Mathematics for Economists: Lecture 1

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Welcome to the course

- Course logistics
 - Lectures Mon, Tue at 13:15 14:45
 - Review sessions with Amin Mohazab Thu 10:15 11:45
 - This week: Tue at 13:15 14:45, Thu 10:15 11:45, first review session Fri 10:15 -11:45
 - Weekly Problem Sets to be returned via MyCourses on specified due date (not first week)

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- 20% of the grade based on problem sets, 80% on final exam
- To succeed in the course, you should attempt all problem sets
- Exam June 1, 9:00-12:00

Contents I

- Course contents: Part I
 - Lectures 1-2 Introduction and Applications of Linear Algebra Readings: Synopsis, Section 1, material for week 1, S&B: Chapter 6-11, 13.
 - Lectures 3-4: Multivariable Calculus Readings: Synopsis, Section 2, material for week 2, S&B: Chapters 14, 15.

Lecture 5: Unconstrained Optimization, Convexity and Concavity Readings: Synopsis, Section 3, material for week 3, S&B: Chapters 16, 17, 21.

Contents II

- Course contents: Part II
 - Lecture 7-8: Constrained Optimization Readings: Synopsis, Sections 4-5, material for week 4, S&B Chapters 18, 19
 - Lecture 9-10: Economic Applications of Constrained Optimization Readings: Synopsis, Sections 4-5: material for week 5, S&B:Chapters 20, 22

Lectures 11-12: Linear Dynamical Systems
 Readings: Synopsis, Sections 6: material for week 6, S&B: 23, 25.1, 25.2

Mathematics and Economic Models

- In Lionel Robbins' definition, economics studies the allocation of scarce resources amongst competing ends
- We seek a mathematical formulation for such problems
 - Competing ends captured by an objective function
 - Scarcity captured by feasible set
 - Economic process captured by either a constrained optimization problem of an economic agent or an equilibrium problem where many agents optimize simultaneously
 - ► Handout on *Setting the Scene* contains more details on this.
- Mathematical requirements for the theory
 - Choices over vectors (e.g. consumption bundles in the budget set or choice of inputs for a producer) -> Vectors and linear algebra
 - ► Objective functions often not linear -> Multivariable calculus
 - ► Environment for choices may evolve over time -> Dynamical systems

Linear economic models

- > The key object of study in linear algebra are *linear equations*
- A linear equation has the form

$$a_1x_1+a_2x_2+\cdots+a_nx_n=b,$$

where

- a_1, a_2, \ldots, a_n, b are fixed real numbers (parameters)
- x_1, x_2, \ldots, x_n are real valued variables
- A system of linear equations is a collection of such equations that hold simultaneously

Examples of systems

A system of two linear equations in two unknowns:

$$2x_1 + 3x_2 = 7 (1)$$

$$2x_1 + x_2 = 4$$
 (2)

A system of two non-linear equations in two unknowns:

$$2x_1x_2 + 3x_2 = 7 (3)$$

$$2x_1^2 + x_2 = 4 (4)$$

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- ► Goal: Determine competitive equilibrium prices and quantities for two goods i ∈ {1,2}.
- Demand Q^d_i depends on the prices of the two goods P₁ and P₂, on disposable income Y and on other factors K_i as follows:

$$Q_1^d = K_1 P_1^{\alpha_{11}} P_2^{\alpha_{12}} Y^{\beta_1},$$

$$Q_2^d = K_1 P_1^{lpha_{21}} P_2^{lpha_{22}} Y^{eta_2}$$

- How would you interpret the parameters α_{ii} ja β_i ?
- Think back to Principles 1 and elasticities

- > Y and K_i are the exogenous variables (i.e. ones not determined in the model).
- Supply functions Q_i^s for the two products are assumed to take the form:

$$\boldsymbol{Q}_{1}^{s}=\boldsymbol{M}_{1}\boldsymbol{P}_{1}^{\gamma_{1}},$$

$$Q_2^s = M_2 P_2^{\gamma_2}.$$

- Again, we take the variables M_i to be exogenous to the model.
- In equilibrium, supply equals demand so that

$$Q_1^d = Q_1^s,$$

and

$$Q_i^d = Q_i^s.$$

► Six equations for six endogenous variables $(Q_i^s, Q_i^d, P_i)_{i=1,2}$, but not linear

► But a change of variables helps: define the following new variables for *i* ∈ {1,2}:

$$q_i^d = \ln Q_i^d, \ q_i^s = \ln Q_i^s \ p_i = \ln P_i, y = \ln Y, \ m_i = \ln M_i, \ k_i = \ln K_i.$$

► By taking logarithms on both sides of each equation, we can write the six equations for *i* ∈ {1,2}:

$$\boldsymbol{q}_{i}^{d} = \boldsymbol{k}_{i} + \alpha_{ii}\boldsymbol{p}_{i} + \alpha_{ij}\boldsymbol{p}_{j} + \beta_{i}\boldsymbol{y},$$

$$\boldsymbol{q}_{i}^{\boldsymbol{s}}=\boldsymbol{m}_{i}+\gamma_{i}\boldsymbol{p}_{i},$$

$$q_i^s = q_i^d$$

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By the third equation, q^d_i = q^s_i for i ∈ {1,2}, and therefore the right hand sides in the first and the second equations are equalized:

$$k_i + \alpha_{ii}p_i + \alpha_{ij}p_j + \beta_i y = m_i + \gamma_i p_i, i \in \{1, 2\}.$$

- The only remaining endogenous variables are: p₁ ja p₂.
- Let's write the exogenous variables on the right-hand side and the endogenous variables on the left-hand side:

$$\begin{array}{rcl} (\alpha_{11} - \gamma_1) \, p_1 & +\alpha_{12} p_2 & = m_1 - k_1 - \beta_1 y, \\ \alpha_{21} p_1 & (\alpha_{22} - \gamma_2) \, p_2 & = m_2 - k_2 - \beta_2 y. \end{array}$$

Let's solve for p₁ from the top equation:

$$p_1 = \frac{m_1 - k_1 - \beta_1 y - \alpha_{12} p_2}{(\alpha_{11} - \gamma_1)}.$$

Substituting into the second equation gives:

$$p_{2} = \frac{m_{2} - k_{2} - \beta_{2}y - \alpha_{21}p_{1}}{(\alpha_{22} - \gamma_{2})}$$
$$= \frac{m_{2} - k_{2} - \beta_{2}y - \alpha_{21}\frac{m_{1} - k_{1} - \beta_{1}y - \alpha_{12}p_{2}}{(\alpha_{11} - \gamma_{1})}}{(\alpha_{22} - \gamma_{2})}$$

• Multiplying both sides by $(\alpha_{22} - \gamma_2)(\alpha_{11} - \gamma_1)$ gives:

$$(\alpha_{22} - \gamma_2)(\alpha_{11} - \gamma_1)p_2 = (\alpha_{11} - \gamma_1)(m_2 - k_2 - \beta_2 y) -\alpha_{21}(m_1 - k_1 - \beta_1 y) + \alpha_{12}\alpha_{21}p_2,$$

.

► Solving for *p*₂,

$$p_{2} = \frac{(\alpha_{11} - \gamma_{1})(m_{2} - k_{2} - \beta_{2}y) - \alpha_{21}(m_{1} - k_{1} - \beta_{1}y)}{(\alpha_{22} - \gamma_{2})(\alpha_{11} - \gamma_{1}) - \alpha_{12}\alpha_{21}}.$$

And substituting back gives:

$$p_{1} = \frac{m_{1} - k_{1} - \beta_{1}y - \alpha_{12} \frac{(\alpha_{11} - \gamma_{1})(m_{2} - k_{2} - \beta_{2}y) - \alpha_{21}(m_{1} - k_{1} - \beta_{1}y)}{(\alpha_{22} - \gamma_{2})(\alpha_{11} - \gamma_{1}) - \alpha_{12}\alpha_{21}}} \\ = \frac{(\alpha_{22} - \gamma_{2})(m_{1} - k_{1} - \beta_{1}y) - \alpha_{12}(m_{2} - k_{2} - \beta_{2}y)}{((\alpha_{22} - \gamma_{2})(\alpha_{11} - \gamma_{1}) - \alpha_{12}\alpha_{21})}.$$

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- The (logarithmic) equilibrium quantities are solved most easily from the supply curves.
- Finally P_i , Q_i are solved by exponentiating p_i , q_i .
- Exercise: Can you see how an improvement in the production technology for good 2 changes the equilibrium?
- Lessons from the example
- A nonlinear model can sometimes be transformed to a linear model (logarithmic transforms are particularly useful)
- Solving by substitution is clumsy and prone to errors.
- Gaussian elimination (familiar from Matrix Algebra) is a systematic representation of this process.

Gaussian Elimination

Consider the following system of linear equations:

$$2x_1 - x_2 = 0$$

-x_1 + 2x_2 - x_3 = 0
-x_2 + 2x_3 - x_4 = 0
-x_3 + 2x_4 = 5

► Write this in matrix form:

$$\left(egin{array}{ccccc} 2 & -1 & 0 & 0 \ -1 & 2 & -1 & 0 \ 0 & -1 & 2 & -1 \ 0 & 0 & -1 & 2 \end{array}
ight) \left(egin{array}{c} x_1 \ x_2 \ x_3 \ x_4 \end{array}
ight) = \left(egin{array}{c} 0 \ 0 \ 0 \ 0 \ 5 \end{array}
ight).$$

Gaussian Elimination

The augmented matrix corresponding to this system is:

$$\left(egin{array}{ccccccc} 2 & -1 & 0 & 0 & \mid & 0 \ -1 & 2 & -1 & 0 & \mid & 0 \ 0 & -1 & 2 & -1 & \mid & 0 \ 0 & 0 & -1 & 2 & \mid & 5 \end{array}
ight).$$

Step 1: Eliminate all terms a_{j1} below the first *pivot* a_{11} (i.e. first non-zero element in column 1). In this case, just multiply the first row by $\frac{1}{2}$ and add to second row.

$$\left(\begin{array}{ccccccccc} 2 & -1 & 0 & 0 & | & 0 \\ 0 & \frac{3}{2} & -1 & 0 & | & 0 \\ 0 & -1 & 2 & -1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 5 \end{array}\right)$$

Step 2: Eliminate all terms blow the second pivot: add the second row multiplied by ²/₃ to the third row.

$$\left(\begin{array}{cccccccccccc} 2 & -1 & 0 & 0 & | & 0 \\ 0 & \frac{3}{2} & -1 & 0 & | & 0 \\ 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 5 \end{array}\right)$$

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Gaussian Elimination

Step 3: Eliminate the term below the third pivot: add row 3 multiplied by ³/₄ to row 4.

$$\left(\begin{array}{cccccccccc} 2 & -1 & 0 & 0 & \mid & 0 \\ 0 & \frac{3}{2} & -1 & 0 & \mid & 0 \\ 0 & 0 & \frac{4}{3} & -1 & \mid & 0 \\ 0 & 0 & 0 & \frac{5}{4} & \mid & 5 \end{array}\right)$$

- Step 4: At this point, the matrix is in *row echelon form*, i.e. each row starts with more zeros than the previous row.
- ► Last row reads: $\frac{5}{4}x_4 = 5$ or $x_4 = 4$. You can substitute this back to row 3 that says $\frac{4}{3}x_3 x_4 = 0$ to get $x_3 = 3$. From row 2, $x_2 = 2$ and from row 1, $x_1 = 1$.
- In Gauss-Jordan elimination, one eliminates all elements above and below the pivot in these steps.
- This requires more eliminations, but avoids the substitutions in the last step

Gaussian Elimination: Second Example

Consider another example:

 $x_1 + x_2 = 1$ $x_1 + x_2 + x_3 = 2$ $x_2 + x_3 = 1$

In matrix form:

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Gaussian Elimination: Second Example

Step 1:

Notice that now the second pivot is in row 3. Swapping rows 2 and 3 does not change the solution to an equation. So Step 2: Swap rows 2 & 3:

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Now you can read $x_3 = 1$, $x_2 = 0$, and $x_1 = 1$.

Gaussian Elimination: General Principles

- Three elementary row operations that leave the solutions to systems of equations unchanged:
 - 1. Multiplying a row by a real number
 - 2. Adding rows to other rows
 - 3. Swapping rows
- Every matrix can be transformed to its row echelon form by elementary row operations.
- ▶ The rank of a matrix is the number of non-zero rows in its row echelon form.
- A linear system of equations Ax = b has a solution if and only if the rank of the coefficient matrix A is equal to the rank of the augmented matrix (A|b).
- If rank (A) = rank (A|b) = n, the solution is unique, if rank (A) = rank (A|b) < n, then the system has infinitely many solutions.</p>

Next Lecture

 A brief review of some of the main concepts of Matrix Algebra or Linear Algebra

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- Input-output models of economic production
- Linear models of exchange