}\boldsymbol{A})}{\partial\boldsymbol{x}} = \frac{\partial}{\partial\boldsymbol{x}} \begin{bmatrix} a_{11}x_1 + a_{21}x_2 & a_{12}x_1 + a_{22}x_2 \end{bmatrix} \\ = \begin{bmatrix} \frac{\partial}{\partial x_1}(a_{11}x_1 + a_{21}x_2) & \frac{\partial}{\partial x_2}(a_{11}x_1 + a_{21}x_2) \\ \frac{\partial}{\partial x_1}(a_{12}x_1 + a_{22}x_2) & \frac{\partial}{\partial x_2}(a_{12}x_1 + a_{22}x_2) \end{bmatrix} = \boldsymbol{A}^{\top}.$$

Note that the result can be generalized for  $\mathbb{R}^n$ -vectors and  $\mathbb{R}^{n \times n}$ -matrices.

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(f) Verify that 
$$\frac{\partial (\boldsymbol{x}^{\top} \boldsymbol{A} \boldsymbol{x})}{\partial \boldsymbol{x}} = \boldsymbol{x}^{\top} (\boldsymbol{A} + \boldsymbol{A}^{\top}).$$
  
Solution.  

$$\frac{\partial (\boldsymbol{x}^{\top} \boldsymbol{A} \boldsymbol{x})}{\partial \boldsymbol{x}} = \begin{bmatrix} \frac{\partial}{\partial x_1} (a_{11} x_1^2 + (a_{12} + a_{21}) x_1 x_2 + a_{22} x_2^2) & \frac{\partial}{\partial x_2} (a_{11} x_1^2 + (a_{12} + a_{21}) x_1 x_2 + a_{22} x_2^2) \end{bmatrix}$$

$$= \begin{bmatrix} 2a_{11} x_1 + (a_{12} + a_{21}) x_2 & (a_{12} + a_{21}) x_1 + 2a_{22} x_2 \end{bmatrix}$$

$$= \begin{bmatrix} a_{11} x_1 + a_{12} x_2 & a_{21} x_1 + a_{22} x_2 \end{bmatrix} + \begin{bmatrix} a_{11} x_1 + a_{21} x_2 & a_{12} x_1 + a_{22} x_2 \end{bmatrix}$$

$$= \boldsymbol{x}^{\top} \boldsymbol{A}^{\top} + \boldsymbol{x}^{\top} \boldsymbol{A} = \boldsymbol{x}^{\top} (\boldsymbol{A} + \boldsymbol{A}^{\top}).$$

Note that the result can be generalized for  $\mathbb{R}^n$ -vectors and  $\mathbb{R}^{n \times n}$ -matrices.

Remark: consider a vector valued function  $f : \mathbb{R}^n \to \mathbb{R}^m$ , that is smooth enough,

$$f(\boldsymbol{x}) = egin{bmatrix} f_1(\boldsymbol{x}) \ f_2(\boldsymbol{x}) \ dots \ f_m(\boldsymbol{x}) \end{bmatrix}, \quad \boldsymbol{x} = (x_1, x_2, ..., x_n) \in \mathbb{R}^n.$$

The derivative of the function is

$$\frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}} = \begin{bmatrix} \frac{\partial f_1(\boldsymbol{x})}{\partial x_1} & \frac{\partial f_1(\boldsymbol{x})}{\partial x_2} & \dots & \frac{\partial f_1(\boldsymbol{x})}{\partial x_n} \\ \frac{\partial f_2(\boldsymbol{x})}{\partial x_1} & \frac{\partial f_2(\boldsymbol{x})}{\partial x_2} & \dots & \frac{\partial f_2(\boldsymbol{x})}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m(\boldsymbol{x})}{\partial x_1} & \frac{\partial f_m(\boldsymbol{x})}{\partial x_2} & \dots & \frac{\partial f_m(\boldsymbol{x})}{\partial x_n} \end{bmatrix}.$$

- **1.2** Consider the linear model  $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$ , where  $\mathbf{y}, \boldsymbol{\varepsilon} \in \mathbb{R}^n$ ,  $\mathbf{X} \in \mathbb{R}^{n \times (k+1)}$  and  $\boldsymbol{\beta} \in \mathbb{R}^{k+1}$ . Let the standard assumptions (i)–(v), given in the lecture slides, hold.
  - a) Show that the least squares (LS) estimator for the vector  $\boldsymbol{\beta}$  is  $\mathbf{b} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}$ .
  - b) Show that **b** is unbiased, that is,  $\mathbb{E}[\mathbf{b}] = \boldsymbol{\beta}$ .
  - c) Show that  $\operatorname{Cov}(\mathbf{b}) = \sigma^2 (\mathbf{X}^\top \mathbf{X})^{-1}$ .

## Solution.

a) The sum of squares is,

$$f(\boldsymbol{\beta}) = \boldsymbol{\varepsilon}^{\top} \boldsymbol{\varepsilon} = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^{\top} (\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) = \mathbf{y}^{\top} \mathbf{y} - 2\boldsymbol{\beta}^{\top} \mathbf{X}^{\top} \mathbf{y} + \boldsymbol{\beta}^{\top} \mathbf{X}^{\top} \mathbf{X}\boldsymbol{\beta}.$$

The LS-estimator for the vector  $\boldsymbol{\beta}$  is obtained by minimizing the sum of squares  $f(\boldsymbol{\beta})$  with respect to the vector  $\boldsymbol{\beta}$ . By differentiating  $f(\boldsymbol{\beta})$  with respect to  $\boldsymbol{\beta}$  and setting the derivative equal to zero, we obtain,

$$f'(\boldsymbol{\beta}) = -2\mathbf{y}^{\top}\mathbf{X} + 2\boldsymbol{\beta}^{\top}\mathbf{X}^{\top}\mathbf{X} = \mathbf{0}.$$

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By the standard assumptions, we have that  $rank(\mathbf{X}) = k + 1$ , which implies that the matrix  $\mathbf{X}^{\top}\mathbf{X}$  is nonsingular and  $\boldsymbol{\beta}$  is solvable. The solution,

$$\mathbf{b} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y},$$

minimizes the function  $f(\boldsymbol{\beta})$ , since  $\mathbf{X}^{\top}\mathbf{X}$  is always a positive definite matrix and,

$$f''(\boldsymbol{\beta}) = 2\mathbf{X}^{\top}\mathbf{X}.$$

b) Note that,

$$\mathbf{b} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}(\mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}) = \boldsymbol{\beta} + (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\boldsymbol{\varepsilon}.$$

Since the vector  $\boldsymbol{\beta}$  and the matrix **X** are non-random, it follows that,

$$\mathbb{E}[\mathbf{b}] = \mathbb{E}[\boldsymbol{\beta}] + (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbb{E}[\boldsymbol{\varepsilon}] = \boldsymbol{\beta} + (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{0} = \boldsymbol{\beta}.$$

c) Using part (b), we obtain,

$$\mathbf{b} - \mathbb{E}[\mathbf{b}] = \mathbf{b} - \boldsymbol{\beta} = (\mathbf{X}^{\top} \mathbf{X})^{-1} \mathbf{X}^{\top} \boldsymbol{\varepsilon}$$

Then, since  $\mathbf{X}$  is non-random,

$$\begin{aligned} \operatorname{Cov}(\mathbf{b}) &= \mathbb{E}[(\mathbf{b} - \mathbb{E}[\mathbf{b}])(\mathbf{b} - \mathbb{E}[\mathbf{b}])^{\top}] \\ &= E[(\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^{\top}\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}] \\ &= (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbb{E}[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^{\top}]\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1} \\ &= (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}(\sigma^{2}\mathbf{I})\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1} \\ &= \sigma^{2}(\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1} \\ &= \sigma^{2}(\mathbf{X}^{\top}\mathbf{X})^{-1}. \end{aligned}$$

## Homework

- **1.3** Consider the linear model  $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$ , where  $\mathbf{y}, \boldsymbol{\varepsilon} \in \mathbb{R}^n$ ,  $\mathbf{X} \in \mathbb{R}^{n \times (k+1)}$  and  $\boldsymbol{\beta} \in \mathbb{R}^{k+1}$ . Let the standard assumptions (i)–(v), given in the lecture slides, hold. Let  $\mathbf{M} = \mathbf{I} - \mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}$  and recall that rank $(\mathbf{M}) = n - (k+1)$ .
  - a) Let **e** be the estimated residual vector, that is,  $\mathbf{e} = \mathbf{y} \hat{\mathbf{y}}$ . Use the results obtained in previous exercises to show that

$$\operatorname{Cov}(\mathbf{e}) = \sigma^2 \mathbf{M}.$$

b) Use previous exercises and part (a), and show that,

$$s^2 = \frac{1}{n-k-1} \sum_{i=1}^n e_i^2,$$

is an unbiased estimator for  $\operatorname{Var}[\varepsilon_i] = \sigma^2$ , that is, show that  $\mathbb{E}[s^2] = \sigma^2$ . **Hint.** (1) The trace of a square matrix equals the sum of the corresponding eigenvalues, and, (2) the eigenvalues of an idempotent matrix are either 0 or 1. (You are not expected to prove results (1)-(2) in this exercise.)