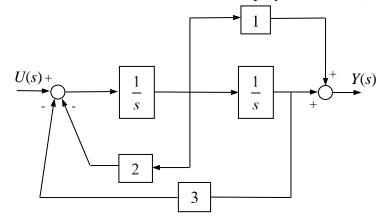
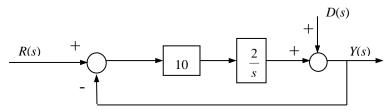
## **ELEC-C8201 Control and Automation** Exercise 4

**1.** Specify the total transfer function for the system given below. (The numerator and denominator of the transfer function are polynomials in *s*)



2. For the system model given below, calculate output y(t), when the reference is  $r(t) = 5.0u_s(t)$  and the disturbance is  $d(t) = 5.0(\cos(t))u_s(t)$ . Note:  $u_s(t-t_0)$  means a step function entering at time  $t_0$ .



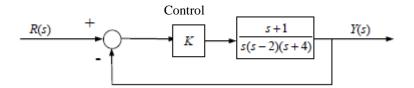
**3.** Calculate the transfer function corresponding to the following state space model:

 $\begin{cases} \mathbf{\dot{x}}(t) = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} u(t) \\ y(t) = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \mathbf{x}(t) \end{cases}$ 

**4.** Examine how many roots do the following polynomials have on the right half plane:

**a.** 
$$s^4 + 6s^3 + 13s^2 + 12s + 4$$
 **b.**  $2s^5 + s^4 + 3s^2 + s + 2$   
**c.**  $s^4 + 2s^3 + 4s^2 + 8s + 10$ 

5. The process of the system below is unstable. Does this mean that the closed loop system is unstable?



## **Tips:**

Matrix A inverse:

First we obtain the components of the adjoint matrix (adjA) from the following expression:

$$a_{ij} = \left(-1\right)^{i+j} \det A_{ij} ,$$

where  $A_{ij}$  is the submatrix of A obtained by removing line *i* and column *j* (Note in particular, the order of indexes).

Inverse of a matrix is obtained from its adjoint matrix by the following relation:

$$A^{-1} = \frac{adjA}{\det A} \, .$$

| Laplace transform expressions | Laplace | transform | expressions: |
|-------------------------------|---------|-----------|--------------|
|-------------------------------|---------|-----------|--------------|

|  | Time domain function  |
|--|---|
| F(s)   | f(t)  |
| $C_1F_2(s) + C_2F_2(s)$  | $C_1f_2(t) + C_2f_2(t)$                                     |
| F(s+a)   | $e^{-at}f(t)$   |
| $e^{-as}F(s)$  | $\begin{cases} 0, & t \le a \\ f(t-a), & t > a \end{cases}$ |
| $\frac{1}{a}F\left(\frac{s}{a}\right)$                         | f(at)   |
| $F_1(s)F_2(s)$   | $\int_{0}^{t} f_{1}(\tau) f_{2}(t-\tau) d\tau$ $f'(t)$      |
| sF(s)-f(0)   | f'(t)   |
| ${}^{n}F(s) - \left[s^{n-1}f(0) + \dots + f^{(n-1)}(0)\right]$ | $f^{(n)}(t)$  |

| Laplace transformation             | Time domain function  |
|------------------------------------|---|
| 1                                  | $\delta(t)$   |
| 1 / <i>s</i>                       | 1   |
| $1 / s^2$                          | t   |
| $1 / s^{n+1}$                      | $t^n / n!$  |
| _1                                 | $e^{-at}$   |
| $\overline{s+a}$                   |   |
| 1                                  | $t^n e^{-at}$   |
| $\overline{(s+a)^{n+1}}$           | <u></u> <u>n!</u>   |
| 1                                  | $\frac{1}{a}(1-e^{-at})$  |
| $\overline{s(s+a)}$                | $\frac{-(1-e)}{a}$  |
| 1                                  | $\frac{1}{a-b}\left(e^{-bt}-e^{-at}\right)$                           |
| $\overline{(s+a)(s+b)}$            | $\frac{1}{a-b}(e^{-e})$   |
| 1                                  | $1$ $1$ $\begin{pmatrix} -bt & -at \end{pmatrix}$                     |
| $\overline{s(s+a)(s+b)}$           | $\frac{1}{ab} + \frac{1}{ab(b-a)} \left( ae^{-bt} - be^{-at} \right)$ |
| a                                  | sin(at)   |
| $\frac{a}{s^2 + a^2}$              |   |
| $\frac{s}{s^2 + a^2}$              | $\cos(at)$  |
|                                    |   |
| $\frac{a}{\left(s+b\right)^2+a^2}$ | $e^{-bt}\sin(at)$   |
| $(s+b)^2 + a^2$                    |   |
| <u>s+b</u>                         | $e^{-bt}\cos(at)$   |
| $\overline{(s+b)^2+a^2}$           |   |
| s + a                              | $\delta(t)+(a-b)e^{-bt}$  |
| $\overline{s+b}$                   |   |

Laplace transformations and Time domain responses