

Maxwellin yhtälöt

$$\nabla \times \bar{E} = - \frac{\partial \bar{B}}{\partial t}$$

$$\nabla \times \bar{H} = \bar{j} + \frac{\partial \bar{D}}{\partial t}$$

$$\nabla \cdot \bar{D} = \rho$$

$$\nabla \cdot \bar{B} = 0$$

$$\bar{D} = \epsilon_0 \bar{E}$$

$$\bar{B} = \mu_0 \bar{H}$$

$$\uparrow$$

$$8,854 \cdot 10^{-12} \frac{As}{Vm}$$

$$\uparrow$$

$$4\pi \cdot 10^{-7} \frac{Vs}{Am}$$

(TYHJIÖSSÄ)

Sähköstaattiset kentät

$$\frac{\partial}{\partial t} = 0$$

$$\nabla \times \bar{E} = - \frac{\partial \bar{B}}{\partial t}$$

$$\nabla \cdot \bar{D} = \rho$$

$$\nabla \times \bar{E}(\vec{r}) = 0$$

$$\nabla \cdot \bar{D}(\vec{r}) = \rho(\vec{r})$$

$$\bar{D}(\vec{r}) = \epsilon_0 \bar{E}(\vec{r})$$

$$\bar{E} = -\nabla\phi$$

$$\nabla \cdot \epsilon_0 (-\nabla\phi) = \rho \Rightarrow \nabla^2 \phi(\vec{r}) = - \frac{\rho(\vec{r})}{\epsilon_0}$$

POISSONIN YHTÄLÖ

Skalaaripotentiali

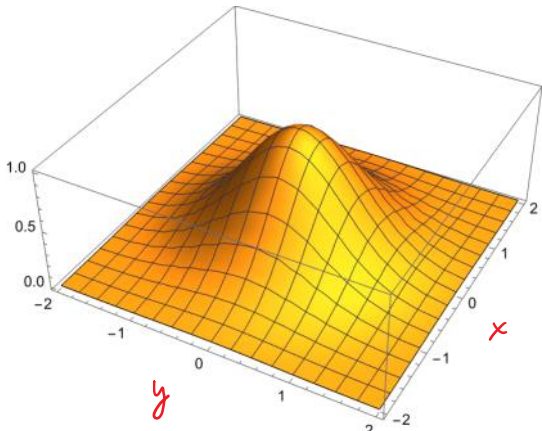
$$\rho \rightarrow \phi \rightarrow \bar{E}$$

Poissonin yhtälö

$$\nabla^2 \phi = - \frac{\rho}{\epsilon_0}$$

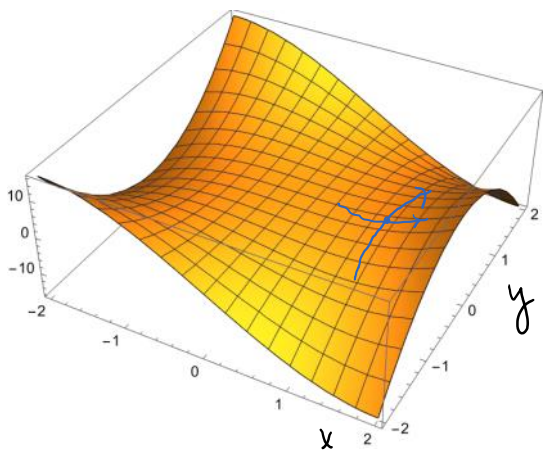
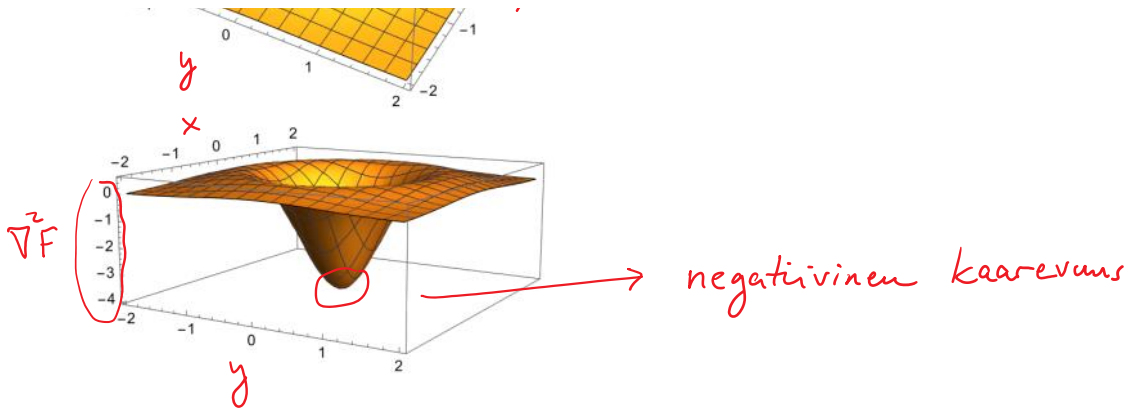
Laplacen yhtälö

$$\rho = 0 \Rightarrow \nabla^2 \phi(\vec{r}) = 0$$



$$F(x,y) = e^{-x^2-y^2}$$

$$\nabla^2 F = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) F(x,y)$$



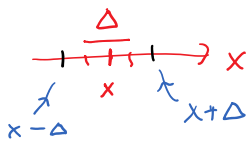
$$G(x, y) = x^3 - 3xy^2$$

$$\frac{\partial^2}{\partial x^2} G = \frac{\partial}{\partial x} (3x^2 - 3y^2) = 6x$$

$$\frac{\partial^2}{\partial y^2} G = \frac{\partial}{\partial y} (-6xy) = -6x$$

$$\nabla^2 G = 0$$

$$f(x) \Rightarrow f'(x) \cong \frac{1}{\Delta} \left[f\left(x + \frac{\Delta}{2}\right) - f\left(x - \frac{\Delta}{2}\right) \right]$$



$$f''(x) = \frac{1}{\Delta^2} \left(f(x+\Delta) - f(x) - (f(x) - f(x-\Delta)) \right)$$

$$f''(x) = 0$$



$$f(x+\Delta) + f(x-\Delta) = 2f(x)$$

$$f(x) = \frac{1}{2} (f(x+\Delta) + f(x-\Delta))$$

(KESKIARVO)

$$\begin{aligned} 3D: f(x, y, z) = & \frac{1}{6} (f(x+\Delta, y, z) + f(x-\Delta, y, z) \\ & + f(x, y+\Delta, z) + f(x, y-\Delta, z) \\ & + f(x, y, z+\Delta) + f(x, y, z-\Delta)) \end{aligned}$$

Pistevarauksen potentiaali

$$\epsilon_0 \quad Q \cdot \vec{r} \quad + \quad \vec{E}(\vec{r}) = \frac{Q}{4\pi\epsilon_0 r^2} \vec{u}_r$$

$$\phi(\vec{r}) = ?$$

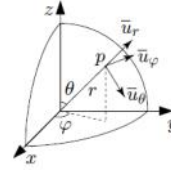
$$\vec{E} = -\nabla\phi$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0} \frac{\vec{u}_r}{r^2}$$

$$= -\vec{u}_r \frac{\partial\phi}{\partial r}$$

$$\Rightarrow \phi(\vec{r}) = \frac{Q}{4\pi\epsilon_0 r}$$

Pallokoordinaatisto



$$\nabla f(\vec{r}) = \vec{u}_r \frac{\partial}{\partial r} f + \vec{u}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} f + \vec{u}_\phi \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} f$$

$$\nabla \times \vec{f} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{u}_r & r\vec{u}_\theta & r \sin \theta \vec{u}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ f_r & r f_\theta & r \sin \theta f_\phi \end{vmatrix}$$

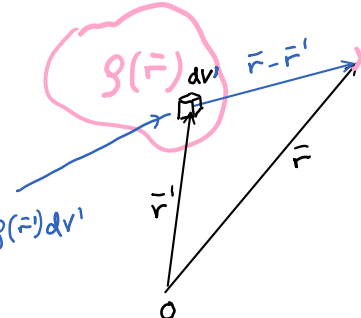
$$\nabla \cdot \vec{f} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 f_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta f_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} f_\phi$$

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$

$$\frac{d}{dr} \left(\frac{1}{r} \right) = \frac{d}{dr} r^{-1} = -1 \cdot r^{-2}$$

Varausjakautuman potentiaali

$$\nabla^2 \phi = -\frac{\rho}{\epsilon_0}$$



$\rho(\vec{r}') dv'$

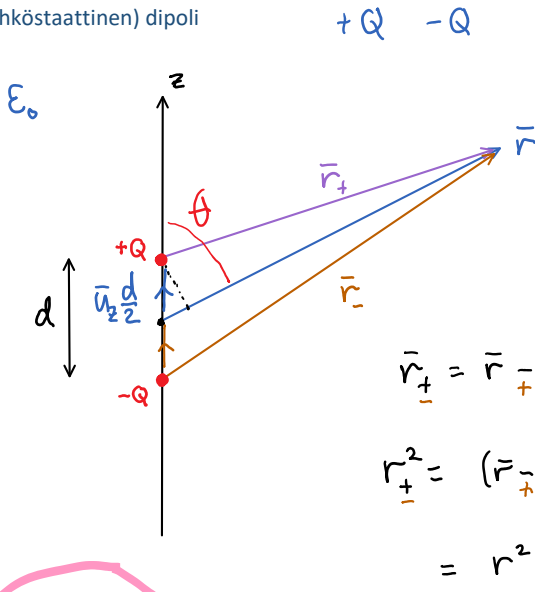
$dQ = \rho(\vec{r}') dv'$

$\phi(\vec{r}) = ?$

$\vec{E}(\vec{r}) = ?$

$$\phi(\vec{r}) = \int_V \frac{\rho(\vec{r}') dv'}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|}$$

(Sähköstaattinen) dipoli



$+Q \quad -Q$

\vec{r}_+

\vec{r}_-

\vec{r}

θ

d

$$\phi(\vec{r}) \rightarrow \vec{E}(\vec{r}) = -\nabla\phi(\vec{r})$$

$$\phi_d = \frac{+Q}{4\pi\epsilon_0 r_+} + \frac{-Q}{4\pi\epsilon_0 r_-}$$

$$\vec{r}_+ = \vec{r} - \vec{u}_z \frac{d}{2}$$

$$r_+ = \sqrt{\vec{r}_+ \cdot \vec{r}_+}$$

$$r_+^2 = (\vec{r} - \vec{u}_z \frac{d}{2}) \cdot (\vec{r} - \vec{u}_z \frac{d}{2}) = r^2 - \vec{r} \cdot \vec{u}_z \frac{d}{2} + \vec{u}_z \cdot \vec{r} \frac{d}{2} + \vec{u}_z \cdot \vec{u}_z \left(\frac{d}{2} \right)^2$$

$$= r^2 - r d \cos \theta + (d/2)^2 = r^2 \left(1 - \frac{d \cos \theta}{r} + \left(\frac{d}{2r} \right)^2 \right)$$

$r \gg d$

$$= r^2 \pm r d \cos\theta + (d/2)^2 = r^2 \left(1 \pm \frac{d \cos\theta}{r} + \left(\frac{d}{2r}\right)^2 \right)$$

$$r_{\pm} = r \sqrt{1 \pm \frac{d \cos\theta}{r}} \approx r \left(1 \pm \frac{d \cos\theta}{2r} \right) = r \pm \frac{d \cos\theta}{2}$$

$$\phi_d(r) = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r_{+}} - \frac{1}{r_{-}} \right) = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r \left(1 - \frac{d \cos\theta}{2r} \right)} - \frac{1}{r \left(1 + \frac{d \cos\theta}{2r} \right)} \right)$$

$$= \frac{Q}{4\pi\epsilon_0 r} \left(\frac{1}{1 - \frac{d \cos\theta}{2r}} - \frac{1}{1 + \frac{d \cos\theta}{2r}} \right)$$

$\left(\frac{1}{1-x} \approx 1+x \right)$
 $(|x| \ll 1)$

$$\approx \frac{Q}{4\pi\epsilon_0 r} \left(1 + \frac{d \cos\theta}{2r} - \left(1 - \frac{d \cos\theta}{2r} \right) \right) = \frac{Q}{4\pi\epsilon_0 r} \cdot \frac{d \cos\theta}{2r} \cdot 2$$

$$= \frac{Q d \cos\theta}{4\pi\epsilon_0 r^2} = \frac{p \cos\theta}{4\pi\epsilon_0 r^2}$$

\downarrow

$p \vec{u}_z \cdot \vec{u}_r$

$(p = Qd)$
 $[p] = \text{Asm}$

$$\vec{E}_d(r) = -\nabla\phi_d = -\nabla \left(\frac{p \cos\theta}{4\pi\epsilon_0 r^2} \right)$$

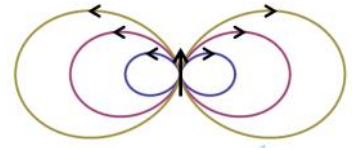
$$= - \left(\vec{u}_r \frac{\partial \phi_d}{\partial r} + \frac{1}{r} \vec{u}_\theta \frac{\partial \phi_d}{\partial \theta} \right)$$

$$\frac{\partial}{\partial r} r^{-2} = -2r^{-3}$$

$$\frac{\partial}{\partial \theta} \cos\theta = -\sin\theta$$

$$= \frac{p}{4\pi\epsilon_0} \left(\vec{u}_r 2r^{-3} \cos\theta + \frac{1}{r} \vec{u}_\theta \sin\theta r^{-2} \right)$$

$$= \frac{p}{4\pi\epsilon_0 r^3} \left(2 \cos\theta \vec{u}_r + \sin\theta \vec{u}_\theta \right)$$



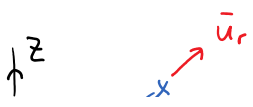
$$R(\theta) = k \sin^2\theta$$

$\uparrow z$

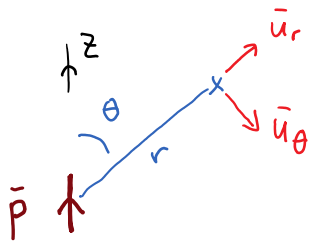
$\uparrow \vec{p} = \vec{u}_z p$

$\times \vec{p} = \vec{u}_\phi p$

$$\phi = \frac{\vec{p} \cdot \vec{u}_r}{4\pi\epsilon_0 r^2}$$



$$\theta = 0 \Rightarrow 2 \vec{u}_r = 2 \vec{u}_z$$



$$\theta = 0 \Rightarrow 2 \bar{u}_r = 2 \bar{u}_z$$

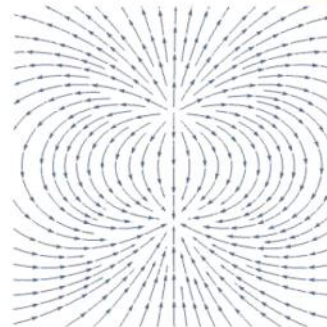
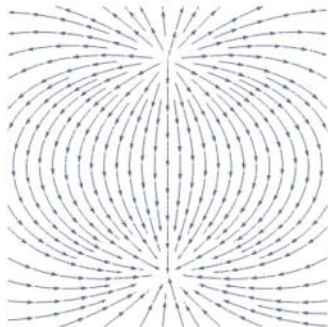
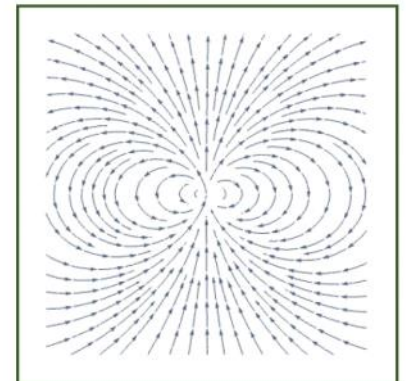
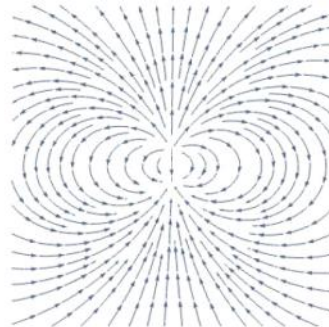
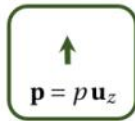
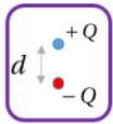
$$\theta = 90^\circ \Rightarrow 1 \bar{u}_\theta = -\bar{u}_z$$

$$\theta = 180^\circ \Rightarrow -2 \bar{u}_r = 2 \bar{u}_z$$

Taylorin sarjojen tarkkuudesta

x	$\frac{1}{1+x}$	$1-x$	virhe	$\sqrt{1+x}$	$1+\frac{x}{2}$	virhe
0,1	0,90909090909	0,9	1 %	1,0488088482	1,05	0,114 %
0,01	0,99009900990	0,99	10^{-4}	1,0049875621	1,005	$1,24 \cdot 10^{-5}$
0,001	0,99900099900	0,999	10^{-6}	1,0004998751	1,0005	$1,25 \cdot 10^{-7}$
0,0001	0,99990009999	0,9999	10^{-8}	1,0000499988	1,00005	$1,25 \cdot 10^{-9}$

Kaksi pistevarausta
vai dipoli?



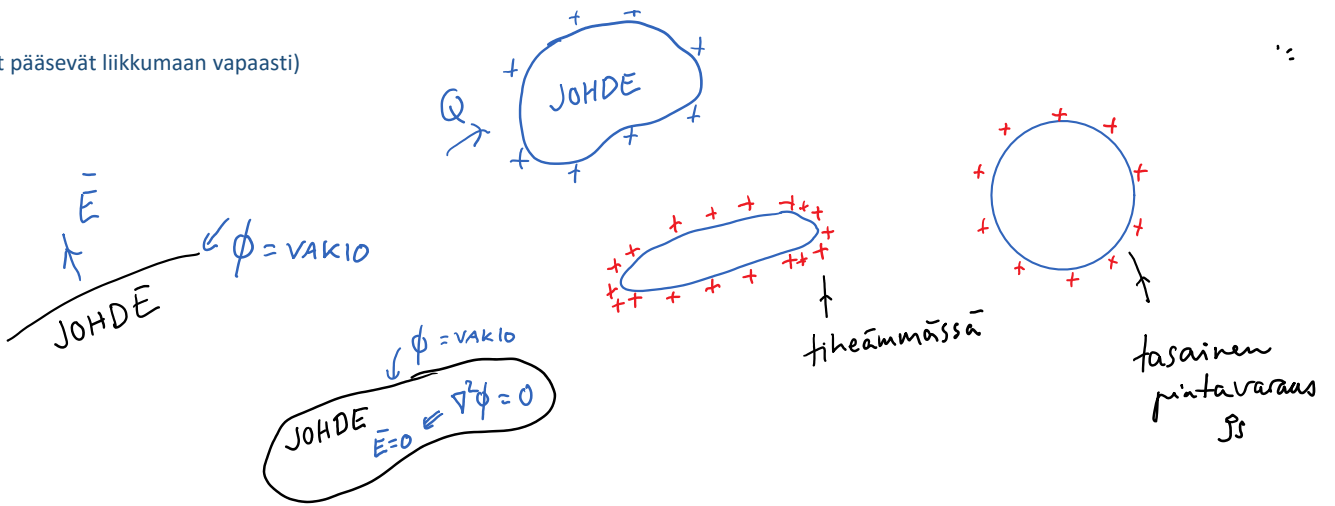
JOHDE

(varaukset pääsevät liikkumaan vapaasti)



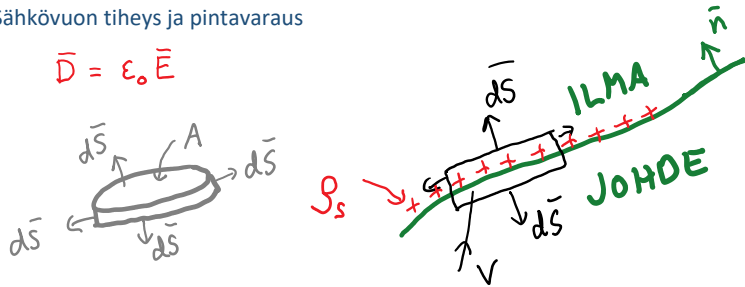
JOHDE

(varaukset pääsevät liikkumaan vapaasti)



Sähkövuon tiheys ja pintavaraus

$$\vec{D} = \epsilon_0 \vec{E}$$

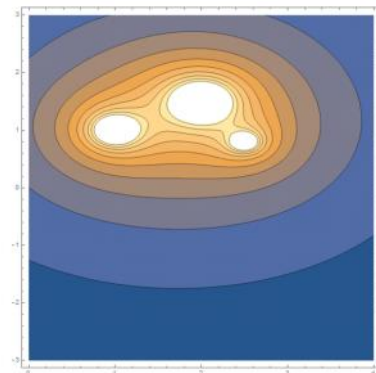
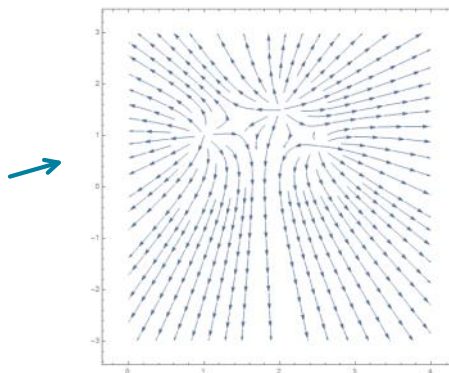
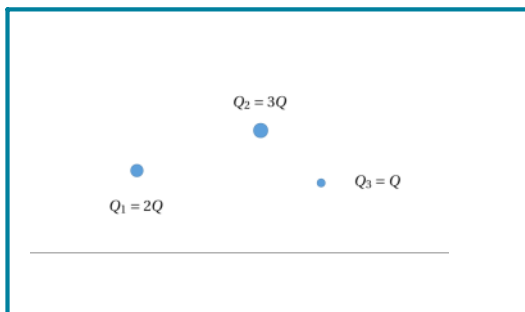
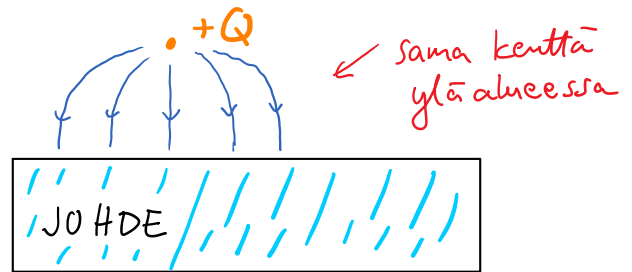
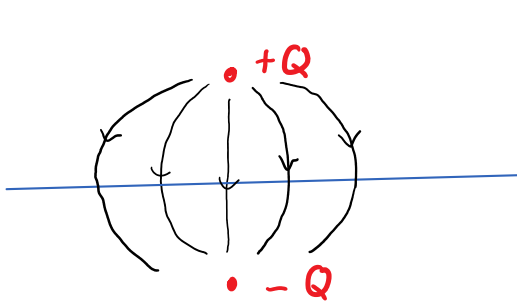


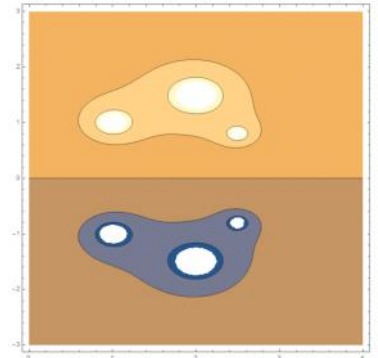
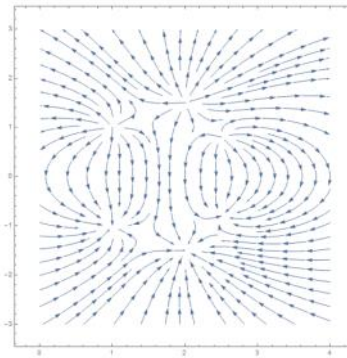
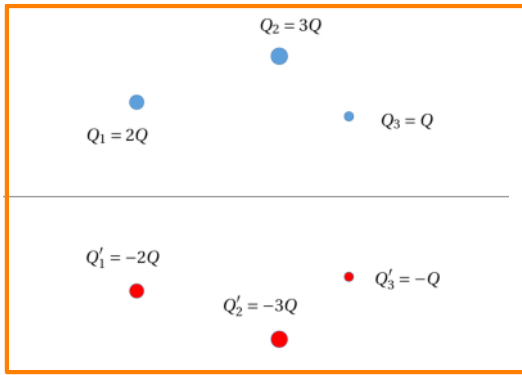
$$\int_V \nabla \cdot \vec{D} dV = \oint_S \vec{D} \cdot d\vec{s}$$

$$= \rho_s A = D A$$

$$\rho_s = D_n$$

Kuvalähdeperiaate (peilikuvaperiaate)





ERISTE



$$\bar{P} = \frac{n\bar{p}}{V}$$

$$\bar{p} = Qd\bar{u}$$

$$Asm$$

$$[\bar{P}] = \frac{Asm}{m^3} = \frac{As}{m^2}$$

$$\bar{D} = \epsilon_0 \bar{E} + \bar{P}$$

$$\bar{P} = \chi_e \epsilon_0 \bar{E}$$

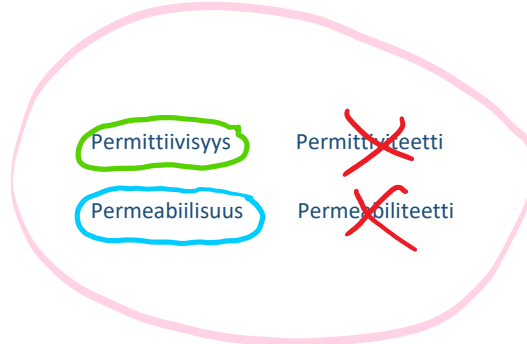
↑
SUSKEPTIIVISUUS

$$\bar{D} = \epsilon_0 (1 + \chi_e) \bar{E} = \epsilon \bar{E}$$

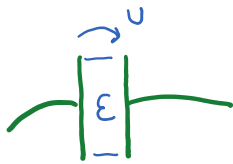
Permittiivisyys $\epsilon = \epsilon_0 (1 + \chi_e) = \epsilon_r \epsilon_0$

Suskeptiivisyys χ_e

Suhteellinen permittiivisyys ϵ_r



Kapasitansi



$$C = \frac{Q}{U}$$

$$\frac{As}{V} = \text{faradi}$$

$$\nabla^2 \phi = 0 \Rightarrow \phi \rightarrow \bar{E} \rightarrow \bar{D} \rightarrow S_s \rightarrow Q$$

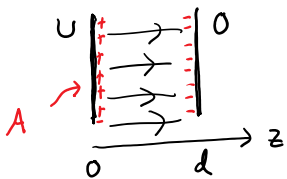


$$\phi''(z) = 0 \quad \phi(z) = Az + B$$

$$\phi(0) = U$$

$$\phi(d) = 0$$

$$\phi(z) = U(1 - z/d)$$



$$\bar{E} = -\nabla \phi = -\bar{u}_z \frac{\partial}{\partial z} U(1 - z/d) = \bar{u}_z \frac{U}{d} \Rightarrow \bar{D} = \epsilon \bar{u}_z \frac{U}{d}$$

$$S_s = \epsilon \frac{U}{d} \Rightarrow Q = \epsilon \frac{U}{d} A$$

$$\Rightarrow C = \epsilon \frac{A}{d}$$

Johtavuus δ

$$\bar{j} = \delta \bar{E} \quad \leftarrow \text{OHMIN LAKI}$$

↑
 $\mu \rho \leftarrow \text{VARAUSTIHEYS}$
↑
LIIKKUVUUS

$$[\delta] = \frac{A/m^2}{V/m} = \frac{A}{Vm} = \frac{S}{m}$$

Rajapintaehdot:

Sähkövuon tiheyden normaalikomponentti jatkuva rajapinnan ylitse

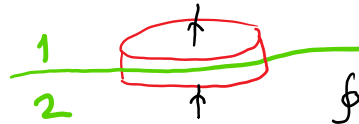
Sähkökentän voimakkuuden tangentialikomponentti jatkuva rajapinnan ylitse

(analogiset rajapintaehdot magneettikenttien puolella)

$$\begin{array}{l} \bar{n} \\ \epsilon_1 \uparrow \bar{E}_1 \quad \bar{D}_1 = \epsilon_1 \bar{E}_1 \\ \hline \epsilon_2 \quad \bar{E}_2 \quad \bar{D}_2 = \epsilon_2 \bar{E}_2 \end{array}$$

$$D_{n1} = D_{n2}$$

$$\bar{n} \cdot \bar{D}_1 = \bar{n} \cdot \bar{D}_2 \quad (\text{normaali-komponentti})$$



$$\oint \bar{D} \cdot d\bar{S} = 0$$

(ei varauksia rajapinnalla)

$$\bar{E}_{t1} = \bar{E}_{t2} \quad (\text{tangentialikomponentti})$$

$$\bar{n} \times \bar{E}_1 = \bar{n} \times \bar{E}_2$$