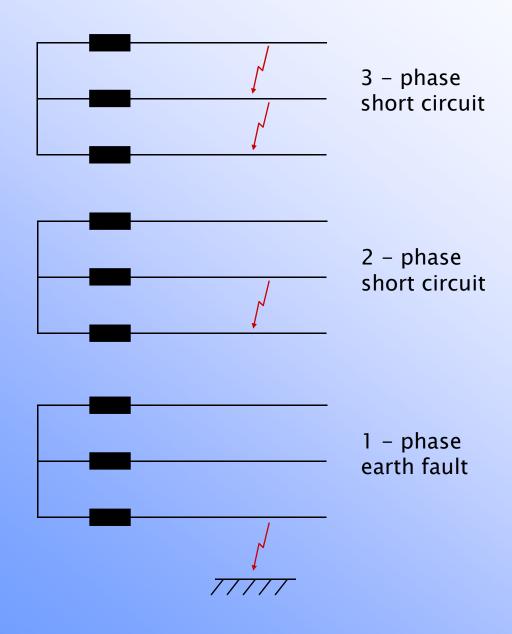
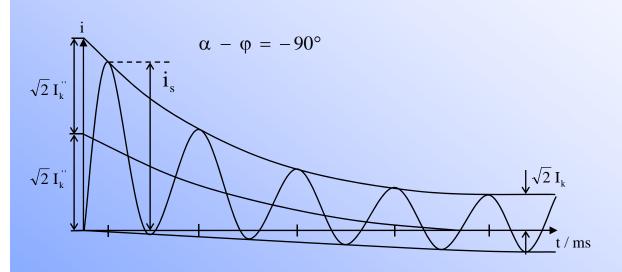
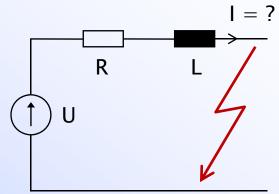
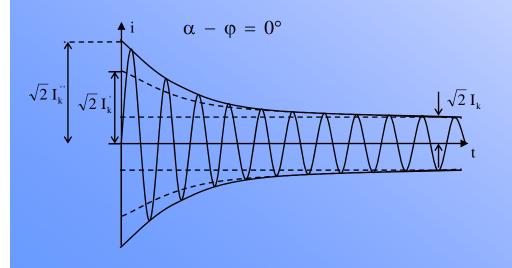
# Power system faults



### The nature of short circuit current







$$X_{d}^{"} < X_{d}^{"} < X_{d}$$

$$\Rightarrow I_{k}^{"} > I_{k}^{"} > I_{k}$$

### The nature of short circuit current

$$u = \sqrt{2} U \sin(\omega t + \alpha)$$

α = switching time after the voltage zero crossing,the time t is computed since this moment

$$Ri + L\frac{di}{dt} = \sqrt{2} U \sin(\omega t + \alpha)$$

$$\Rightarrow \frac{\sqrt{2} U}{Z} \left[ \sin(\omega t + \alpha - \phi) - e^{-\frac{R}{L}t} \sin(\alpha - \phi) \right]$$

$$Z = \sqrt{R^2 + (\omega L)^2} \quad :: \quad \tan \phi = \frac{\omega L}{R}$$

Peak short circuit current:

$$I_S = H\sqrt{2} I_K^{"}$$

$$H = f\left(\frac{R}{X}\right) = \text{attenuation factor}$$

$$I_K^{"} = \text{subtransient short circuit current}$$

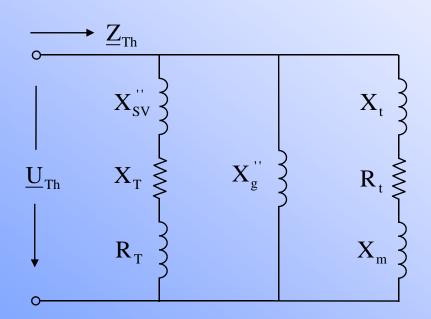
At transmission voltages:

$$H \approx 1.8 \quad \left(\frac{R}{X} \approx 0.07\right)$$
  
 $\Rightarrow I_S = 2.5 I_K$ 

Note: Ik" is rms value Is max instantaneous value

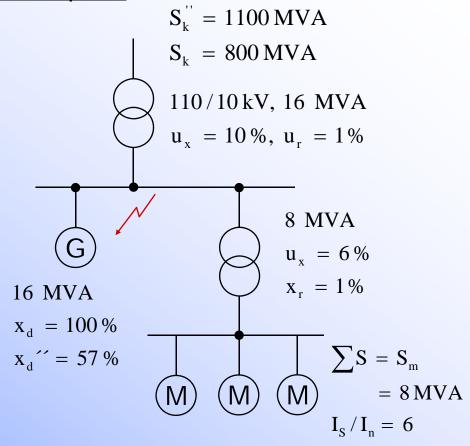
### Example: 3-phase short circuit in a power plant

#### One line diagram:



### Subtransient current $I_k$ " = ?

Computation at 10 kV voltage level



1. Power transmission grid:  $\underline{z}_{v}$ 

$$\underline{z}_{v} = R_{T} + j(X_{T} + X_{SV}'')$$

$$= u_{r} \frac{U^{2}}{S_{T}} + j \left( u_{x} \frac{U^{2}}{S_{T}} + \frac{U^{2}}{S_{k}''} \right)$$

$$= 0.0625 + j0.716 \Omega = 0.719 \angle 85^{\circ} \Omega$$

2. Generator influence  $\underline{z}_{g}$ 

$$\underline{\mathbf{z}}_{g} = j \mathbf{x}_{d}^{"} \frac{\mathbf{U}^{2}}{S_{k}} = j0,57 \frac{10^{2}}{16} = 3,563 \angle 90^{\circ} \Omega$$

#### Example: 3-phase short circuit

# 3. The motors $\underline{z}_{m}$ $\underline{z}_{m} = R_{t} + j(x_{t} + x_{m})$ $= u_{r} \frac{U^{2}}{S_{t}} + j \left( u_{x} \frac{U^{2}}{S_{t}} + \frac{U^{2}}{I_{s}/I_{n} \cdot S_{m}} \right)$ $= 0.125 + j 2.833 \Omega = 2.836 \angle 87.5^{\circ} \Omega$

4. The Thevenin impedance

$$\underline{z}_{Th} = \left(\frac{1}{\underline{z}_{v}} + \frac{1}{\underline{z}_{g}} + \frac{1}{\underline{z}_{m}}\right)^{-1} = 0,494 \angle 86,1^{\circ}\Omega$$

$$\underline{u}_{Th} = \frac{10}{\sqrt{3}} \angle 0^{\circ} kV$$

$$\Rightarrow \underline{I}_{k}'' = \frac{\underline{u}_{Th}}{\underline{z}_{Th}} = \underline{11,69} \angle = -86,1^{\circ} kA$$

### Example: 3-phase short circuit

A simple way : R << x, ol.  $R \sim 0$ 

⇒ computation using powers S

Subtransient short circuit power in busbar :

$$S_{k}'' = S_{k,sv}'' + S_{k,g}'' + S_{k,m}''$$

1. Transmission grid:

$$S_{k,sv}^{"} = \frac{S_k " \cdot S_{kT}}{S_k " + S_{kT}} ; S_{kT} = \frac{1}{u_x} \cdot S = 160 \text{ MVA}$$
$$= \frac{1100 \cdot 160}{1100 + 160} \text{ MVA} = 139,7 \text{ MVA}$$

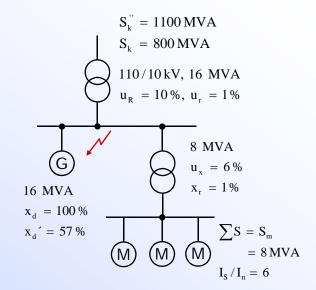
2. Generator : 
$$S_{k,g}'' = \frac{1}{X_d''} S_g = 28,1 \text{ MVA}$$

3. Motors:

$$S_{k,m}^{"} = \frac{S_{kT} \cdot S_{km}}{S_{kT} + S_{km}} ; S_{km} = I_{s} / I_{n} \cdot S_{m} = 48 \text{ MVA}$$

$$S_{k,t} = \frac{1}{u_{x}} S = \frac{8}{0,06} = 133,3 \text{ MVA}$$

$$= \frac{133,3 \cdot 48}{133,3 + 48} \text{ MVA} = 35,3 \text{ MVA}$$



### Example: 3-phase short circuit

$$S_{k}'' = S_{k,sv}'' + S_{k,g}'' + S_{k,m}''$$
  
= 139,7 + 28,1 + 35,3 MVA  
= 203,1 MVA  
 $S_{k}'' = \sqrt{3} U I_{k}''$   
 $\Rightarrow I_{k}'' = \frac{S_{k}''}{\sqrt{3} U} = \underline{11,73 \text{ kA}}$ 

Steady state  $I_k$ ? (motors do not affect)

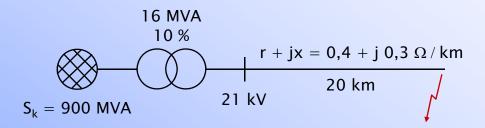
$$S_{k} = S_{k,sv} + S_{kg}$$

$$= \frac{S_{k} \cdot S_{kT}}{S_{k} + S_{kT}} + \frac{1}{X_{d}} S_{g}$$

$$= \frac{800 \cdot 160}{800 + 160} + \frac{1}{1,0} \cdot 16 \text{ MVA} = 149,3 \text{ MVA}$$

$$\Rightarrow I_{k} = \frac{S_{k}}{\sqrt{3}U} = 8,62 \text{ kA}$$

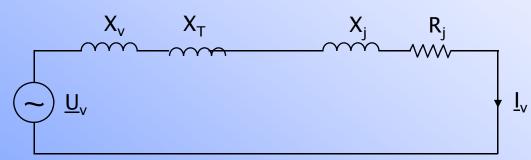
### Example: MV-distribution line & 3-ph vs. 2-ph faults



Xv&Xt grid&transformer reactance Xj&Rj line reactance&resistance

$$\begin{array}{c|c} z_{j} = R_{j} + jX_{j} = 8 + j6\Omega \\ \hline Z_{j} = R_{j} + jX_{j} = 8 + j6\Omega \\ \hline X_{T} = u_{x} \frac{21^{2}}{16}\Omega = 2,76\Omega \\ \hline X_{v} = \frac{U^{2}}{S} = \frac{21^{2}}{900}\Omega = 0,49\Omega \end{array}$$

### 3-phase fault current

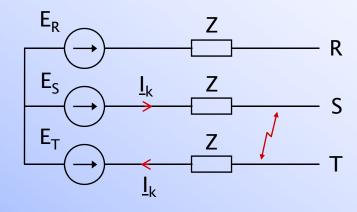


$$I_{k} = \frac{\underline{U}_{v}}{\underline{z}} = \frac{\underline{U}_{v}}{R_{j} + j(x_{v} + x_{T} + x_{j})} ; U_{v} = \frac{U_{p}}{\sqrt{3}} = \frac{21}{\sqrt{3}}$$

$$= \frac{21}{\sqrt{3} \cdot 12,23 \angle 49^{\circ}} kA$$

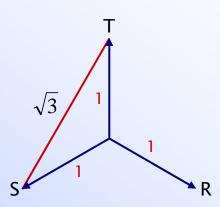
$$= \underline{0,99} \angle -49^{\circ} kA$$

### 2-phase fault current



$$\begin{cases} \underline{\mathbf{U}}_{\mathrm{Th}} = \underline{\mathbf{E}}_{\mathrm{S}} - \underline{\mathbf{E}}_{\mathrm{T}} \\ \underline{\mathbf{Z}}_{\mathrm{Th}} = 2\,\underline{\mathbf{Z}} \end{cases}$$

$$\underline{I}_{k} = \frac{\underline{E}_{S} - \underline{E}_{T}}{2\underline{Z}} = \frac{\sqrt{3} \, \underline{E}_{R} \angle -90^{\circ}}{2\underline{Z}}$$



With the numbers:

$$\underline{I}_{k} = \frac{\sqrt{3}}{2} \frac{E_{R}}{Z} = \frac{\sqrt{3}}{2} \cdot 0.99 \,\text{kA} \, (=0.86 \,\text{kA})$$

$$\Rightarrow$$

$$I_{k2v} = \frac{\sqrt{3}}{2} \cdot I_{k3v}$$
(holds, when  $\underline{Z}_1 = \underline{Z}_2$ )

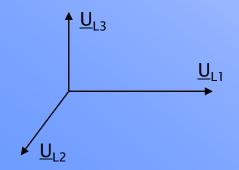
# Symmetrical components

The relation between phase quantities and symmetrical components:

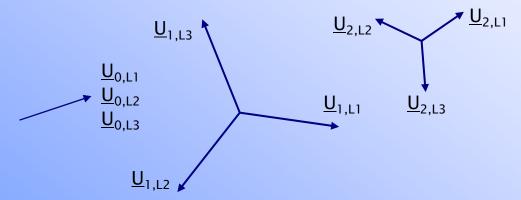
$$\begin{bmatrix} \underline{\mathbf{U}}_{L1} \\ \underline{\mathbf{U}}_{L2} \\ \underline{\mathbf{U}}_{L3} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & \underline{\mathbf{a}}^2 & \underline{\mathbf{a}} \\ 1 & \underline{\mathbf{a}} & \underline{\mathbf{a}}^2 \end{bmatrix} \begin{bmatrix} \underline{\mathbf{U}}_0 \\ \underline{\mathbf{U}}_1 \\ \underline{\mathbf{U}}_2 \end{bmatrix}$$

The left hand vector includes the phase voltages, the right hand vector zero-, positive- and negative sequence voltages. The transformation matrix is defined using the phase shift operator  $\underline{a} = 1 \angle 120^{\circ}$ . The inverse transformation is:

$$\begin{bmatrix} \underline{\mathbf{U}}_0 \\ \underline{\mathbf{U}}_1 \\ \underline{\mathbf{U}}_2 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & \underline{\mathbf{a}} & \underline{\mathbf{a}}^2 \\ 1 & \underline{\mathbf{a}}^2 & \underline{\mathbf{a}} \end{bmatrix} \begin{bmatrix} \underline{\mathbf{U}}_{L1} \\ \underline{\mathbf{U}}_{L2} \\ \underline{\mathbf{U}}_{L3} \end{bmatrix}$$



An example case of phase voltages



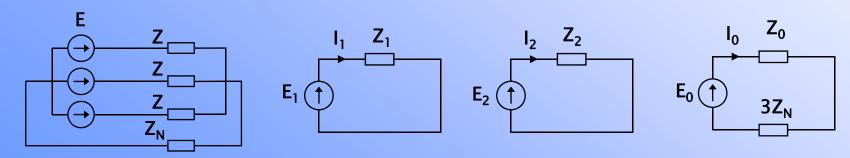
And the corresponding symmetrical components

# Symmetrical components

Positive sequence system includes the normal symmetric three phase system. Computations can be done using a one line diagram.

The negative sequence components are similar to positive ones, but they rotate in An opposite order. For passive components, the impedance Z1 and Z2 are equal, but not for rotating machines.

The zero sequence component is similar in all the three phases. It causes a current, which has to return through neutral wire, where the current IO is hence three-fold. For this reason the impedance of the neutral wire is also taken three fold.



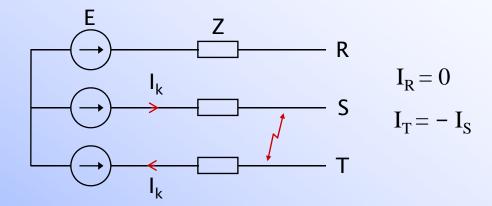
Network example

Positive sequence network

Negative sequence

Zero sequence

# 2-phase short circuit using symmetric components



$$\begin{vmatrix} I_0 \\ I_1 \\ I_2 \end{vmatrix} = \frac{1}{3} \begin{vmatrix} 1 & 1 & 1 \\ 1 & \underline{a} & \underline{a}^2 \\ 1 & \underline{a}^2 & \underline{a} \end{vmatrix} \begin{vmatrix} I_R \\ I_S \\ I_T \end{vmatrix} = \frac{1}{3}.$$
 1.  $\underline{a} = 1 \angle 120^{\circ}$ 

$$\underline{\mathbf{a}} = 1 \angle 120^{\circ}$$

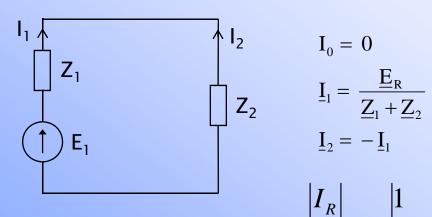
1. 
$$\Rightarrow$$
  $I_0 = 0$ 

2. & 3. & 
$$I_T = -I_S \implies I_2 = -I_1$$

Voltage source is symmetric:

$$\Rightarrow$$
  $E_1 = E_R$  ;  $E_2 = 0$  ;  $E_0 = 0$ 

# 2-phase short circuit using symmetric components One line diagram:



$$I_0 = 0$$

$$\underline{I}_1 = \frac{\underline{E}_R}{\underline{Z}_1 + \underline{Z}_2}$$

$$\underline{I}_2 = -\underline{I}_1$$

$$\begin{vmatrix} I_R \\ I_S \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 1 & \underline{a}^2 & \underline{a} \\ 1 & \underline{a} & \underline{a}^2 \end{vmatrix} \begin{vmatrix} I_0 \\ I_1 \\ I_2 \end{vmatrix}$$

Let us solve the  $I_S$ :

$$\underline{I}_{S} = \underline{a}^{2} \underline{I}_{1} + \underline{a} \underline{I}_{2}$$

$$= \frac{\underline{a}^{2} \underline{E}_{R} - \underline{a} \underline{E}_{R}}{\underline{Z}_{1} + \underline{Z}_{2}} = \frac{\sqrt{3} E_{R} \angle -90^{\circ}}{\underline{Z}_{1} + \underline{Z}_{2}}$$

$$IF \ \underline{Z}_{1} = \underline{Z}_{2} = \underline{Z}, \text{ then}$$

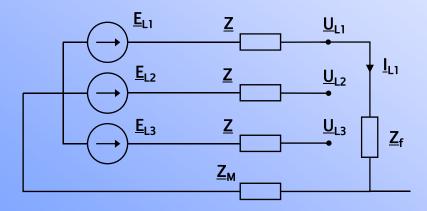
$$\underline{I}_{S} = \frac{\sqrt{3} E_{R} \angle -90^{\circ}}{2\underline{Z}}$$

# Single phase earth fault

One phase conductor is connected into the ground. The fault is unsymmetric. The zero sequence system strongly depends on how Neutral is grounded.

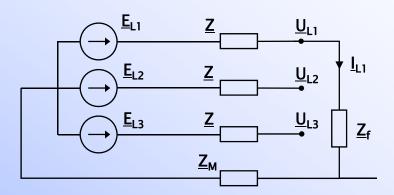
The earth fault differs clearly from the short circuit faults. In ungrounded or compensated neutral systems, the fault current is small. The voltage between sound phases and ground rises (up to the line voltage).

In Finland the 10 kV and 20 kV systems usually are ungrounded or compensated neutral systems.



One phase earth fault

# One phase earth fault



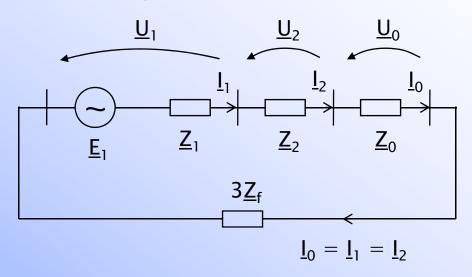
#### Solution using symmetric components

 $U_2 = -Z_2 I_2$ 

$$\begin{array}{c} \text{During the earth fault:} \underline{U}_{L1} = \ \underline{Z}_f \ \underline{I}_{L1} \\ & \underline{I}_{L2} = 0 \\ & \underline{I}_{L3} = 0 \end{array} \qquad \qquad \begin{bmatrix} \underline{U}_{L1} \\ \underline{U}_{L2} \\ \underline{U}_{L3} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & \underline{a}^2 & \underline{a} \\ 1 & \underline{a} & \underline{a}^2 \end{bmatrix} \begin{bmatrix} \underline{U}_0 \\ \underline{U}_1 \\ \underline{U}_2 \end{bmatrix} \\ & \mathbf{I}_1 = \mathbf{I}_2 \\ & \underline{I}_0 + a^2 \underline{I}_1 + a^2 \underline{I}_2 = 0 \\ & \underline{I}_0 + a \ \underline{I}_1 + a^2 \underline{I}_2 = 0 \\ & \underline{U}_1 = \underline{E}_1 - \underline{Z}_1 \ \underline{I}_1 \end{array} \qquad \qquad \begin{array}{c} \underline{u}_0 = \underline{I}_1 = \underline{I}_2 \\ & \underline{U}_1 = \underline{I}_2 \end{array}$$

\*  $-Z_0 I_0 + E_1 - Z_1 I_1 - Z_2 I_2 = 3 Z_1 I_0$ 

# One phase earth fault



Component networks are in series connection

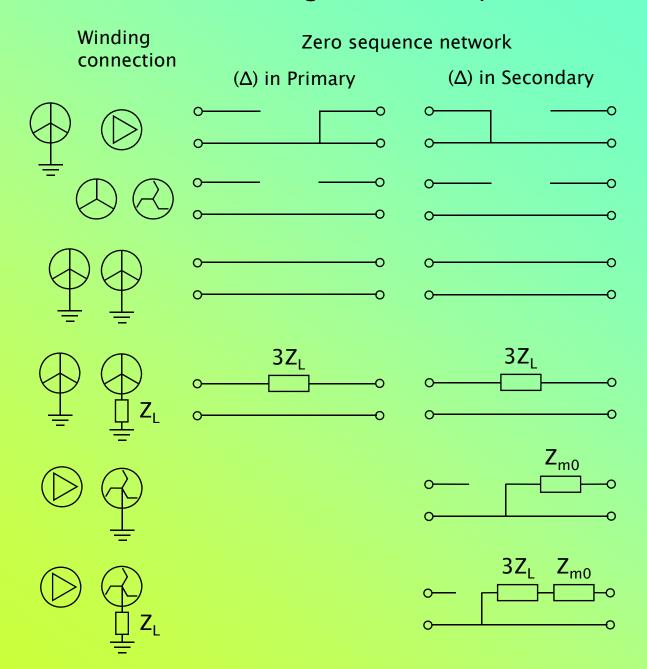
Which gives for the zero sequence current:

$$\underline{\mathbf{I}}_0 = \frac{\underline{\mathbf{E}}_1}{\underline{\mathbf{Z}}_0 + \underline{\mathbf{Z}}_1 + \underline{\mathbf{Z}}_2 + 3\underline{\mathbf{Z}}_f} = \frac{\underline{\mathbf{E}}_1}{3\underline{\mathbf{Z}} + 3\underline{\mathbf{Z}}_M + 3\underline{\mathbf{Z}}_f}$$

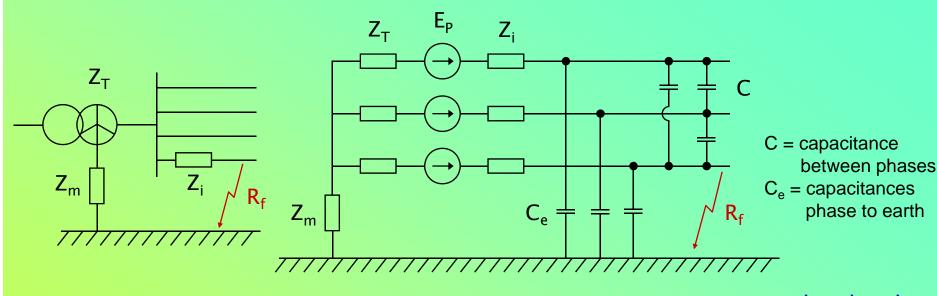
The total fault current is three times the zero sequence current:

$$\underline{\mathbf{I}}_{f} = 3\,\underline{\mathbf{I}}_{0} = \frac{3\,\underline{\mathbf{E}}_{1}}{\underline{\mathbf{Z}}_{0} + \underline{\mathbf{Z}}_{1} + \underline{\mathbf{Z}}_{2} + 3\,\underline{\mathbf{Z}}_{f}} = \frac{\underline{\mathbf{E}}_{1}}{\underline{\mathbf{Z}} + \underline{\mathbf{Z}}_{M} + \underline{\mathbf{Z}}_{f}}$$

### Transformer windings in zero sequence networks



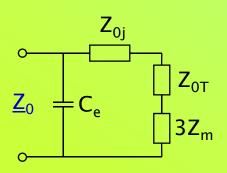
# Solution for 1-phase earth fault:



$$\underline{I_f} = 3\underline{I_0} = \frac{3\underline{E_P}}{\underline{Z_0 + Z_1 + Z_2 + 3R_f}} = \frac{\underline{E_P}}{\frac{1}{3}(\underline{Z_0 + Z_1 + Z_2}) + R_f}$$

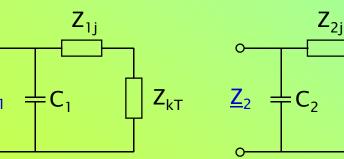
 $\underline{I}_{0} = \underline{I}_{1} = \underline{I}_{2}$   $3R_{f} \qquad \underline{Z}_{0}$   $\underline{Z}_{1}$   $\underline{E}_{P} \qquad \underline{Z}_{2}$ 

0-network



Positive seq. /

negative seq. ntwk



 $C_1 = C_e + 3C$   $C_1 = C_2$ 

# Comparison of 1-ph, 2-ph, 3-ph faults for fault currents (Thevenin's method):

1-ph: 
$$\underline{I}_f = \frac{\underline{E}_P}{\frac{1}{3}(\underline{Z}_0 + \underline{Z}_1 + \underline{Z}_2) + R_f}$$

2-ph: 
$$\underline{I}_f = \frac{\sqrt{3}\underline{E}_P}{\underline{Z}_1 + \underline{Z}_2 + R_f}$$

3-ph: 
$$\underline{I}_f = \frac{\underline{E}_P}{\underline{Z}_1 + R_f}$$

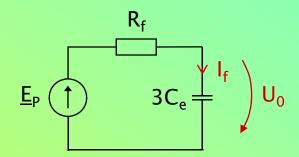
Ep is phase voltage; Rf is fault resistance Z1,Z2,Z0 are sequence impedances

# Earth faults in ungrounded systems:

$$\underline{Z}_0 \approx \frac{1}{j\omega C_e}$$

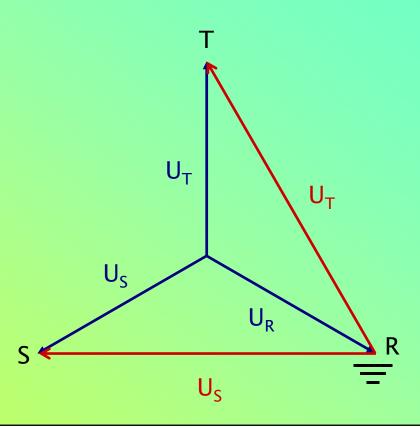
$$\underline{Z}_0 \gg \underline{Z}_1 \quad \& \quad \underline{Z}_0 \gg \underline{Z}_2$$

⇒ one line diagram:



$$\begin{cases} \underline{I}_{f} = \frac{\underline{E}_{P}}{R_{f} + \frac{1}{j\omega 3C_{e}}} \\ \frac{U_{0}}{E_{P}} = \frac{1}{\sqrt{1 + (3\omega C_{e} R_{f})^{2}}} \end{cases}$$

# Voltages during an earth fault :



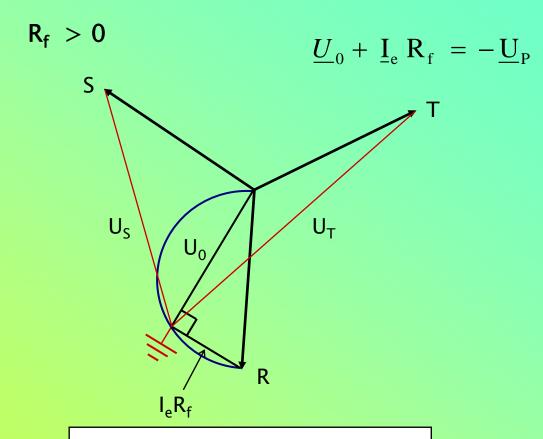
In sound network

$$U_R = U_S = U_T = U_P$$

During earth fault, if  $R_f = 0$ 

$$U_R = 0$$
 ;  $U_T = \sqrt{3} U_P$  ;  $U_S = \sqrt{3} U_P$ 

# Voltages during an earth fault :



$$U_T > \sqrt{3} U_P$$
 ?

Max. voltage for  $U_T$ , when

$$R_{f} = 0.37 \frac{1}{j\omega C_{0}}$$

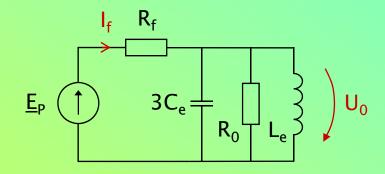
And 
$$U_T = 1.05 \cdot \sqrt{3} \cdot U_P$$

# Compensated neutral systems : $Z_m = \omega L_e$

Inductance L<sub>e</sub> is selected such that the current of C<sub>e</sub> is cancelled

$$\underline{\mathbf{Y}}_0 \approx \mathbf{j}\omega \mathbf{C}_{\mathrm{e}} - \frac{1}{\mathbf{j}\omega 3\mathbf{L}_{\mathrm{e}}} \approx 0$$

One line diagram:



R<sub>0</sub> is the network leakage resistance

If 100 % compensation:

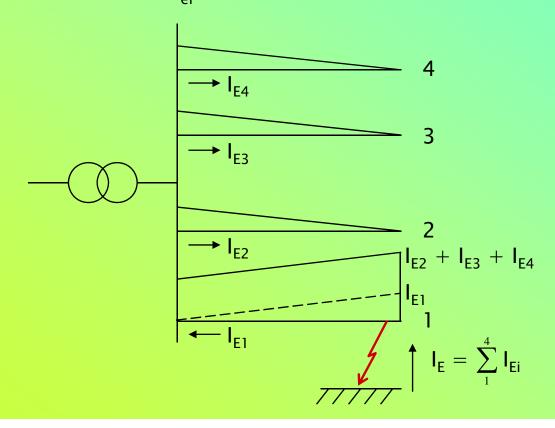
$$\begin{cases} I_f = \frac{E}{R_f + R_0} \\ \frac{U_0}{E} = \frac{R_0}{R_0 + R_f} \end{cases}$$

### Earth fault currents in an ungrounded system

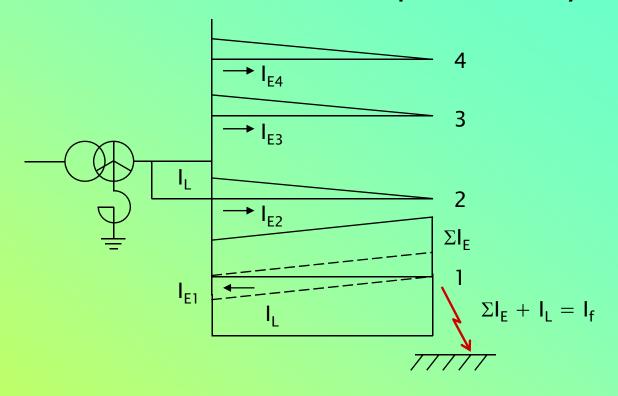
The current measured at the substation ( $\Sigma I_0$ ) includes the current in the fault location less the current which flows through the earth capacitances of the faulty line:

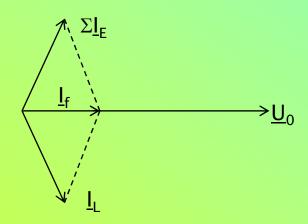
 $\sum I_0 = \frac{C_0 - C_{01}}{C_0} I_{ef}$ 

where  $C_0$  is total earth capacitance of the network,  $C_{01}$  is earth capacitance of the line concerned and  $I_{ef}$  is the total earth fault current.



# Earth fault currents in a compensated system





Current in the fault location in case of 100% compensation

