

The use of *CFD* in Hydroelastic Slamming

Marine Technology Gala

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Fluid-Solid Interaction in the Ocean

The mutual effects of water and solid on each other



Slamming



The water entering process of a solid object

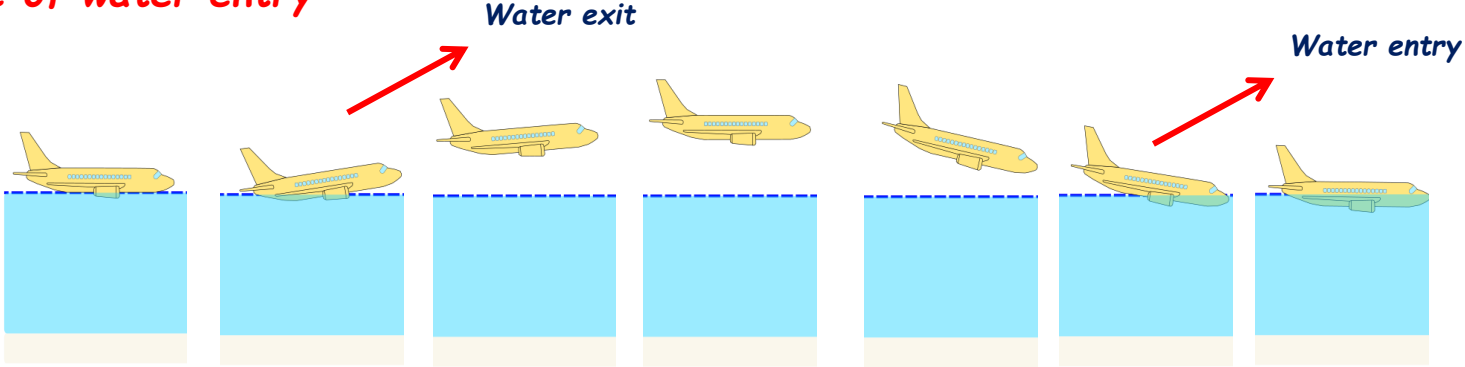
Large loads

Structural damages



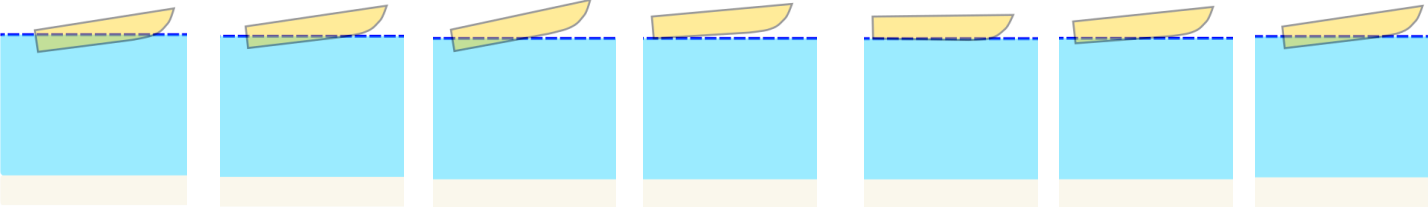
We want to predict the load and the resulting stresses!

Example of water entry

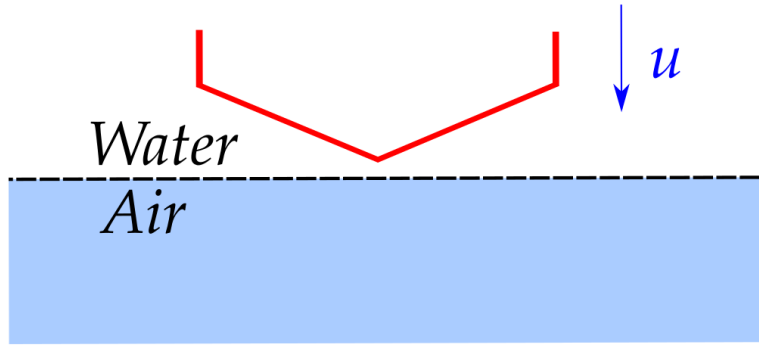


Water exit

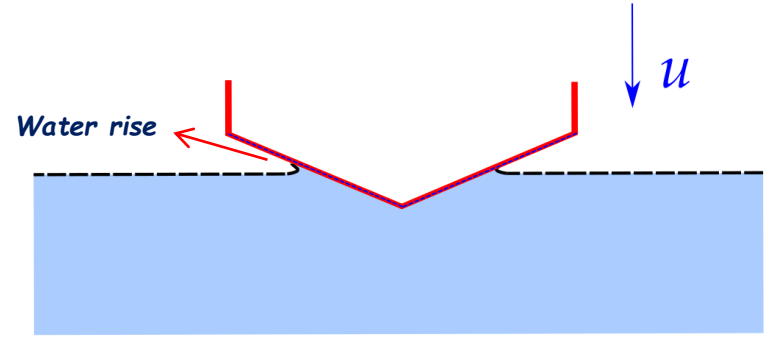
Water entry



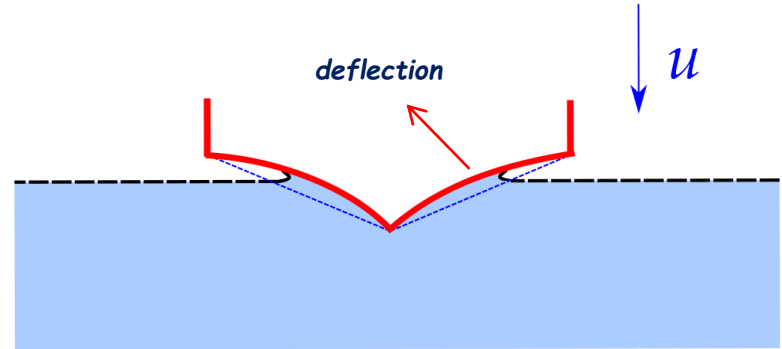
Hydroelastic water entry



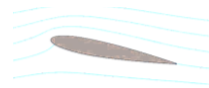
Rigid body



Elastic body



How to solve the problem?



1) The classical approach



Fluid

Zero-viscosity assumption \longrightarrow Laplace equation

Boundary Integration Methods or Analytical solutions

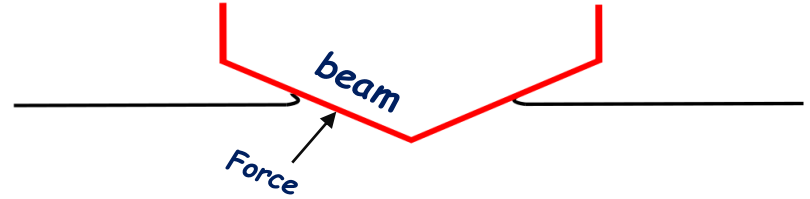
Fluid-solid interaction is treated by matching BCs



Solid

Plate/beam theories

FEA and modal analysis



Breaking process, and high-order nonlinear phenomena may not be well captured

Fluid domain

How to solve the problem?

2) Viscous approach



Fluid

Viscous fluid \longrightarrow NS equations

CFD or SPH methods

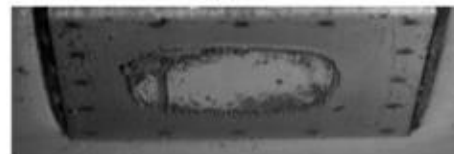
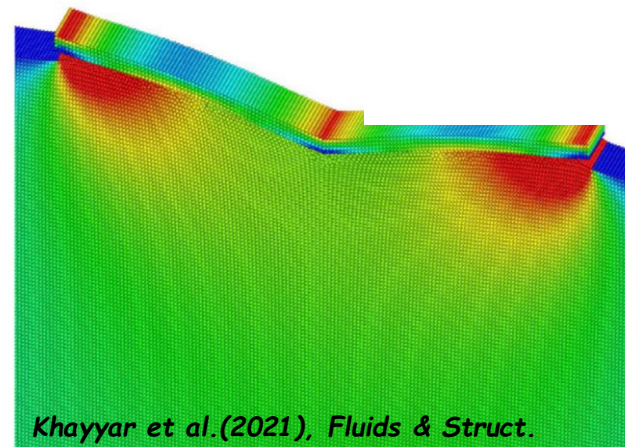
Fluid-solid interaction is treated by setting



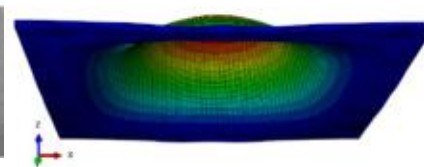
Solid

Plate/beam theories or continuum medium

FEA, Meshless, FVM



Yan et al.(2022), Marine Struct.



What happens if we use FVM to solve both problems

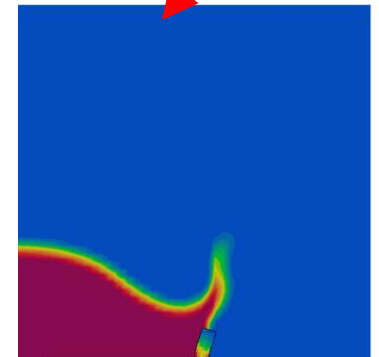
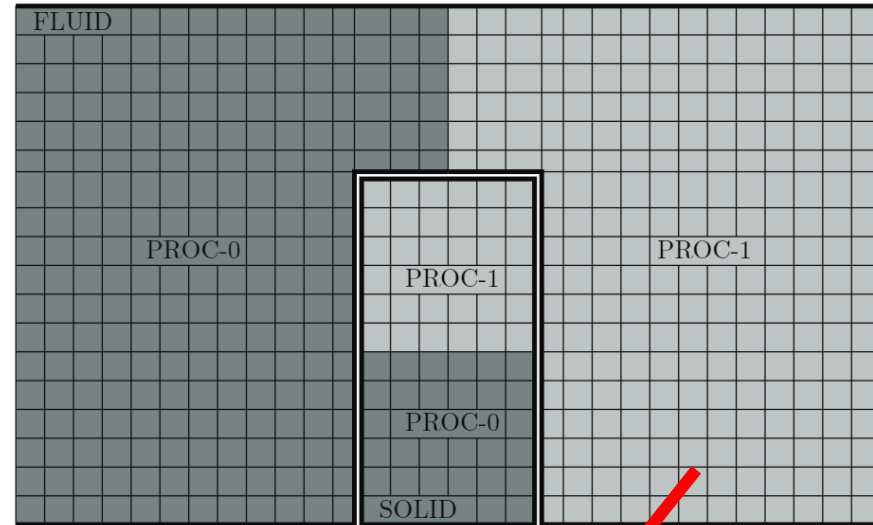
Cardiff (2022), 2nd CCP-WSI Hackathon

Same decomposition method

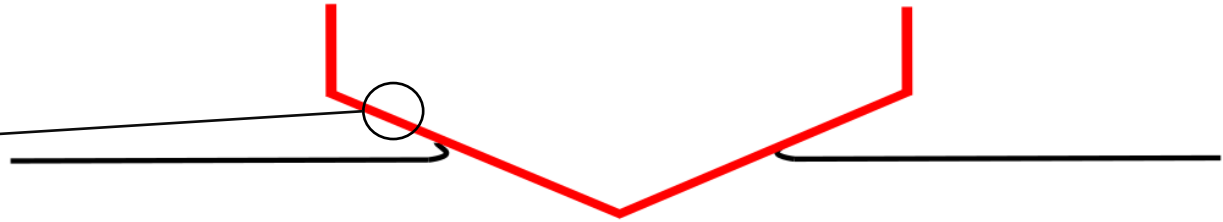
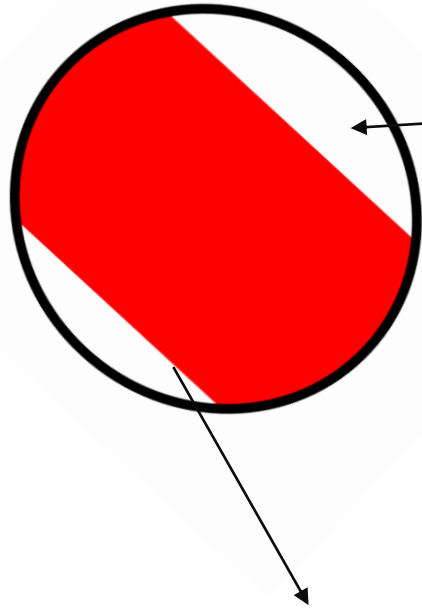
Faster simulations

Better matching on FS interface

Large strains can be monitored



Governing equations



$$\nabla \cdot \mathbf{v} = 0$$

$$\int \rho_s \frac{\partial^2 \mathbf{u}}{\partial t^2} d\Omega_S = \oint_{\Gamma_S} \mathbf{n} \cdot \boldsymbol{\sigma} d\Gamma_S + \int_{\Omega_S} \rho_S b d\Omega_S (\nabla \mathbf{v} + \nabla \mathbf{v}^T)$$

$$\partial_t \gamma + \nabla \cdot \gamma \mathbf{v} + \nabla \cdot [\mathbf{v}_\xi \gamma (1 - \gamma)] = 0.$$

NS equations and conservation of VoF

Conservation of displacement rate

$$n_{FS} \cdot \boldsymbol{\sigma}^+(x; t) = n_{FS} \cdot \boldsymbol{\sigma}^-(x; t) \quad \mathbf{u}(x; t)^+ = \mathbf{u}(x; t)^-$$

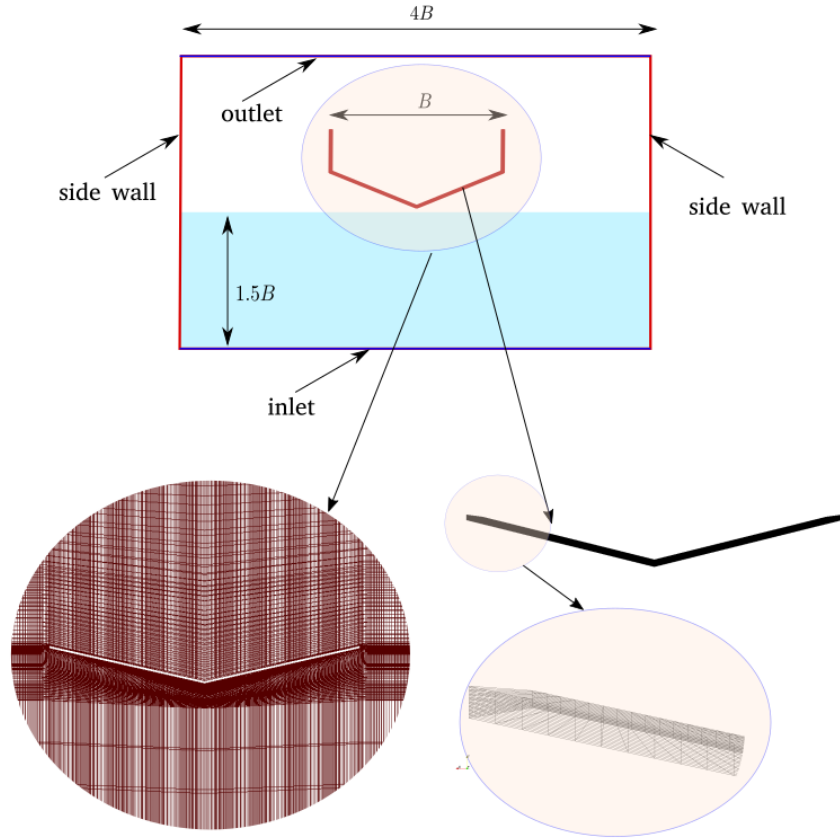
$$\mathbf{v}(x; t)^+ = \mathbf{v}(x; t)^-$$

Boundary conditions of FS interface

How do we set it up?

Fluid and solid domains are generated

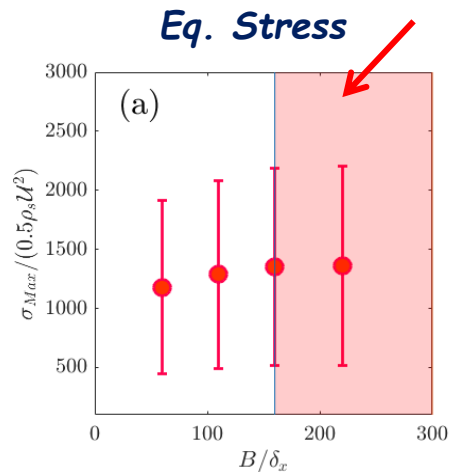
Fluid and solid domains are meshed



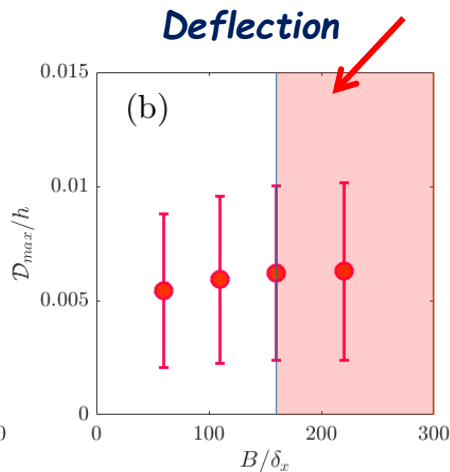
Mesh Study

● Average value

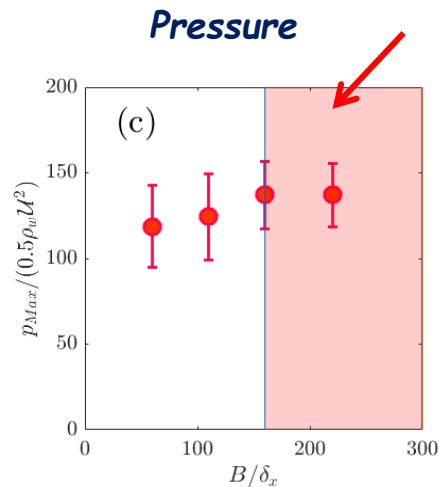
I Standard variation



Cell length



Cell length

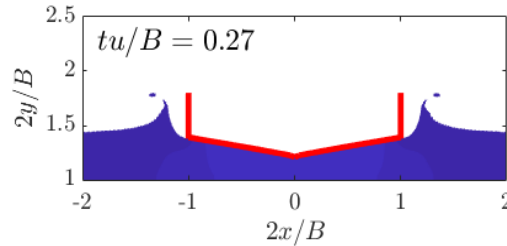
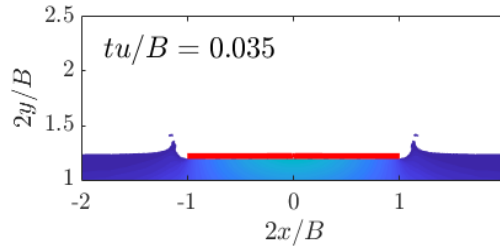
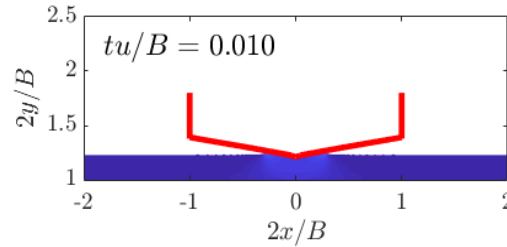
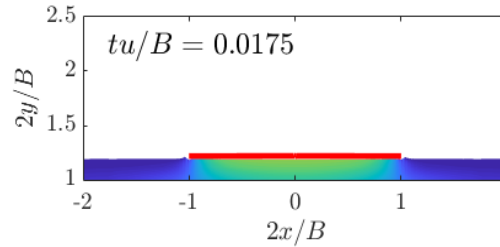


Cell length



Snapshots of the pressure field

An elastic flat plate versus an elastic wedge

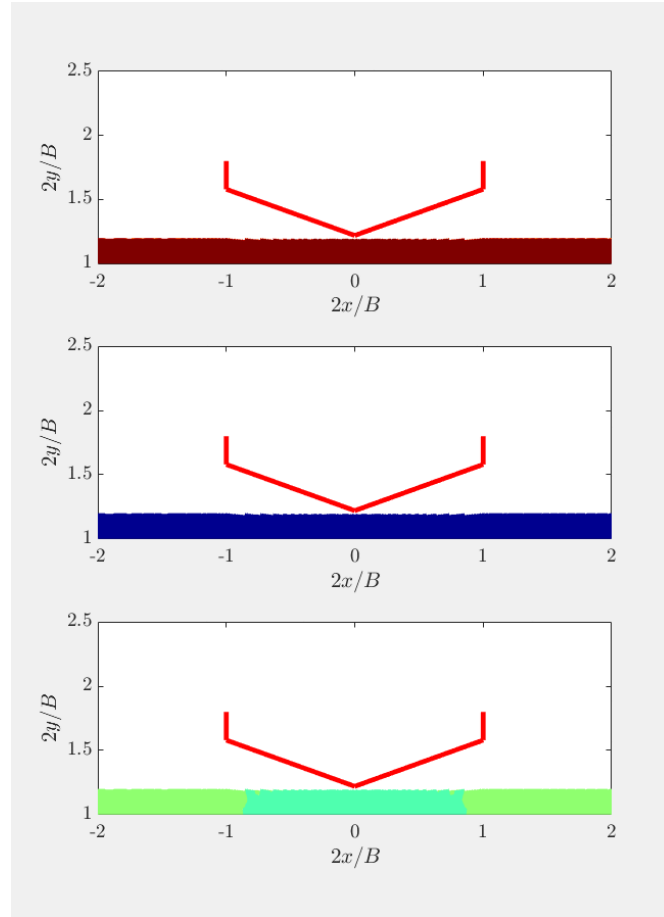


A demo of simulations

Water

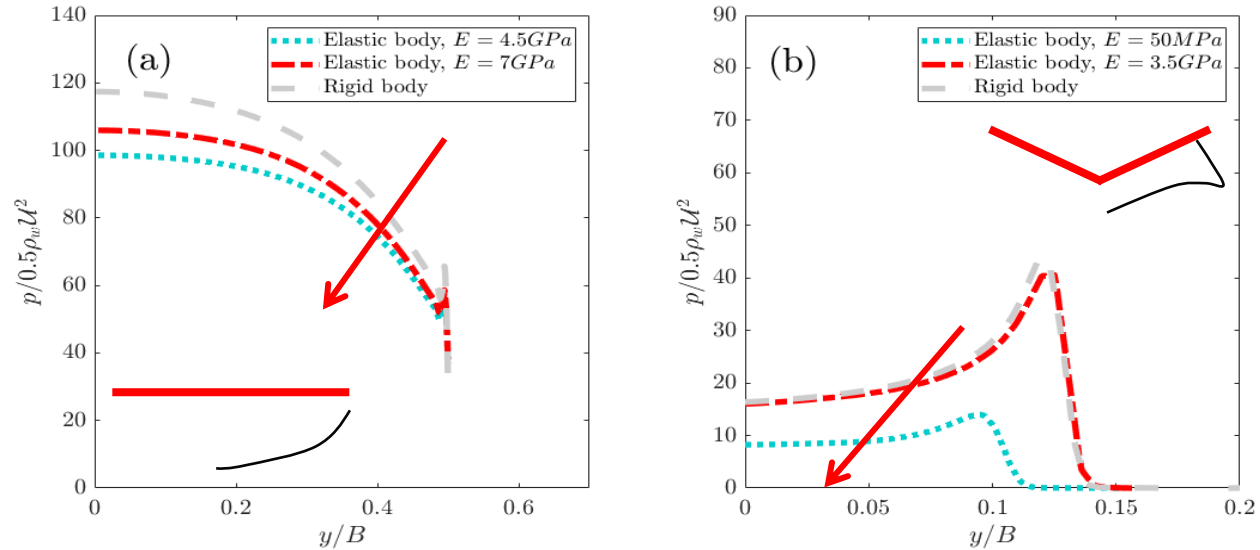
Pressure

Velocity



Does elasticity affect the pressure?

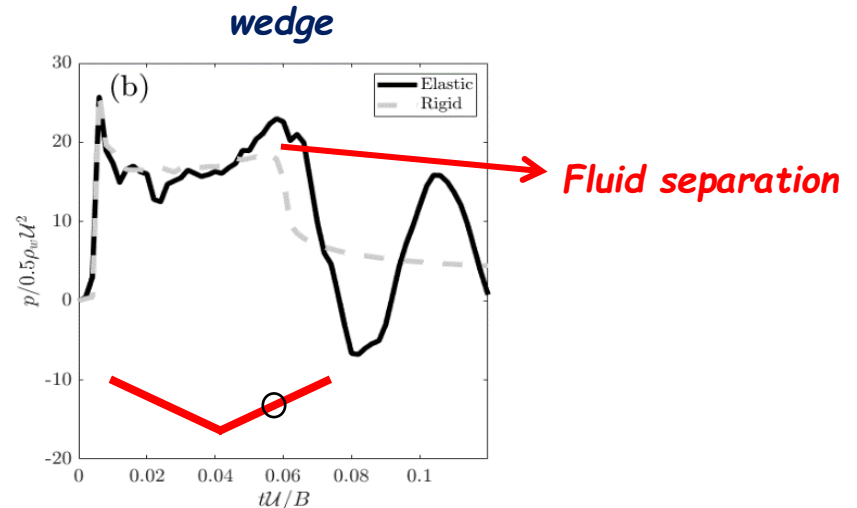
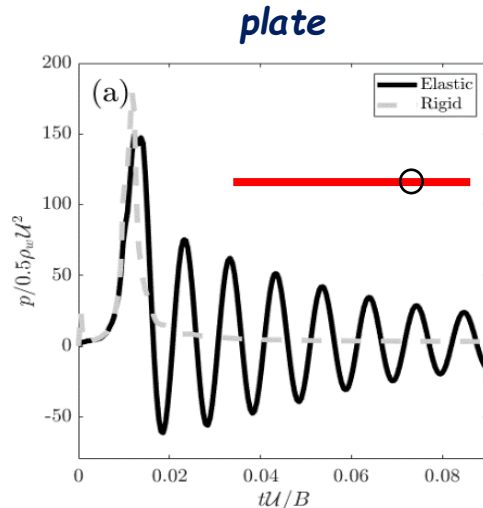
Pressure along the wall of plate or wedge



The pressure is reduced by the decrease in elastic modulus

Does elasticity affect the pressure?

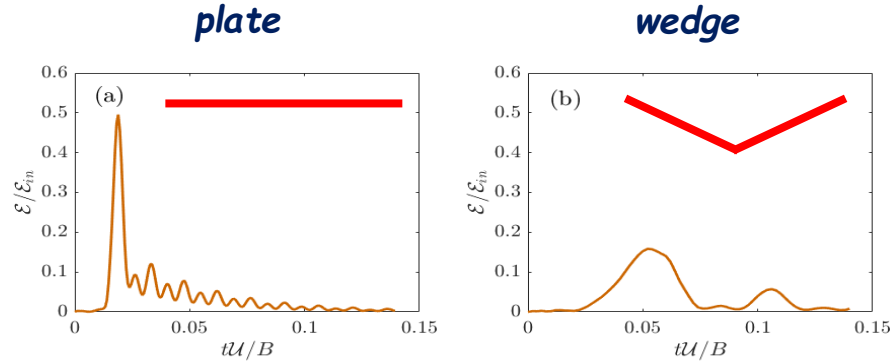
Time history of pressure at a point



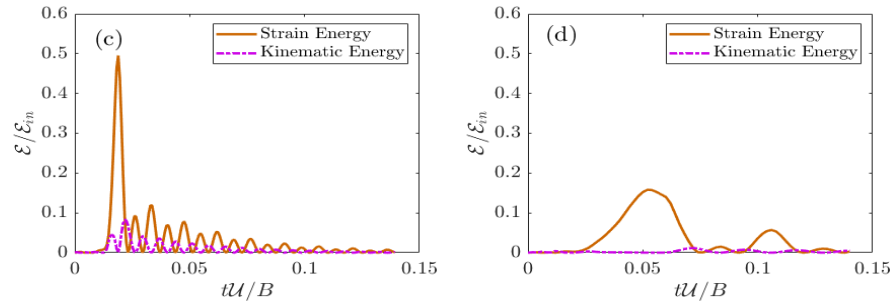
The harmonic behavior observed is due to elastic motion of the solid body

Energy arising in the solid body

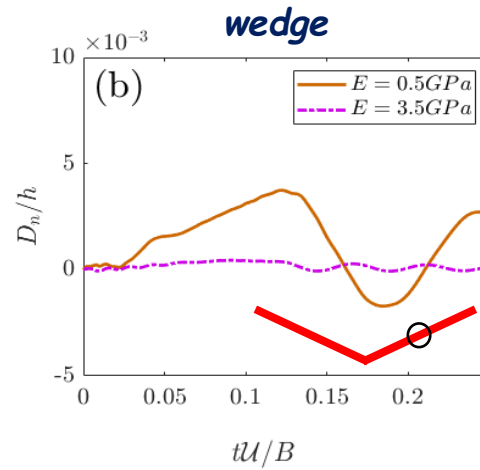
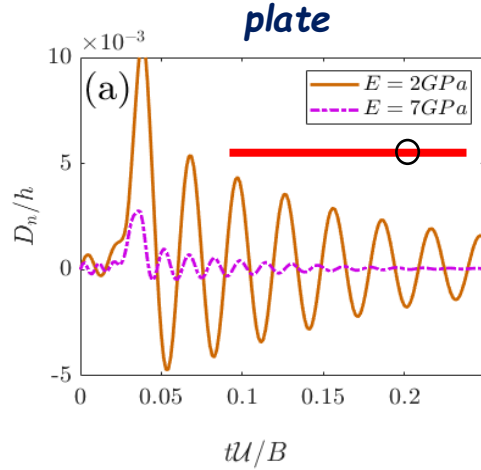
Total energy



Energy components



Displacement at the quarter point



Conclusions

- *FVM can be used for solving slamming problem, which is very fast!*
- *Flexible motion reduces the impact pressure.*
- *Strain energy is much larger than the kinematic energy.*

Thank you!

