1. Theoretical exercises

Demo exercises

1.1 Let **A** be a real valued 2×2 -matrix and let $x, b \in \mathbb{R}^2$,

$$m{A} = egin{bmatrix} a_{11} & a_{12} \ a_{21} & a_{22} \end{bmatrix}, \qquad m{x} = egin{bmatrix} x_1 \ x_2 \end{bmatrix}, \qquad m{b} = egin{bmatrix} b_1 \ b_2 \end{bmatrix}$$

(a) Write explicitly \mathbf{A}^{\top} , $\mathbf{A}^{\top}\mathbf{A}$ $\mathbf{A}\mathbf{x}$, $\mathbf{x}^{\top}\mathbf{A}$ and $\mathbf{x}^{\top}\mathbf{A}\mathbf{x}$. Solution.

$$oldsymbol{A}^ op = egin{bmatrix} a_{11} & a_{21} \ a_{12} & a_{22} \end{bmatrix}, & oldsymbol{A}^ op oldsymbol{A}^ op oldsymbol{A} = egin{bmatrix} a_{11} & a_{21} & a_{11}a_{12} + a_{21}a_{22} \ a_{11}a_{12} + a_{21}a_{22} & a_{12}^2 + a_{22}^2 \end{bmatrix}, & oldsymbol{A}oldsymbol{x} = egin{bmatrix} a_{11}x_1 + a_{12}x_2 \ a_{21}x_1 + a_{22}x_2 \end{bmatrix}, & oldsymbol{x}^ op oldsymbol{A} = egin{bmatrix} a_{11}x_1 + a_{21}x_2 & a_{12}x_1 + a_{22}x_2, \end{bmatrix} & oldsymbol{x}^ op oldsymbol{A} = oldsymbol{a}_{11}x_1 + a_{21}x_2 & a_{12}x_1 + a_{22}x_2, \end{bmatrix}$$

(b) Verify that $\frac{\partial (\boldsymbol{b}^{\top} \boldsymbol{x})}{\partial \boldsymbol{x}} = \frac{\partial (\boldsymbol{x}^{\top} \boldsymbol{b})}{\partial \boldsymbol{x}} = \boldsymbol{b}^{\top}$.

Solution. Since.

$$\boldsymbol{b}^{\top}\boldsymbol{x} = \boldsymbol{x}^{\top}\boldsymbol{b} = b_1x_1 + b_2x_2,$$

and

$$\begin{bmatrix} \frac{\partial}{\partial x_1}(b_1x_1 + b_2x_2) & \frac{\partial}{\partial x_2}(b_1x_1 + b_2x_2) \end{bmatrix} = \begin{bmatrix} b_1 & b_2 \end{bmatrix} = \boldsymbol{b}^\top,$$

which proves the claim. Note that the result can be generalized for \mathbb{R}^n -vectors.

(c) Verify that $\frac{\partial (\boldsymbol{x}^{\top}\boldsymbol{x})}{\partial \boldsymbol{x}} = 2\boldsymbol{x}^{\top}$

Solution. The claim follows by taking the derivatives from,

$$\boldsymbol{x}^{\top}\boldsymbol{x} = x_1^2 + x_2^2.$$

Note that the result can be generalized for \mathbb{R}^n -vectors.

(d) Verify that $\frac{\partial (Ax)}{\partial x} = A$.

Solution.

$$\frac{\partial (\boldsymbol{A}\boldsymbol{x})}{\partial \boldsymbol{x}} = \frac{\partial}{\partial \boldsymbol{x}} \begin{bmatrix} a_{11}x_1 + a_{12}x_2 \\ a_{21}x_1 + a_{22}x_2 \end{bmatrix} = \begin{bmatrix} \frac{\partial}{\partial x_1}(a_{11}x_1 + a_{12}x_2) & \frac{\partial}{\partial x_2}(a_{11}x_1 + a_{12}x_2) \\ \frac{\partial}{\partial x_1}(a_{21}x_1 + a_{22}x_2) & \frac{\partial}{\partial x_2}(a_{21}x_1 + a_{22}x_2) \end{bmatrix} = \boldsymbol{A}.$$

Note that the result can be generalized for \mathbb{R}^n -vectors and $\mathbb{R}^{m \times n}$ -matrices.

(e) Verify that $\frac{\partial (\boldsymbol{x}^{\top} A)}{\partial \boldsymbol{x}} = \boldsymbol{A}^{\top}$.

Solution.

$$\frac{\partial(\boldsymbol{x}^{\top}\boldsymbol{A})}{\partial\boldsymbol{x}} = \frac{\partial}{\partial\boldsymbol{x}} \begin{bmatrix} a_{11}x_1 + a_{21}x_2 & a_{12}x_1 + a_{22}x_2 \end{bmatrix}
= \begin{bmatrix} \frac{\partial}{\partial x_1}(a_{11}x_1 + a_{21}x_2) & \frac{\partial}{\partial x_2}(a_{11}x_1 + a_{21}x_2) \\ \frac{\partial}{\partial x_1}(a_{12}x_1 + a_{22}x_2) & \frac{\partial}{\partial x_2}(a_{12}x_1 + a_{22}x_2) \end{bmatrix} = \boldsymbol{A}^{\top}.$$

Note that the result can be generalized for \mathbb{R}^n -vectors and $\mathbb{R}^{m \times n}$ -matrices.

Ilmonen/ Shafik/ Pere/ Mellin Fall 2022 Exercise 1.

(f) Verify that $\frac{\partial (\boldsymbol{x}^{\top} \boldsymbol{A} \boldsymbol{x})}{\partial \boldsymbol{x}} = \boldsymbol{x}^{\top} (\boldsymbol{A} + \boldsymbol{A}^{\top}).$ Solution.

$$\frac{\partial(\boldsymbol{x}^{\top}\boldsymbol{A}\boldsymbol{x})}{\partial\boldsymbol{x}} = \begin{bmatrix} \frac{\partial}{\partial x_{1}}(a_{11}x_{1}^{2} + (a_{12} + a_{21})x_{1}x_{2} + a_{22}x_{2}^{2}) & \frac{\partial}{\partial x_{2}}(a_{11}x_{1}^{2} + (a_{12} + a_{21})x_{1}x_{2} + a_{22}x_{2}^{2}) \end{bmatrix}
= \begin{bmatrix} 2a_{11}x_{1} + (a_{12} + a_{21})x_{2} & (a_{12} + a_{21})x_{1} + 2a_{22}x_{2} \end{bmatrix}
= \begin{bmatrix} a_{11}x_{1} + a_{12}x_{2} & a_{21}x_{1} + a_{22}x_{2} \end{bmatrix} + \begin{bmatrix} a_{11}x_{1} + a_{21}x_{2} & a_{12}x_{1} + a_{22}x_{2} \end{bmatrix}
= \boldsymbol{x}^{\top}\boldsymbol{A}^{\top} + \boldsymbol{x}^{\top}\boldsymbol{A} = \boldsymbol{x}^{\top}(\boldsymbol{A} + \boldsymbol{A}^{\top}).$$

Note that the result can be generalized for \mathbb{R}^n -vectors and $\mathbb{R}^{m \times n}$ -matrices.

Remark: consider a vector valued function $f: \mathbb{R}^n \to \mathbb{R}^m$, that is smooth enough,

$$f(oldsymbol{x}) = egin{bmatrix} f_1(oldsymbol{x}) \ f_2(oldsymbol{x}) \ dots \ f_m(oldsymbol{x}) \end{bmatrix}, \quad oldsymbol{x} = (x_1, x_2, ..., x_n) \in \mathbb{R}^n.$$

The derivative of the function is

$$rac{\partial f(m{x})}{\partial m{x}} = egin{bmatrix} rac{\partial f_1(m{x})}{\partial x_1} & rac{\partial f_1(m{x})}{\partial x_2} & \dots & rac{\partial f_1(m{x})}{\partial x_n} \ rac{\partial f_2(m{x})}{\partial x_1} & rac{\partial f_2(m{x})}{\partial x_2} & \dots & rac{\partial f_2(m{x})}{\partial x_n} \ dots & dots & dots & dots & dots \ rac{\partial f_2(m{x})}{\partial x_1} & rac{\partial f_2(m{x})}{\partial x_2} & \dots & rac{\partial f_2(m{x})}{\partial x_n} \ dots & dots & dots & dots \ rac{\partial f_n(m{x})}{\partial x_1} & rac{\partial f_n(m{x})}{\partial x_2} & \dots & rac{\partial f_n(m{x})}{\partial x_n} \ \end{bmatrix}.$$

- **1.2** Consider the linear model $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$, where $\mathbf{y}, \boldsymbol{\varepsilon} \in \mathbb{R}^n$, $\mathbf{X} \in \mathbb{R}^{n \times (k+1)}$ and $\boldsymbol{\beta} \in \mathbb{R}^{k+1}$. Let the standard assumptions (i)–(v), given in the lecture slides, hold.
 - a) Show that the least squares (LS) estimator for the vector $\boldsymbol{\beta}$ is $\mathbf{b} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}$.
 - b) Show that **b** is unbiased, that is, $\mathbb{E}[\mathbf{b}] = \boldsymbol{\beta}$.
 - c) Show that $Cov(\mathbf{b}) = \sigma^2(\mathbf{X}^\top \mathbf{X})^{-1}$.

Solution.

a) The sum of squares is,

$$f(\boldsymbol{\beta}) = \boldsymbol{\varepsilon}^{\top} \boldsymbol{\varepsilon} = (\mathbf{y} - \mathbf{X} \boldsymbol{\beta})^{\top} (\mathbf{y} - \mathbf{X} \boldsymbol{\beta}) = \mathbf{y}^{\top} \mathbf{y} - 2 \boldsymbol{\beta}^{\top} \mathbf{X}^{\top} \mathbf{y} + \boldsymbol{\beta}^{\top} \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\beta}.$$

The LS-estimator for the vector $\boldsymbol{\beta}$ is obtained by minimizing the sum of squares $f(\boldsymbol{\beta})$ with respect to the vector $\boldsymbol{\beta}$. By differentiating $f(\boldsymbol{\beta})$ with respect to $\boldsymbol{\beta}$ and setting the derivative equal to zero, we obtain,

$$f'(\boldsymbol{\beta}) = -2\mathbf{y}^{\mathsf{T}}\mathbf{X} + 2\boldsymbol{\beta}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{X} = \mathbf{0}.$$

By the standard assumptions, we have that $\operatorname{rank}(\mathbf{X}) = k+1$, which implies that the matrix $\mathbf{X}^{\top}\mathbf{X}$ is nonsingular and $\boldsymbol{\beta}$ is solvable. The solution,

$$\mathbf{b} = (\mathbf{X}^{\top} \mathbf{X})^{-1} \mathbf{X}^{\top} \mathbf{y},$$

minimizes the function $f(\boldsymbol{\beta})$, since $\mathbf{X}^{\top}\mathbf{X}$ is always a positive definite matrix and,

$$f''(\boldsymbol{\beta}) = 2\mathbf{X}^{\top}\mathbf{X}.$$

b) Note that,

$$\mathbf{b} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}(\mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}) = \boldsymbol{\beta} + (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\boldsymbol{\varepsilon}.$$

Since the vector $\boldsymbol{\beta}$ and the matrix **X** are non-random, it follows that,

$$\mathbb{E}[\mathbf{b}] = \mathbb{E}[\boldsymbol{\beta}] + (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbb{E}[\boldsymbol{\varepsilon}] = \boldsymbol{\beta} + (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{0} = \boldsymbol{\beta}.$$

c) Using part (b), we obtain,

$$\mathbf{b} - \mathbb{E}[\mathbf{b}] = \mathbf{b} - \boldsymbol{\beta} = (\mathbf{X}^{\top} \mathbf{X})^{-1} \mathbf{X}^{\top} \boldsymbol{\varepsilon}.$$

Then, since X is non-random,

$$Cov(\mathbf{b}) = \mathbb{E}[(\mathbf{b} - \mathbb{E}[\mathbf{b}])(\mathbf{b} - \mathbb{E}[\mathbf{b}])^{\top}]$$

$$= E[(\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^{\top}\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}]$$

$$= (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbb{E}[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^{\top}]\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}$$

$$= (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}(\sigma^{2}\mathbf{I})\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}$$

$$= \sigma^{2}(\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}$$

$$= \sigma^{2}(\mathbf{X}^{\top}\mathbf{X})^{-1}.$$

Homework

- **1.3** Consider the linear model $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$, where $\mathbf{y}, \boldsymbol{\varepsilon} \in \mathbb{R}^n$, $\mathbf{X} \in \mathbb{R}^{n \times (k+1)}$ and $\boldsymbol{\beta} \in \mathbb{R}^{k+1}$. Let the standard assumptions (i)–(v), given in the lecture slides, hold. Let $\mathbf{M} = \mathbf{I} \mathbf{X}(\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}$ and recall that $\operatorname{rank}(\mathbf{M}) = n (k+1)$.
 - a) Let **e** be the estimated residual vector, that is, $\mathbf{e} = \mathbf{y} \hat{\mathbf{y}}$. Use the results obtained in previous exercises to show that

$$Cov(\mathbf{e}) = \sigma^2 \mathbf{M}.$$

b) Use previous exercises and part (a), and show that,

$$s^{2} = \frac{1}{n-k-1} \sum_{i=1}^{n} e_{i}^{2},$$

is an unbiased estimator for $\operatorname{Var}[\varepsilon_i] = \sigma^2$, that is, show that $\mathbb{E}[s^2] = \sigma^2$.

Hint. (1) The trace of a square matrix equals the sum of the corresponding eigenvalues, and, (2) the eigenvalues of an idempotent matrix are either 0 or 1. (You are not expected to prove results (1)-(2) in this exercise.)