## ELEC-C8201 Control and Automation

## Exercise 4

1. Specify the total transfer function for the system given below. (The numerator and denominator of the transfer function are polynomials in $s$ )

2. For the system model given below, calculate output $y(t)$, when the reference is $r(t)=5.0 u_{s}(t)$ and the disturbance is $d(t)=5.0(\cos (t)) u_{s}(t)$. Note: $u_{s}\left(t-t_{0}\right)$ means a step function entering at time $t_{0}$.

3. Calculate the transfer function corresponding to the following state space model:

$$
\left\{\begin{array}{l}
\dot{\mathbf{x}}(t)=\left[\begin{array}{lll}
1 & 0 & 2 \\
1 & 1 & 0 \\
0 & 2 & 1
\end{array}\right] \mathbf{x}(t)+\left[\begin{array}{l}
1 \\
0 \\
0
\end{array}\right] u(t) \\
y(t)=\left[\begin{array}{lll}
1 & 0 & 0
\end{array}\right] \mathbf{x}(t)
\end{array}\right.
$$

4. Examine how many roots do the following polynomials have on the right half plane:
a. $s^{4}+6 s^{3}+13 s^{2}+12 s+4$
b. $2 s^{5}+s^{4}+3 s^{2}+s+2$
c. $s^{4}+2 s^{3}+4 s^{2}+8 s+10$
5. The process of the system below is unstable. Does this mean that the closed loop system is unstable?


## Tips:

Matrix A inverse:
First we obtain the components of the adjoint matrix (adjA) from the following expression:

$$
a_{i j}=(-1)^{i+j} \operatorname{det} A_{i j},
$$

where $\boldsymbol{A}_{i j}$ is the submatrix of $A$ obtained by removing line $i$ and column $j$ (Note in particular, the order of indexes).

Inverse of a matrix is obtained from its adjoint matrix by the following relation:

$$
A^{-1}=\frac{\operatorname{adj} A}{\operatorname{det} A} .
$$

## Laplace transform expressions:



## Laplace transformations and Time domain responses

| Laplace transformation | Time domain function |
| :---: | :---: |
| 1 | $\delta(t)$ |
| $1 / s$ | 1 |
| $1 / s^{2}$ | $t$ |
| $1 / s^{n+1}$ | $t^{n} / n!$ |
| $\frac{1}{s+a}$ | $e^{-a t}$ |
| $\frac{1}{(s+a)^{n+1}}$ | $\frac{t^{n} e^{-a t}}{n!}$ |
| $\frac{1}{s(s+a)}$ | $\frac{1}{a}\left(1-e^{-a t}\right)$ |
| $\frac{1}{(s+a)(s+b)}$ | $\frac{1}{a-b}\left(e^{-b t}-e^{-a t}\right)$ |
| $\frac{1}{s(s+a)(s+b)}$ | $\frac{1}{a b}+\frac{1}{a b(b-a)}\left(a e^{-b t}-b e^{-a t}\right)$ |
| $\frac{a}{s^{2}+a^{2}}$ | $\sin (a t)$ |
| $\frac{s}{s^{2}+a^{2}}$ | $\cos (a t)$ |
| $\frac{a}{(s+b)^{2}+a^{2}}$ | $e^{s+b}$ |
| $\frac{s+b)^{2}+a^{2}}{(s+a t}(a t)$ |  |
| $\frac{s+a}{s+b}$ | $\delta(t)+(a-b) e^{-b t}$ |

