

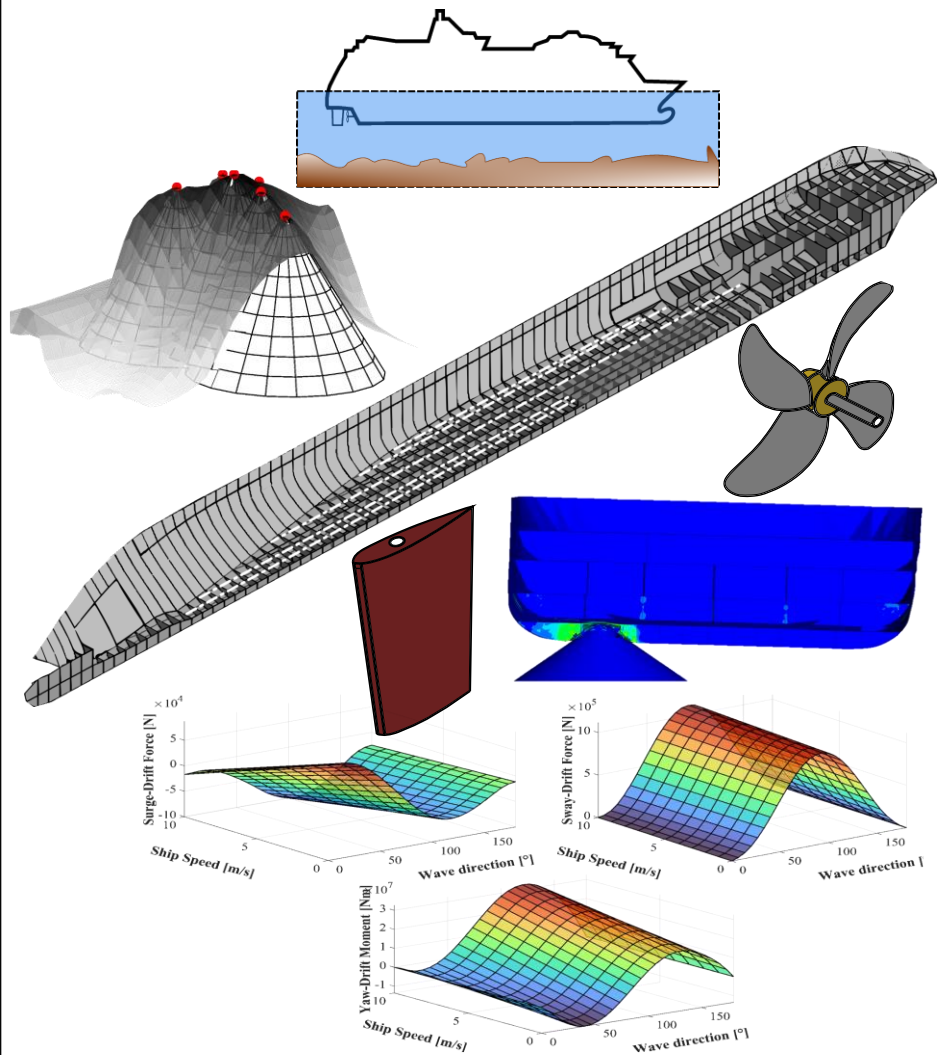
A rapid model for the assessment of ship hard grounding

Marine Technology GALA

Ghalib Humayun Taimuri
30 November, 2022



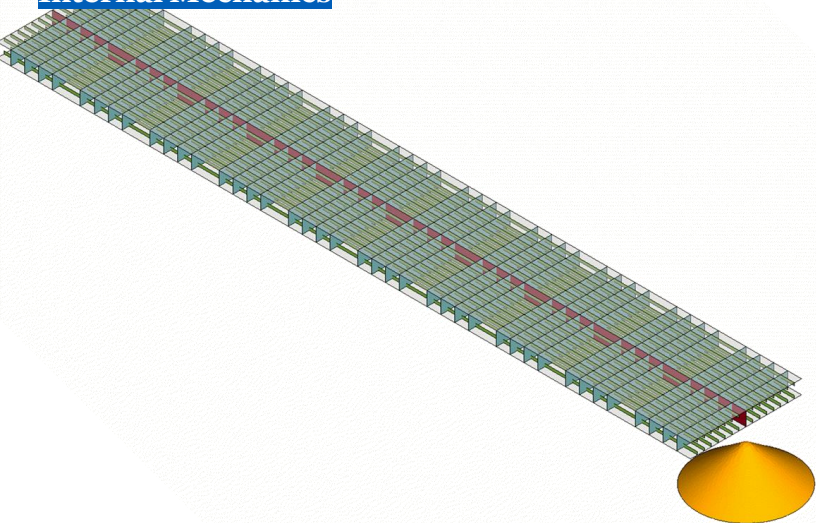
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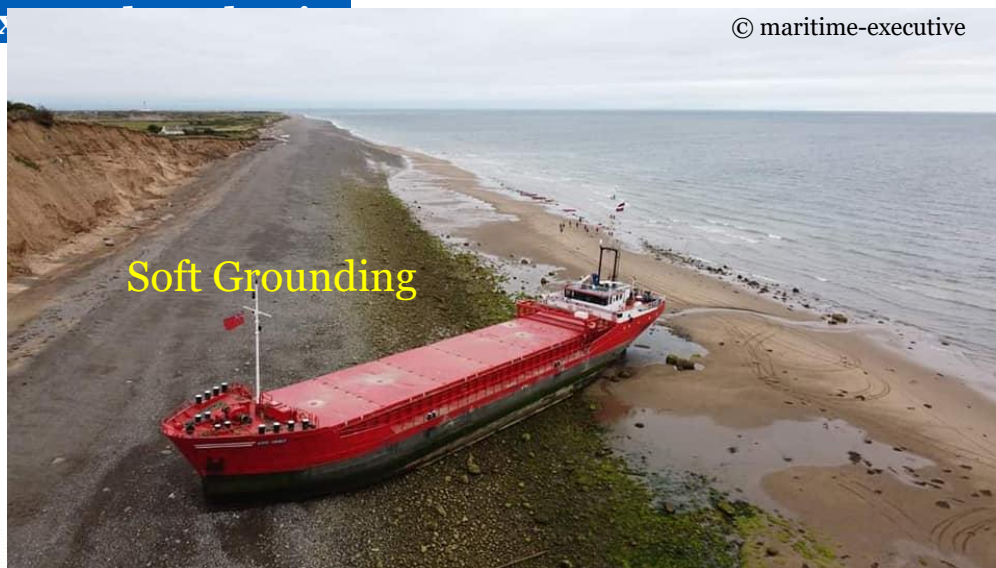
Overview

- ❖ What is ship grounding?
- ❖ Key Terminologies

Internal Mechanics



Ex



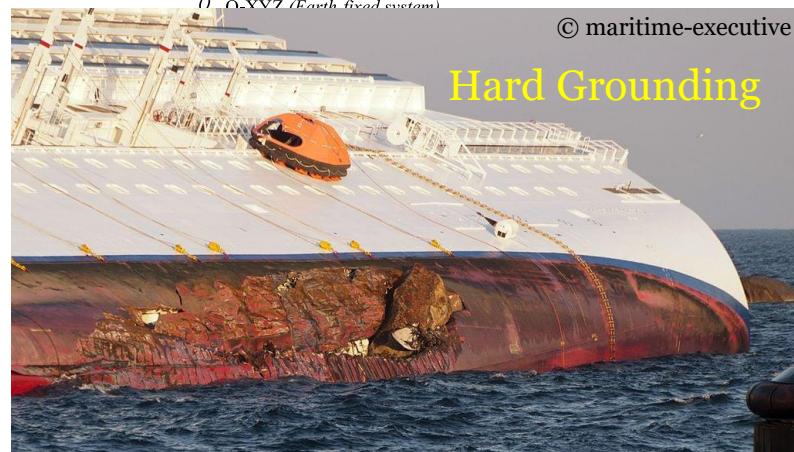
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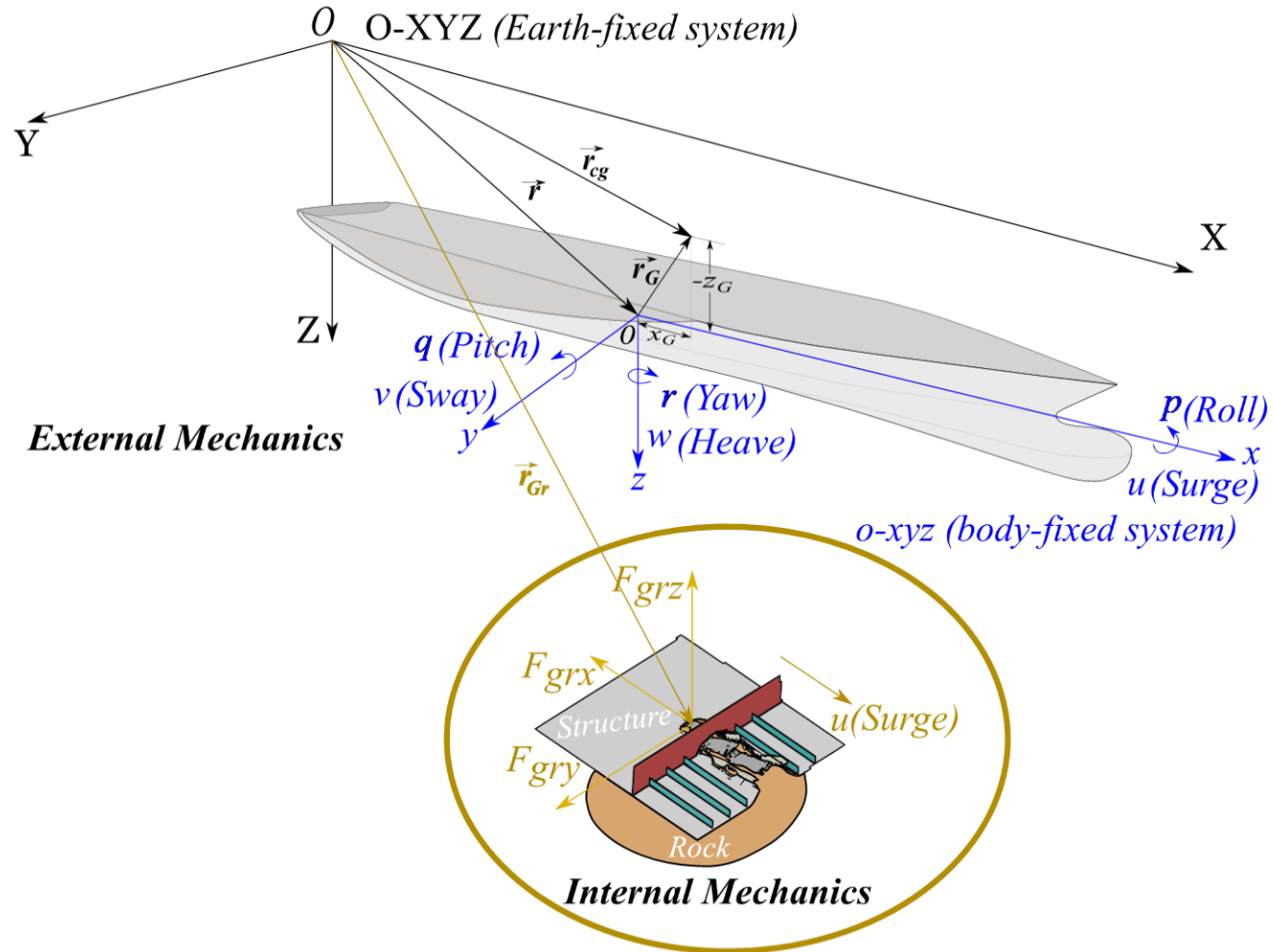
$\hat{O} = O-XYZ$ (Earth-fixed system)

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Content

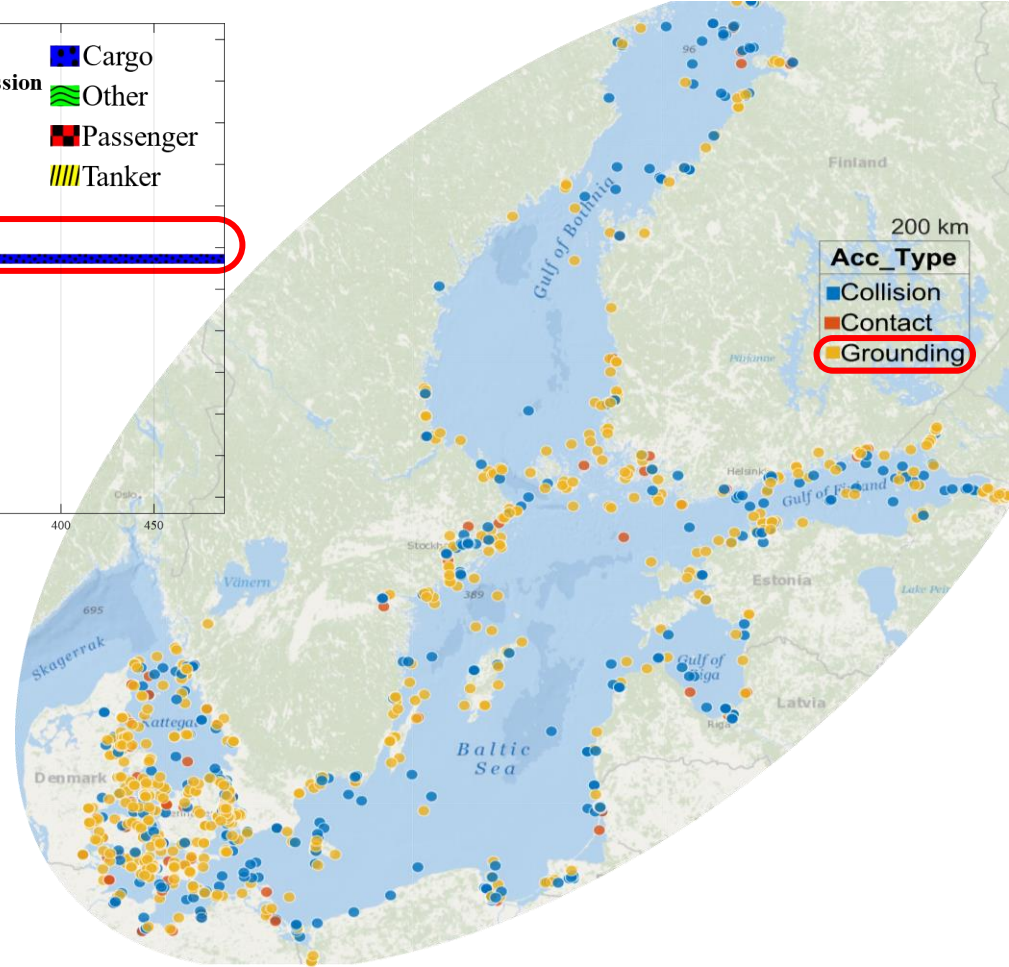
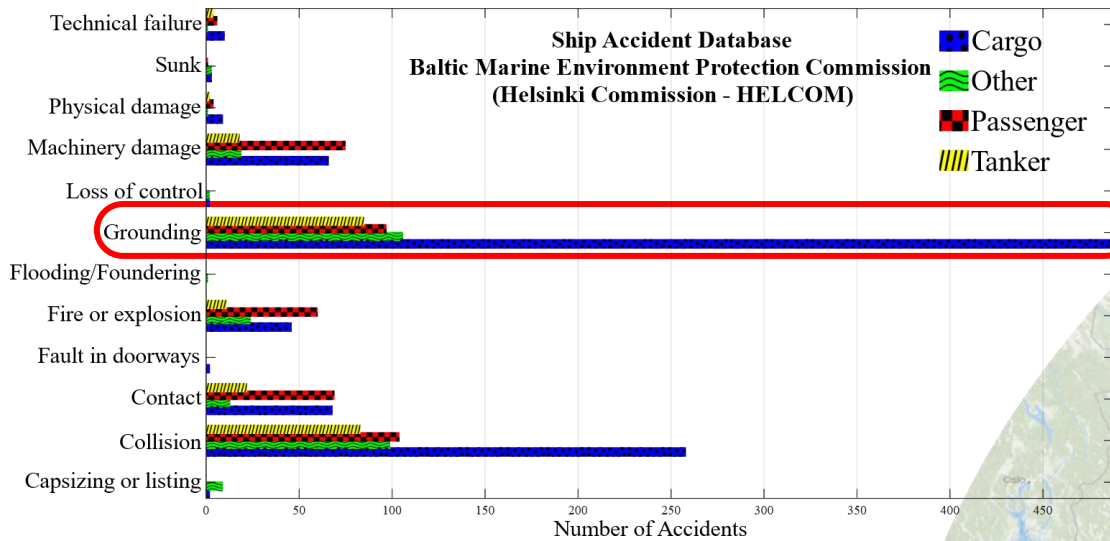
- ❖ Background
- ❖ Research challenges
- ❖ Aims
- ❖ Methodology
- ❖ Summary of results
- ❖ Conclusion
- ❖ Applications



Background

- ❖ Ship Grounding can cause
 - ❑ Contamination of marine habitats,
 - ❑ Disruption of traffic flow,
 - ❑ Serious ship damages, and
 - ❑ Loss of human life
- ❖ Grounding accidents pose significant safety risks
- ❖ Grounding accidents are frequent while navigating in confined and shallow waters.

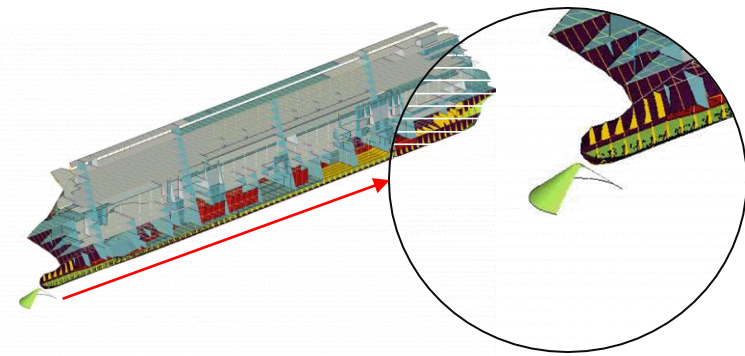




- ❖ Ship accidents tend to persist despite regulatory advancements.
- ❖ Risks associated with accidental events should be reduced to improve maritime safety
- ❖ To mitigate grounding risks and enhance ship safety rapid time-domain multiphysics models are required

Research challenges

- ❖ High computational time
- ❖ No evasive ship dynamics
- ❖ Most models are decoupled
- ❖ Existing models are not feasible for crashworthiness, evasive and probabilistic assessment.
- ❖ The damage extents dataset of passenger vessel grounding is limited



Aims

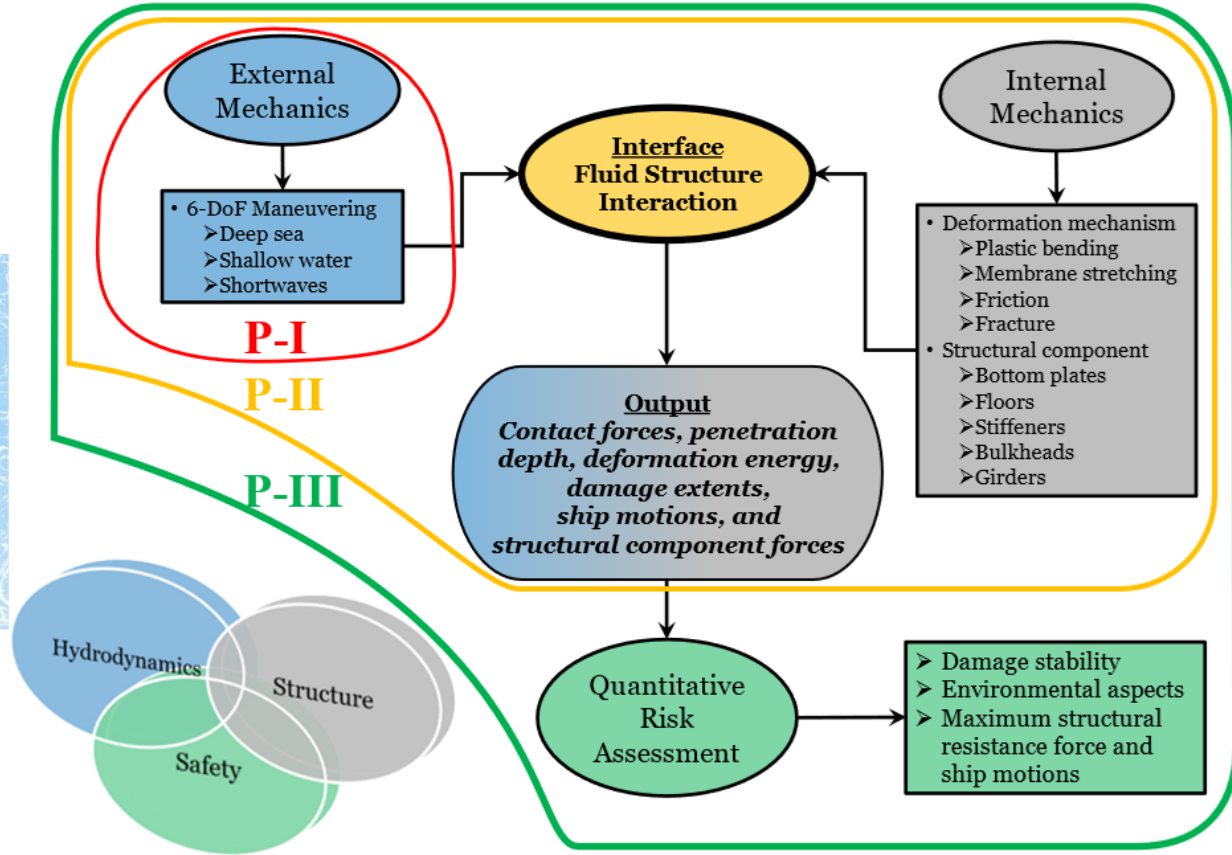
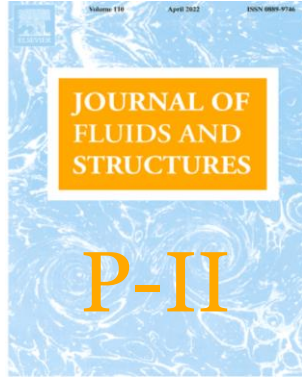
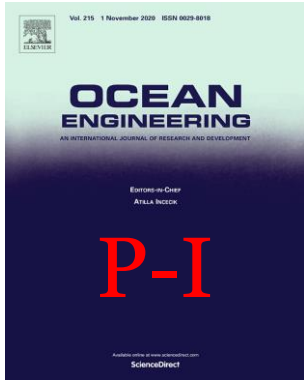
Develop a computationally efficient and accurate ship grounding assessment method that combines ship dynamics with structural deformation under realistic operational conditions. And populates the passenger vessel damage statistics.

Summary of ship grounding assessment methods

Authors	Internal Mechanics	External Mechanics										Vessel Types		Ship Model	Obstacle	Evaluation Presented		
Simonsen (1997)	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Matusiak and Varsta (2002)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Nguyen et al. (2011)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Hong and Amdahl (2012)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Abubakar and Dow (2013)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Heinvee and Tabri (2015)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Zeng et al. (2016)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Yu and Amdahl, (2016)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Yu et al. (2016)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Lee et al. (2017, 2013)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Song and Hu (2017)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Calle et al. (2017)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Prabowo et al. (2020)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Liu et al. (2021)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Brubak et al. (2021)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Kim et al. (2021, 2020)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Kim et al. (2022a)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Kim et al. (2022b)*		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█
Taimuri et al. (2022a, 2022b)		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█

Key features

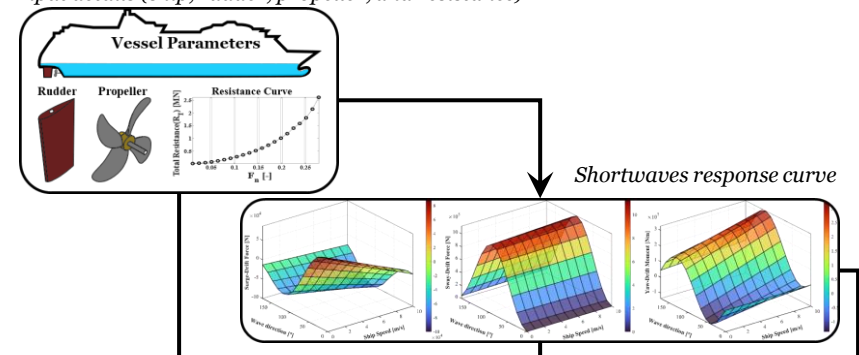
Methodology



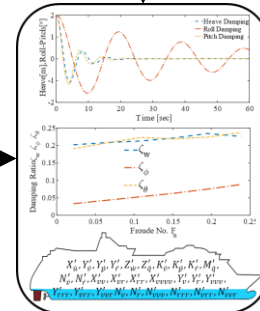
External Mechanics

- ✓ Mathematical modelling of **6-DoF Maneuvering model**
- ✓ Consideration of deep sea, **shallow sea**, calm water, **short waves**, wind and ocean currents
- ✓ Single and **twin-screw vessel**
- ✓ A **Reference technique** to account hydrodynamic derivatives of twin screw vessel.
- ✓ Modelling of out of the plane motions (**Heave, Roll and Pitch**)

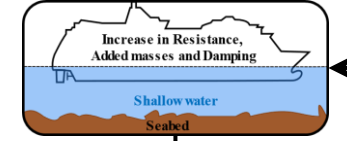
Input details (ship, rudder, propeller, and resistance)



Ship hydrodynamics



Shallow water effects

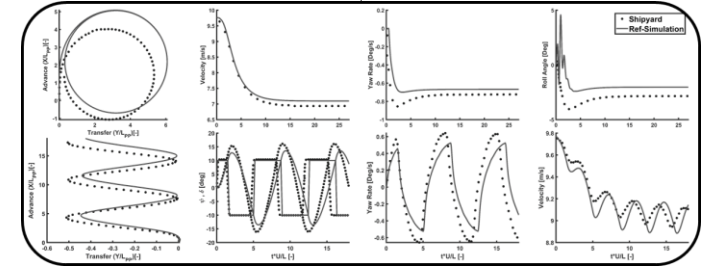


6-DOF Maneuvering Mathematical Model

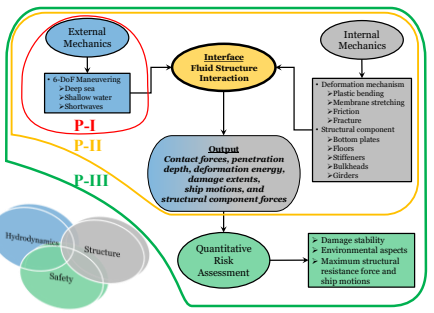
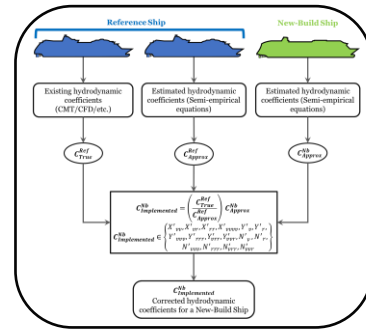
[Inertia] = [Coriolis & Centripetal] + [Restoring] + [Damping] + [Control] + [Environmental]

Runge-Kutta 4th Order Numerical Integration of the Equation of Motion

Results (Ship Response)

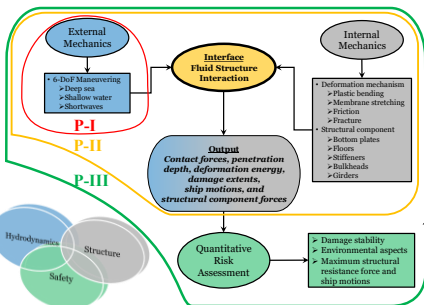
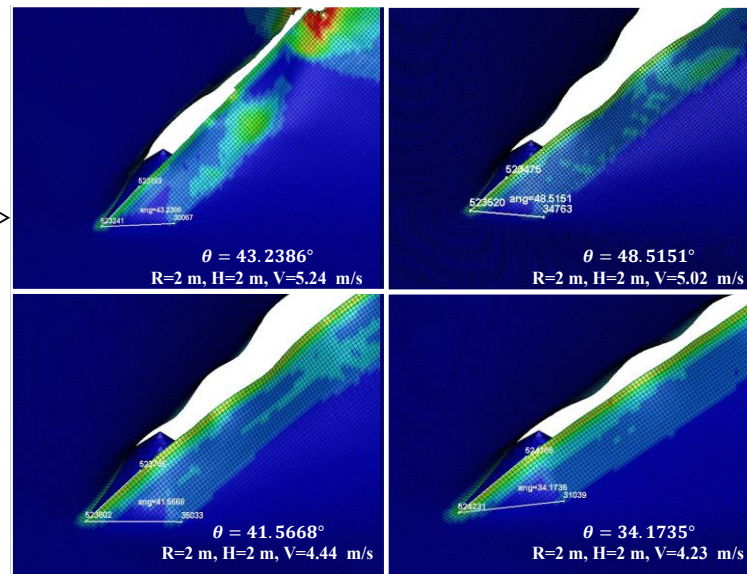
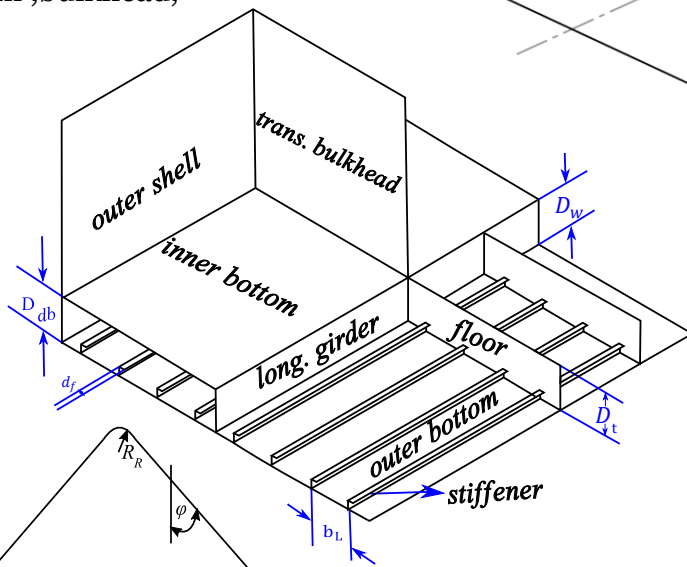
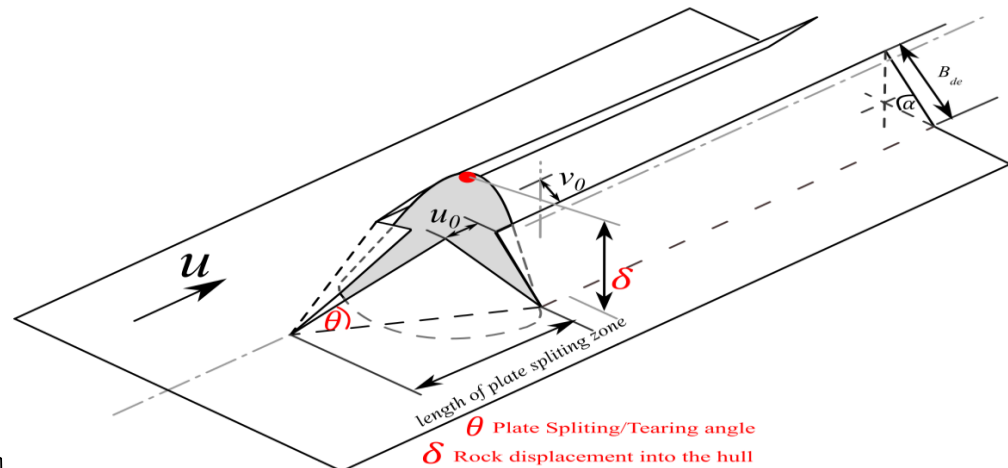


Reference technique



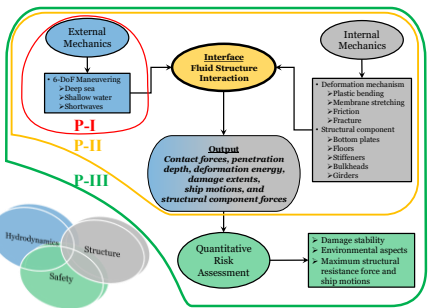
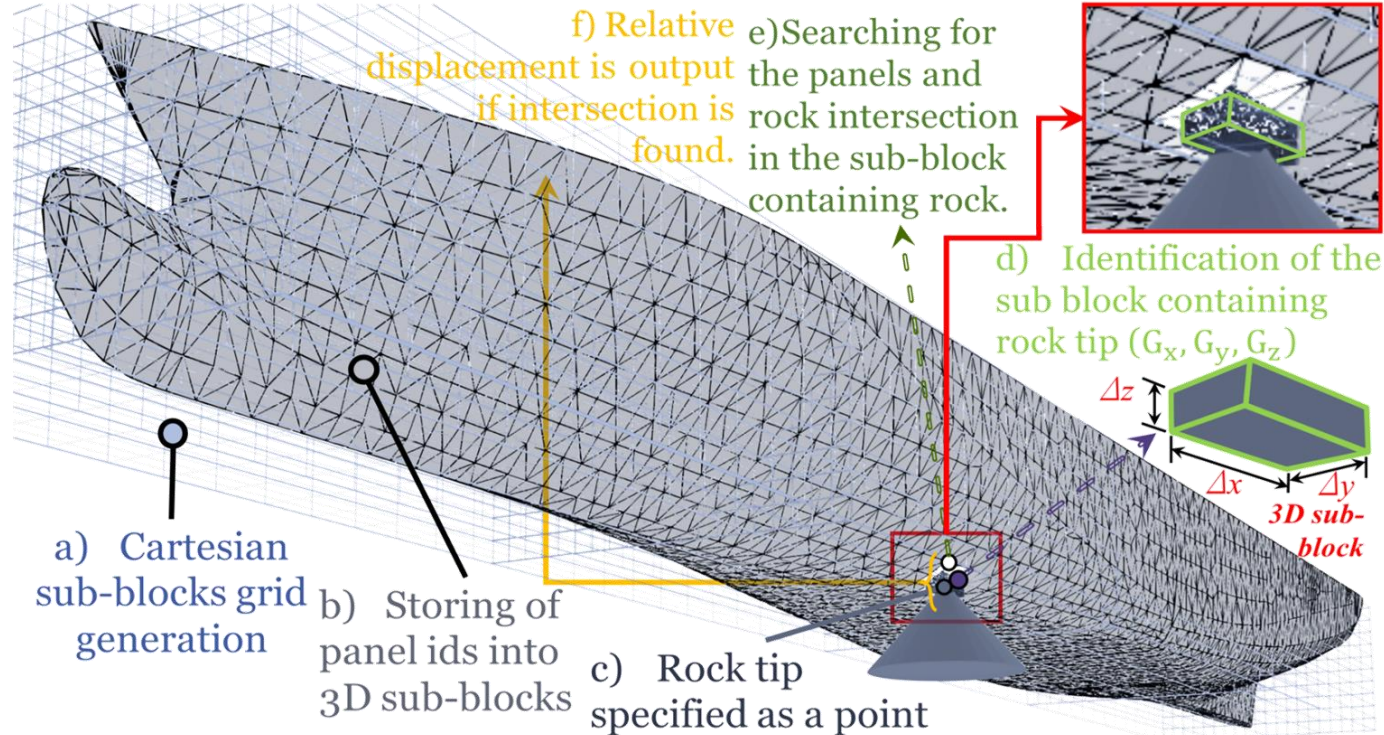
Internal Mechanics

- ✓ Motion dependent structural failure model (*Redefinition of plate tearing angle θ*)
- ✓ Consideration of general arrangement of bottom structure and major components (plate, beam, bulkhead, etc...)



Contact coupling (Interface)

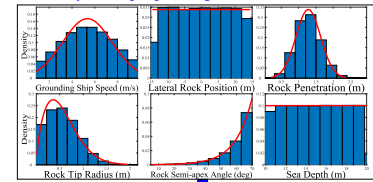
- ✓ Require hull panels, rock tip, ship location and motions.
- ✓ Hull panel stored in sub-block for *rapid search* of rock tip.
- ✓ Implementation of *ray-tracing algorithm* to identify penetration



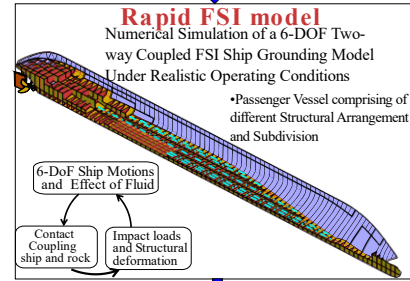
Probabilistic Damage Extent

- ✓ Use of the **rapid FSI model**
- ✓ Performed **Monte Carlo simulations** to generate the **ship operating parameters** and **conical rock profile**.
- ✓ In an event of grounding the method determines:
 - ❑ extents of actual damage,
 - ❑ the maximum resistance force of structure,
 - ❑ the maximum attained ship motions, and
 - ❑ Attained subdivision index

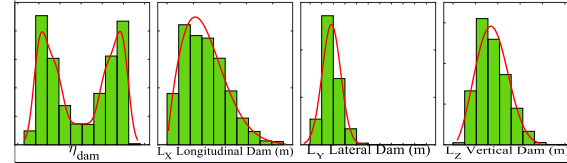
Probability of Ship Operating Condition Before Grounding



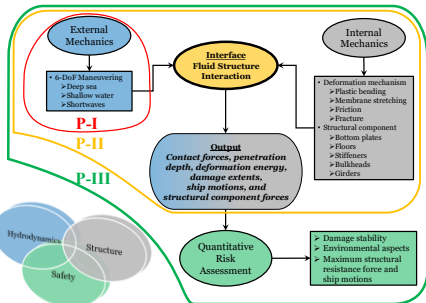
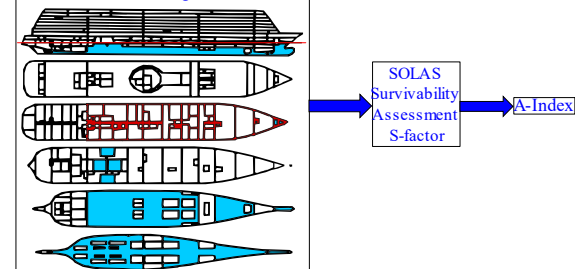
Monte Carlo Simulation



Generation of Damage Extent from Deterministic Coupled Maneuvering and structural deformation model



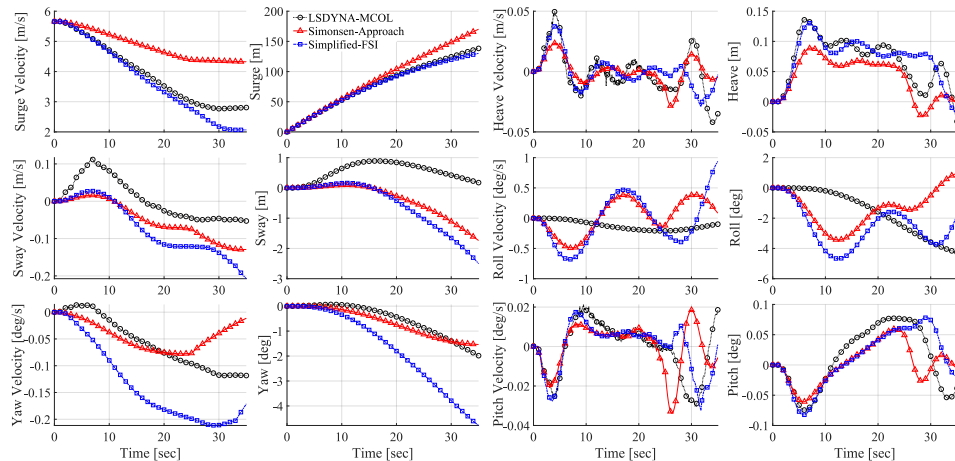
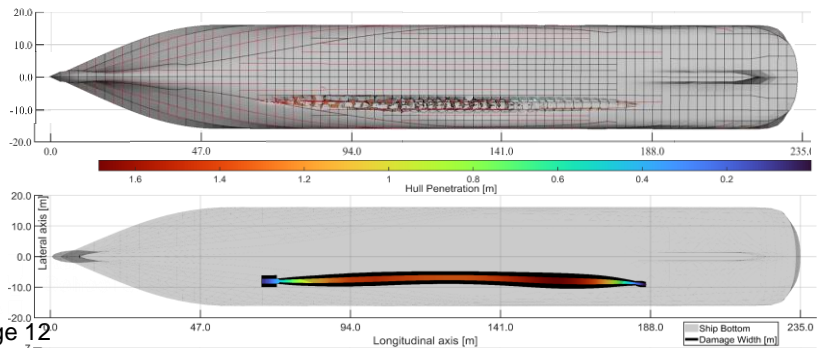
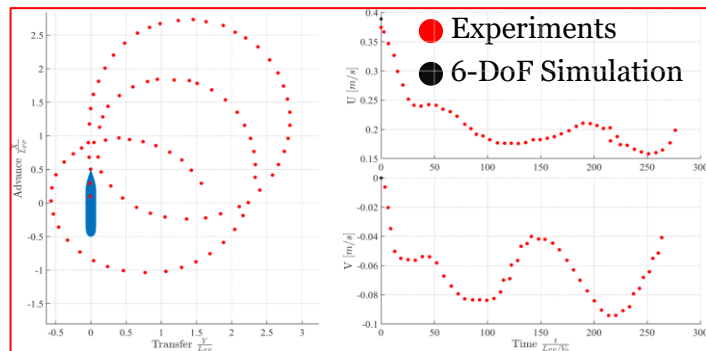
Classification of Damage rooms P-factor



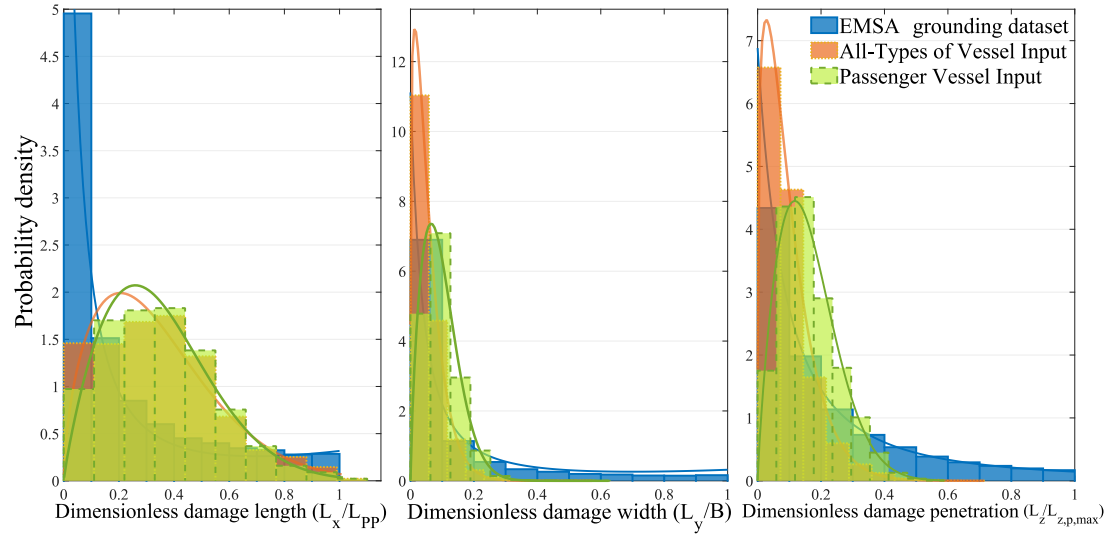
Results

- ✓ Reasonable estimates of trajectories and ship motions.
- ✓ CFD or Experiment hydrodynamic coefficient are more accurate.
- ✓ Reference technique is best choice for the initial estimation of TPTR vessel maneuvering.
- ✓ Under shortwaves conditions Sway velocities, are little overestimated.
- ✓ Ship motion dependent plate tearing angle outperforms the simplified technique of constant plate tearing angle
- ✓ LSDYNA-MCOL results matched reasonably well against rapid FSI model.
- ✓ Some **LIMITATIONS** observed in FSI model when simulating real ship topology:
 - ❑ Overestimation of vertical force near bulbous bow and curved regions
 - ❑ Underestimation of Lateral force when rock is fastened between two longitudinal girders.

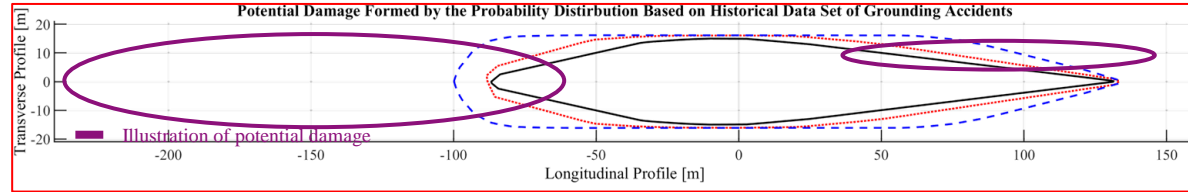
DTC Head waves maneuver



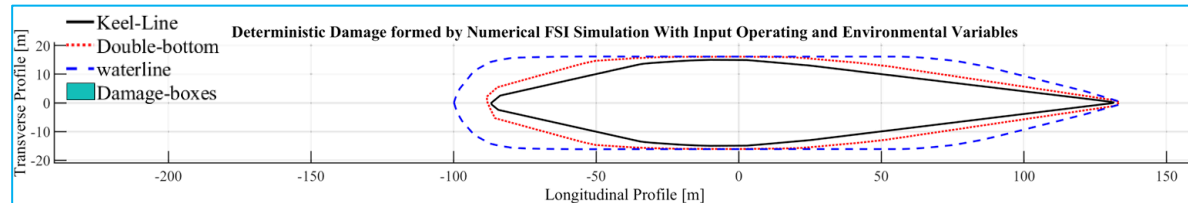
- ✓ Mean damage length output from the rapid FSI method is 55% larger than the historical database of EMSA
- ✓ Damage breadth and penetration from FSI model is 30% and 25% is lower, from FSI model.
- ✓ Little difference between deep and shallow water.
- ✓ Potential damage vs Actual damage
- ✓ Certain hull breaches outside ship domain.
- ✓ FSI model allows for a more realistic idealization of the influence of the effects of material properties and the operational conditions/environment.



Existing Distributions

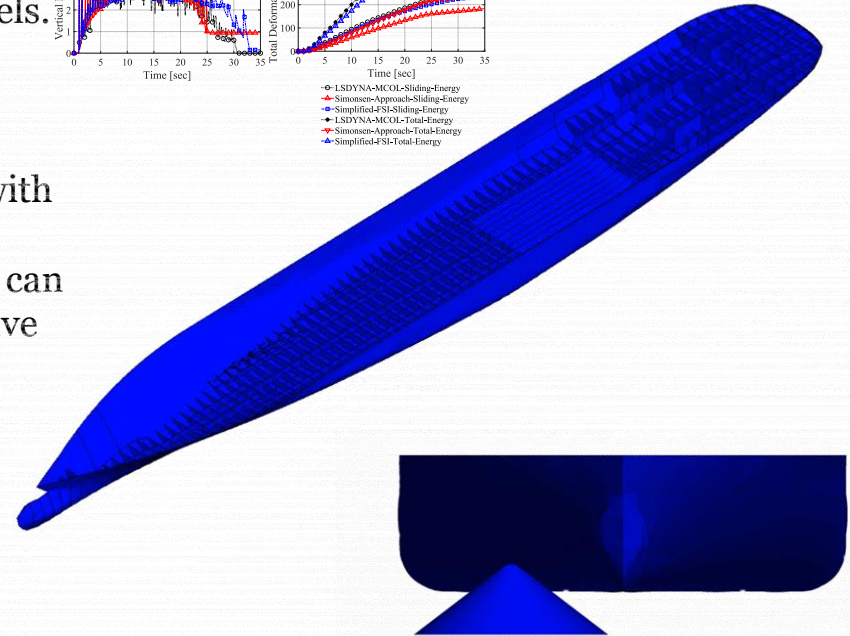
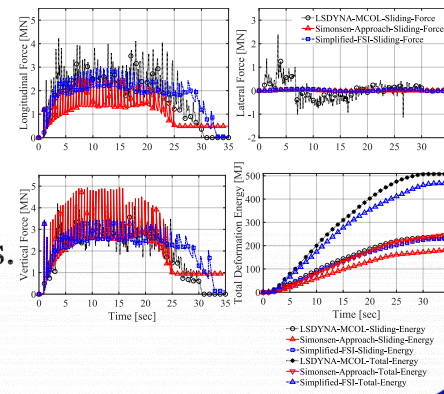


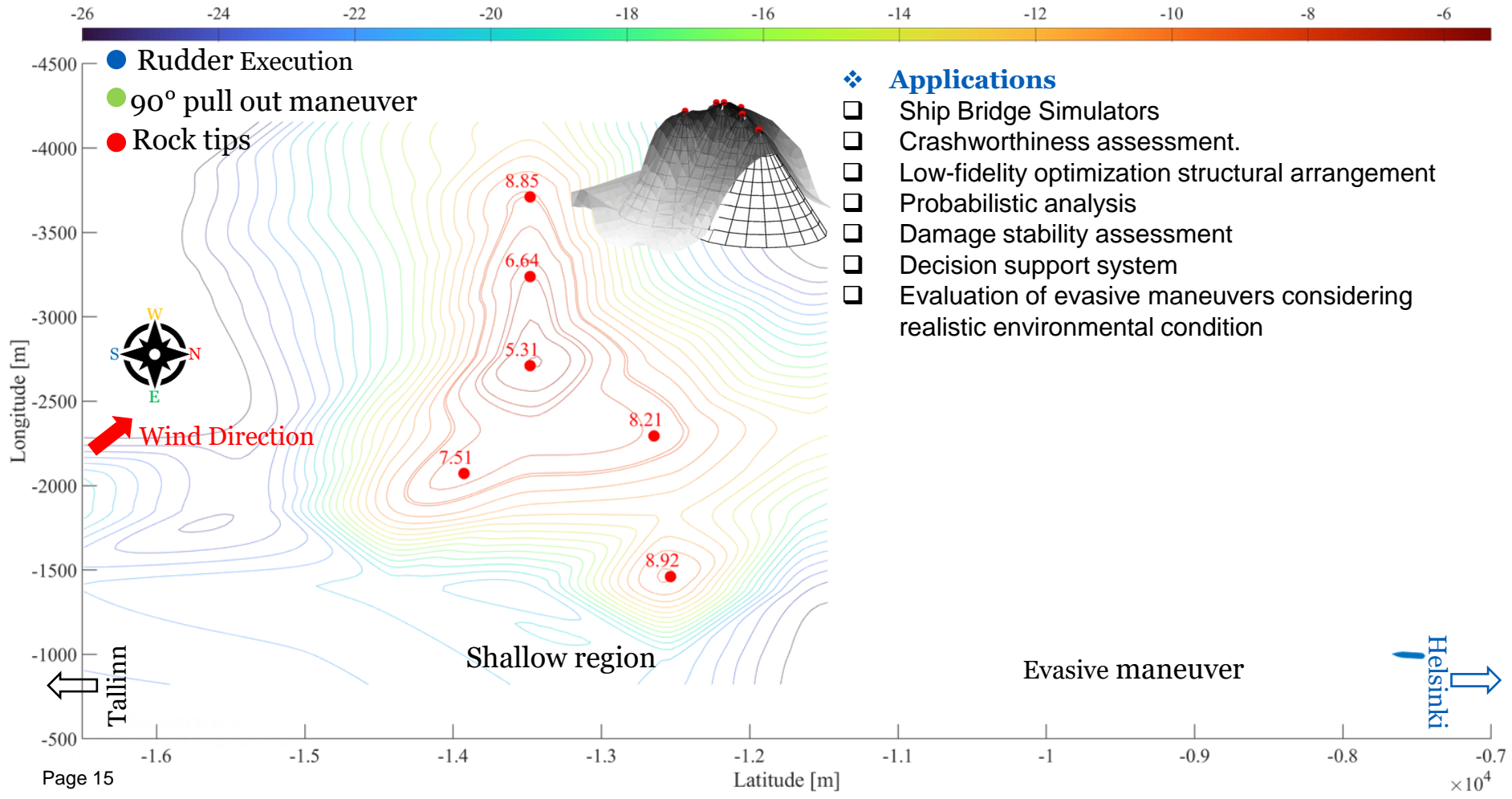
Rapid FSI-Model



Conclusion

- ❖ An improved model for ship grounding dynamics is introduced.
- ❖ Reference technique is feasible for the prediction of maneuvering trajectories of existing or new-build vessels.
- ❖ Well validated maneuvering under shallow water and shortwaves conditions.
- ❖ Motion-dependent plate split angle must be used.
- ❖ Prediction of damage extent and deformation energy with simplified FSI model are generally acceptable.
- ❖ Maneuvering dynamics and meteorological conditions can be considered for structural crashworthiness and evasive actions.
- ❖ Addition of ship restoring forces, damping and 6-DoF rigid body dynamics is essential





- Rudder Execution
- 90° pull out maneuver
- Rock tips

❖ **Applications**

- ☐ Ship Bridge Simulators
- ☐ Crashworthiness assessment.
- ☐ Low-fidelity optimization structural arrangement
- ☐ Probabilistic analysis
- ☐ Damage stability assessment
- ☐ Decision support system
- ☐ Evaluation of evasive maneuvers considering realistic environmental condition

A!

Aalto University
School of Engineering



Defense Date:
20th January 2023

Thank You !
Questions ?

ghalib.taimuri@aalto.fi