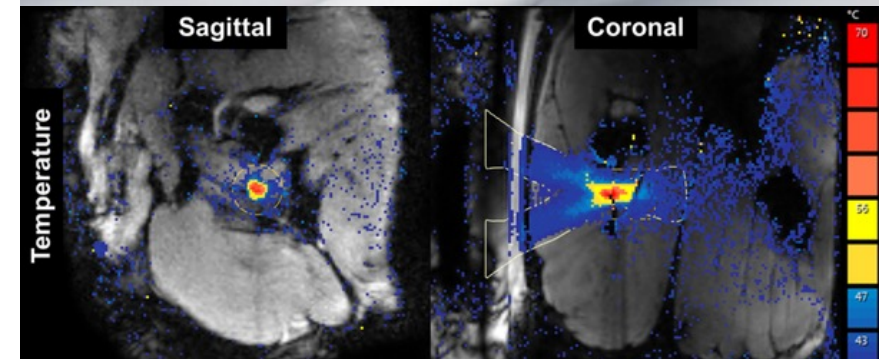
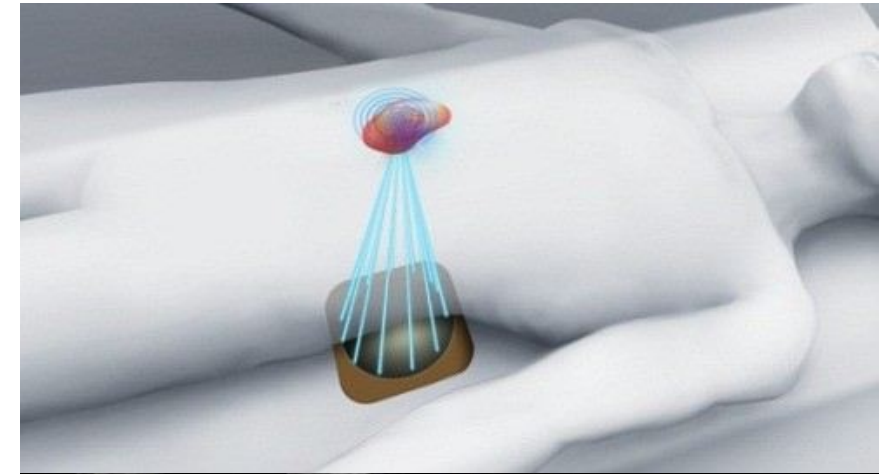
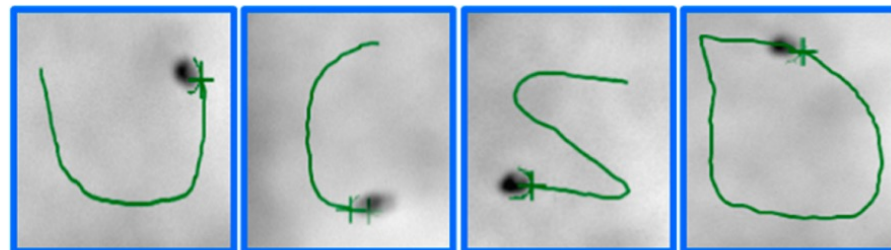
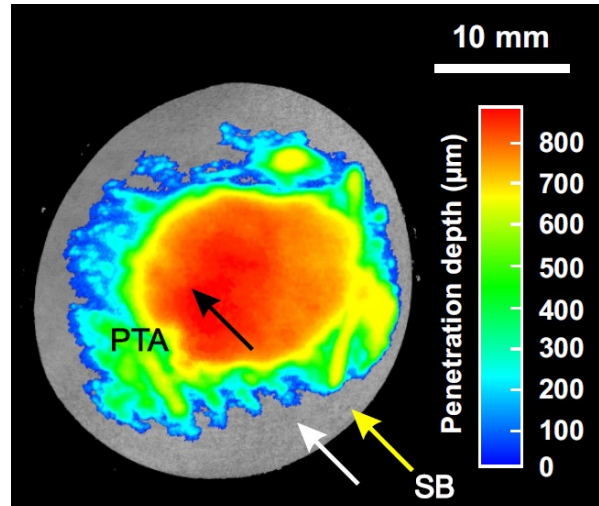


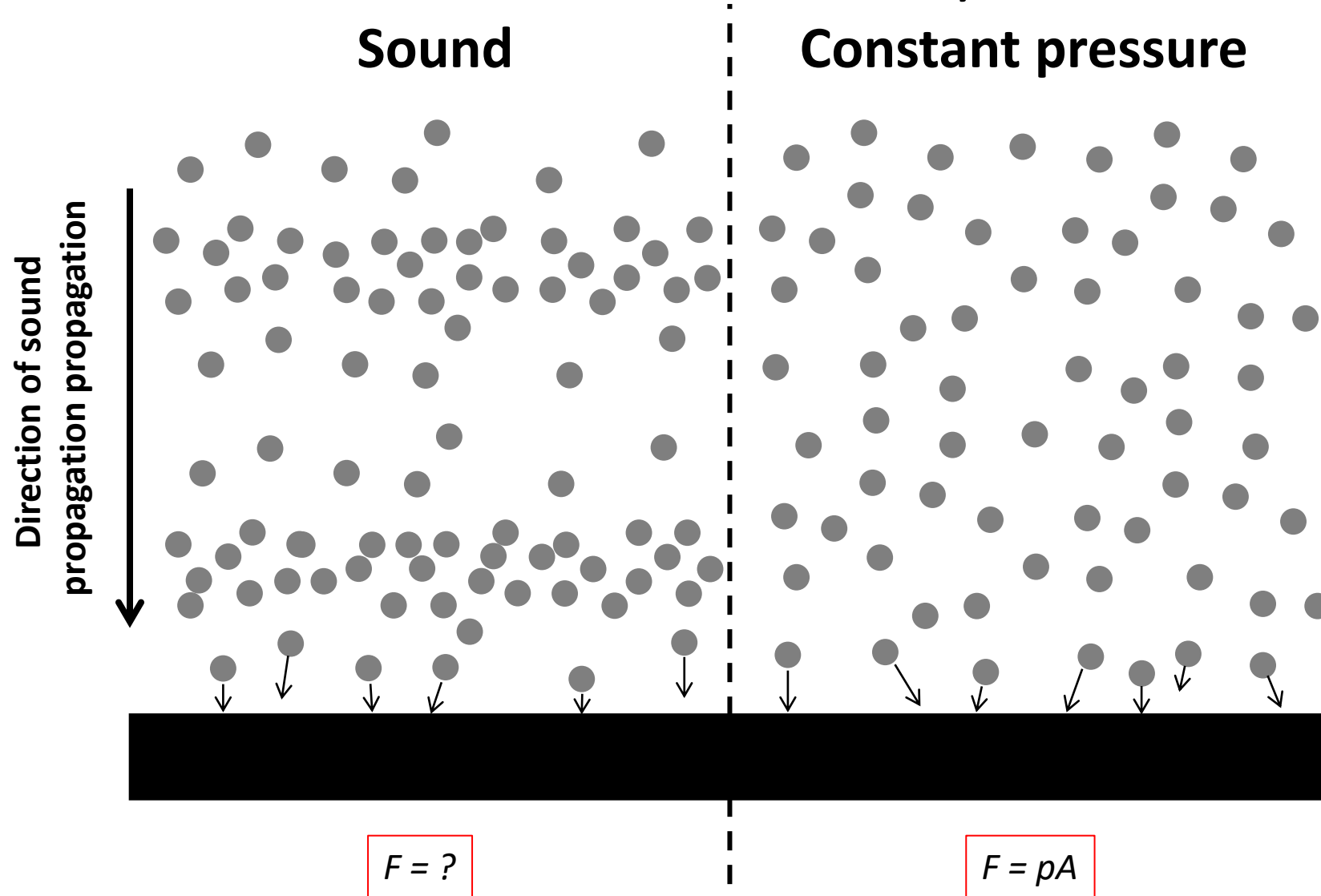
Biomedical Ultrasonics, 5 cr

Heikki Nieminen

13.9.-17.12.2023



Particle motion at a boundary



General presentation of acoustic radiation force

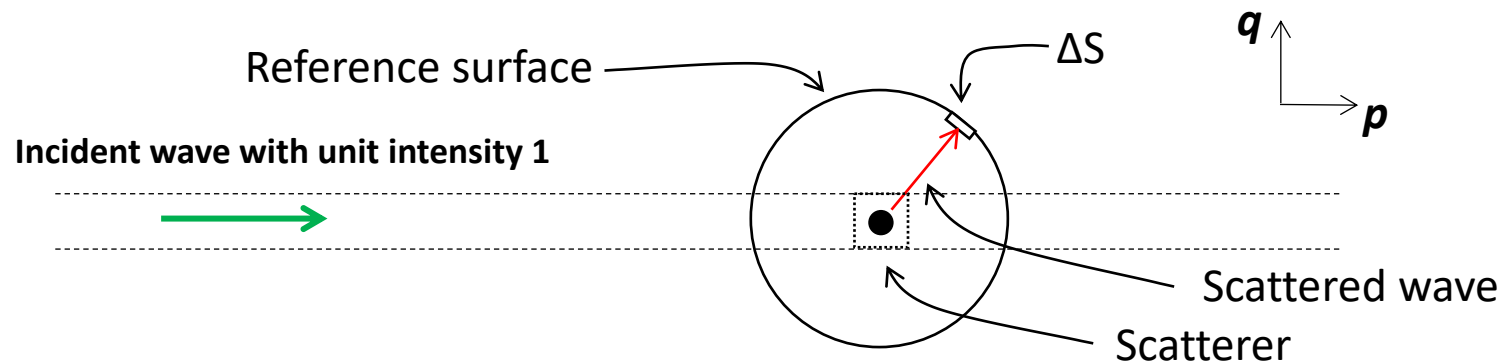
- Langevin radiation pressure, P_{Lan} , is defined as the energy density (time average over one cycle, sinusoidal wave)

$$P_{\text{Lan}} = \langle E \rangle_T = \hat{p}^2 / 2\rho_0 c^2$$

- The radiation force is a **vector quantity** and can be defined from the energy density as follows:

$$\mathbf{F} = \mathbf{d}_r \langle E \rangle_T S$$

where \mathbf{d}_r is a *drag coefficient* vector containing two perpendicular unit vectors \mathbf{p} and \mathbf{q} in a 2D simplification.



Drag coefficient

- In 2D the drag coefficient can be written as

$$\mathbf{d}_r = \frac{\mathbf{p}}{S} \left(\underbrace{\Pi_a}_{\text{Absorbed power}} + \underbrace{\Pi_s}_{\text{Total scattered power}} - \underbrace{\Delta S \sum_i \gamma_i \cos \theta_i}_{\text{Scattered intensity at surface element } \Delta S} \right) - \frac{\mathbf{q}}{S} \left(\Delta S \sum_i \gamma_i \sin \theta_i \right)$$

Unit projected area

Incident wave with unit intensity 1

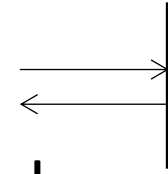
ΔS

θ_i

\mathbf{q}

\mathbf{p}

Perfect reflection, no absorption

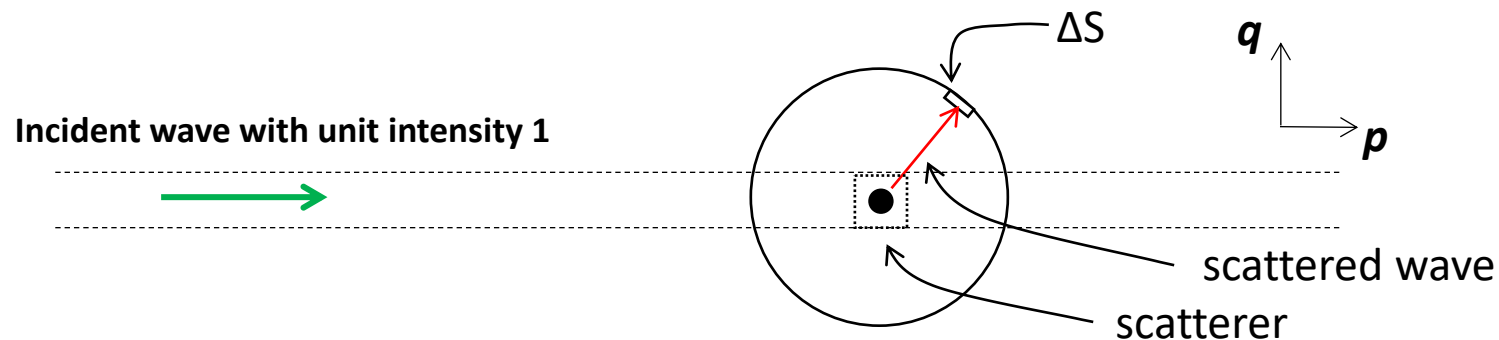


- E.g. wave meets a fluid-air interface at normal angle

$$\mathbf{d}_r = \frac{\mathbf{p}}{S} \left(\underbrace{\Pi_a + \Pi_s}_{=0} - \underbrace{\Delta S \sum_i \gamma_i \cos \theta_i}_{=-\Pi_s} \right) - \frac{\mathbf{q}}{S} \left(\underbrace{\Delta S \sum_i \gamma_i \sin \theta_i}_{=0} \right)$$

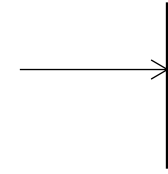
$$\underbrace{\hspace{10em}}_{=2\Pi_s}$$

$$d_r = |\mathbf{d}_r| = 2\Pi_s = 2 \text{ (in } p \text{ - direction)} \Rightarrow F = 2 \langle E \rangle_T S$$



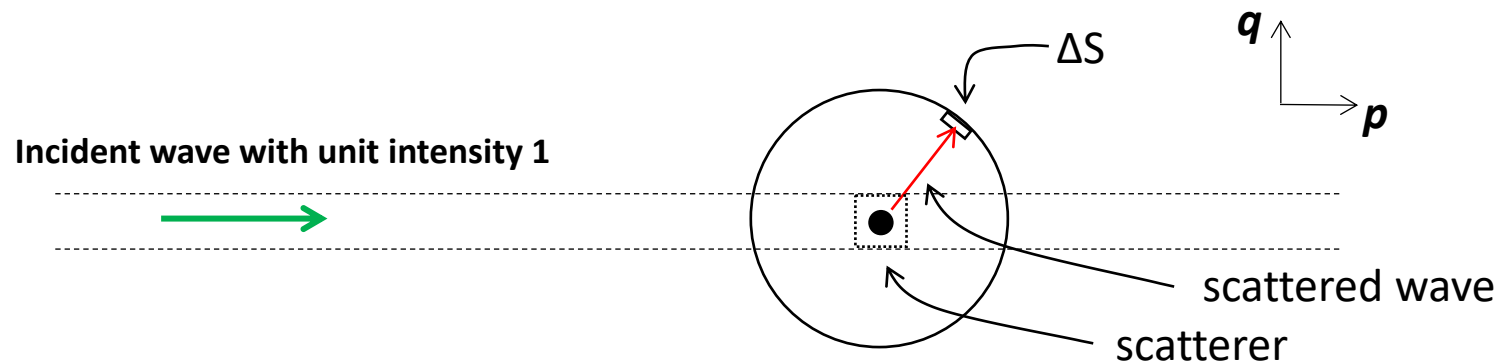
Perfect absorption, no reflection

- E.g. wave meets an oily target

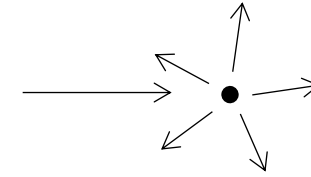


$$\mathbf{d}_r = \frac{\mathbf{p}}{S} \left(\underbrace{\Pi_a}_{=1} + \underbrace{\Pi_s}_{=0} - \underbrace{\Delta S \sum_i \gamma_i \cos \theta_i}_{=0} \right) - \frac{\mathbf{q}}{S} \left(\underbrace{\Delta S \sum_i \gamma_i \sin \theta_i}_{=0} \right)$$

$$d_r = |\mathbf{d}_r| = \Pi_a = 1 \text{ (in } p \text{ - direction)} \Rightarrow F = \langle E \rangle_T S$$



Rayleigh scatterer

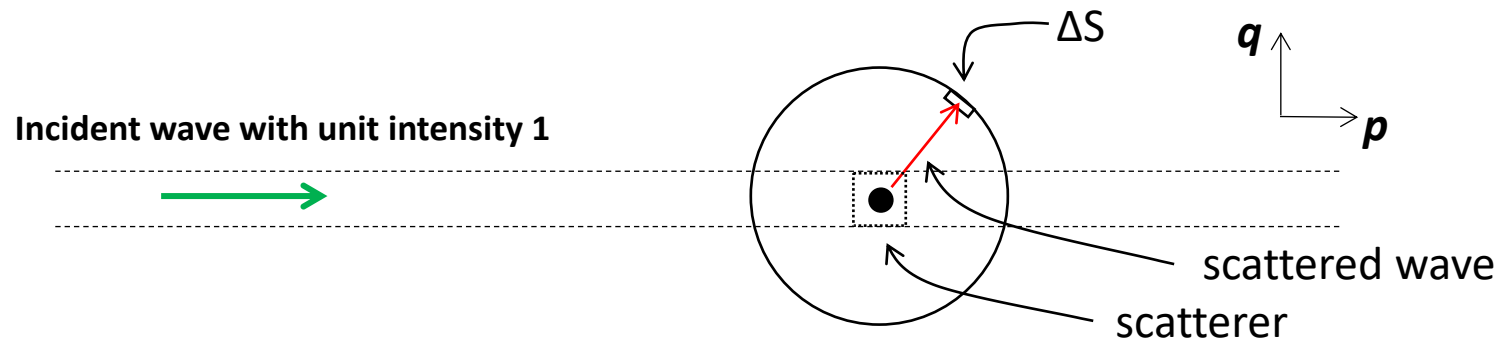


- Scatterer smaller than the wavelength:

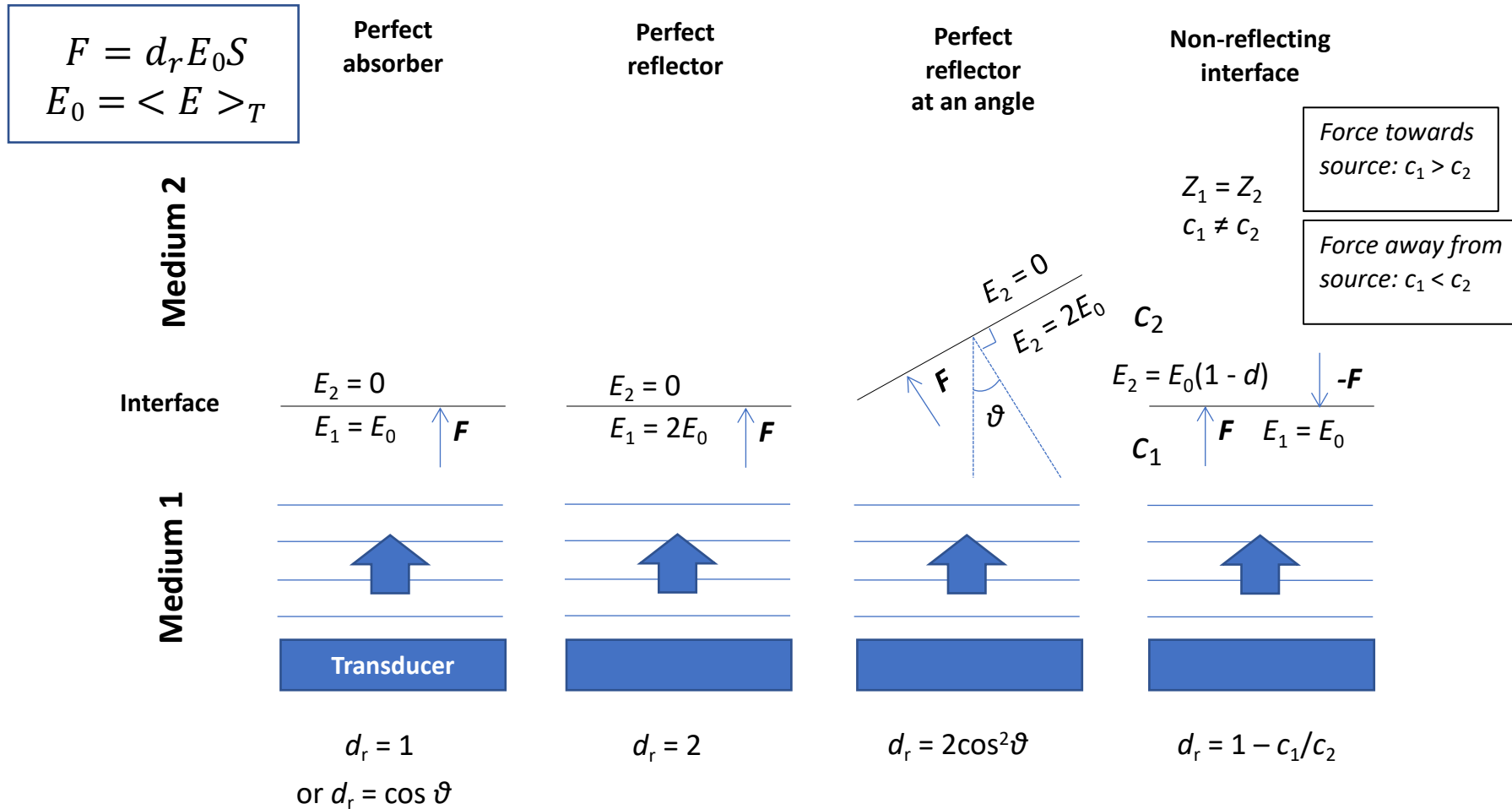
$$\mathbf{d}_r = \frac{\mathbf{p}}{S} \left(\Pi_a + \Pi_s - \underbrace{\Delta S \sum_i \gamma_i \cos \theta_i}_{=0} \right) - \frac{\mathbf{q}}{S} \left(\underbrace{\Delta S \sum_i \gamma_i \sin \theta_i}_{=0} \right)$$

$$\mathbf{d}_r = \frac{\mathbf{p}}{S} (\Pi_a + \Pi_s) \implies \text{In tissue the scattering component is small and usually can be neglected}$$

$$d_r = |\mathbf{d}_r| = \Pi_a + \Pi_s \approx \Pi_a \text{ (in } \mathbf{p} \text{ - direction)} \Rightarrow F \approx \langle E \rangle_T S \text{ (if perfect absorber)}$$

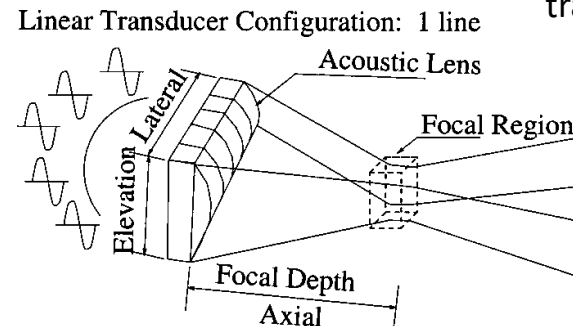
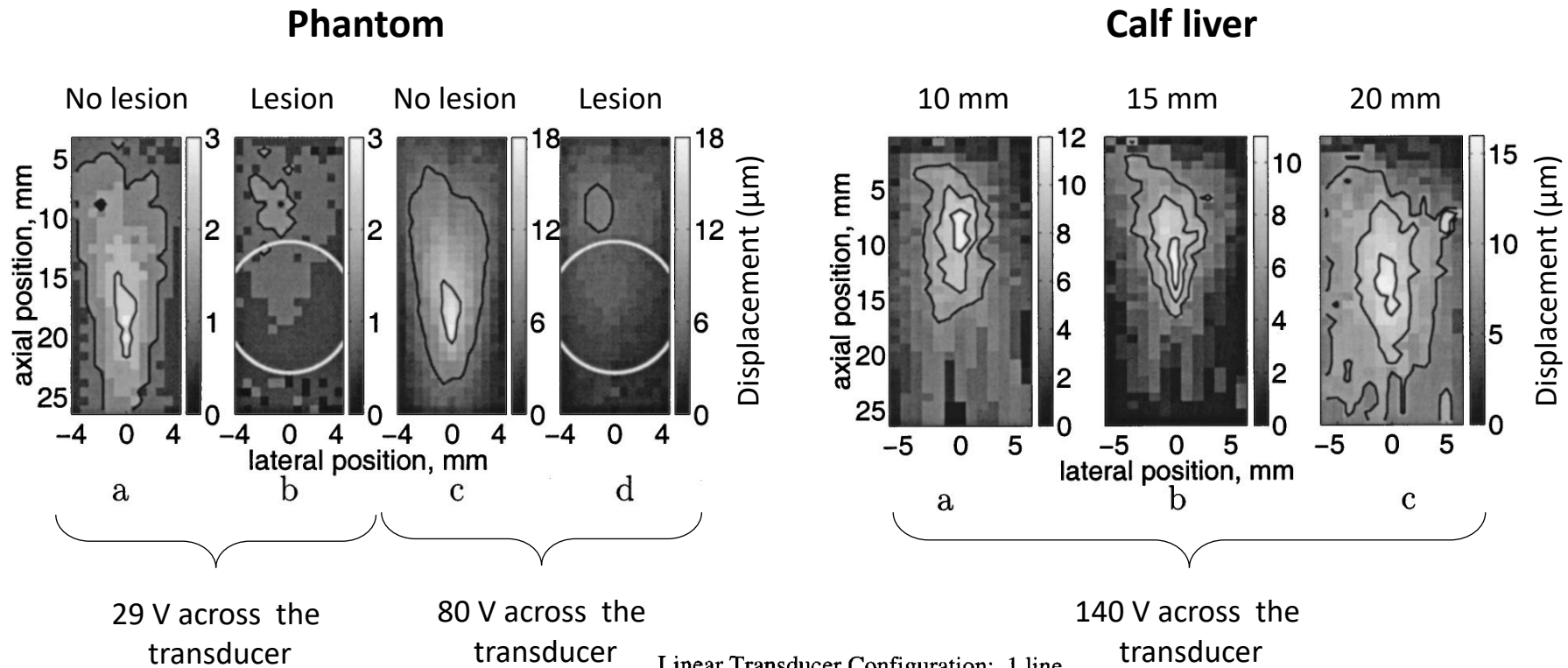


Acoustic radiation force at a boundary: different cases



Radiation force
(travelling longitudinal wave)
Real-life examples

Acoustic radiation force in attenuating medium: *remote palpation*

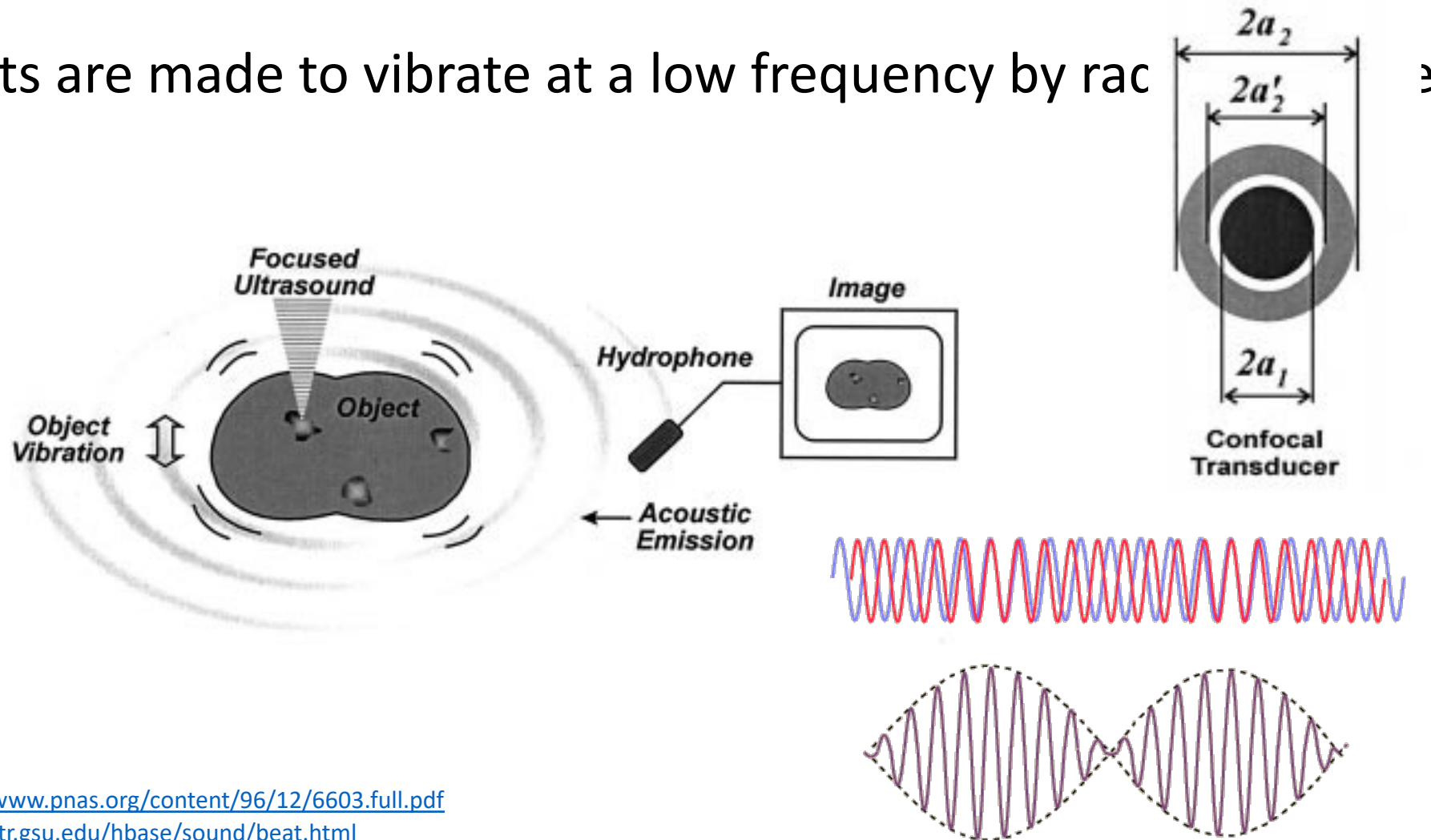


$$f = 7.2 \text{ MHz}$$

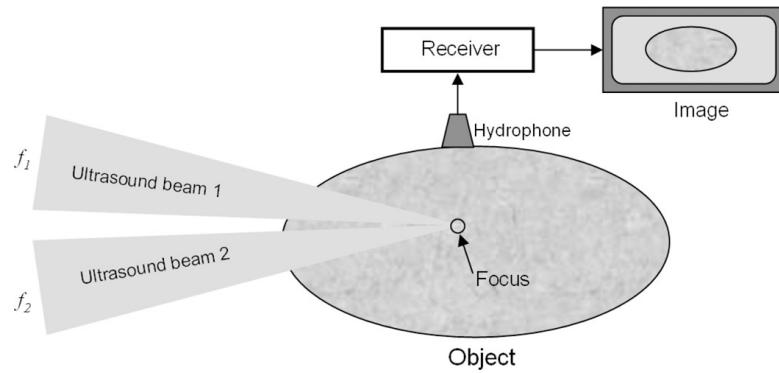
$$I_{\text{sptp}} = 2.4 - 140 \text{ W/cm}^2$$

Ultrasound vibro-acoustography (USVA)

- Objects are made to vibrate at a low frequency by receiving



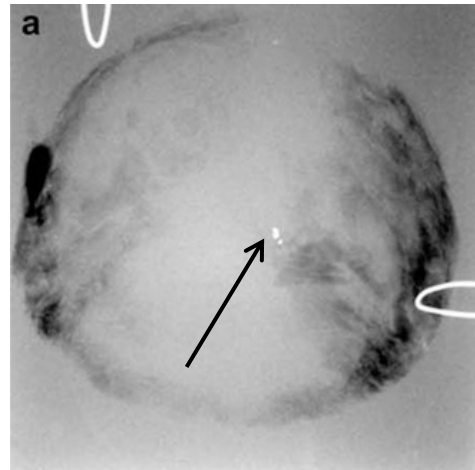
Ultrasound vibro-acoustography (USVA)



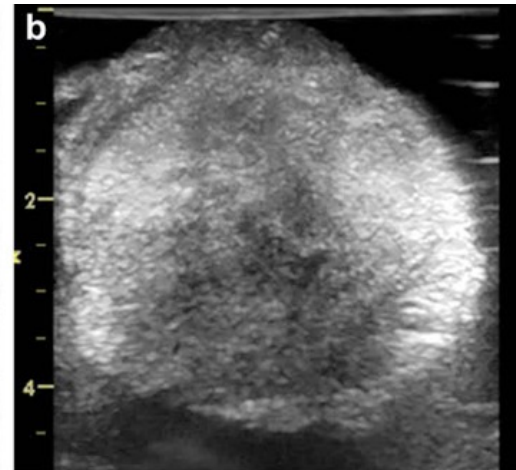
Two frequencies in MHz range
produces a beat frequency at kHz range

Human prostate with a localized miniature calcification

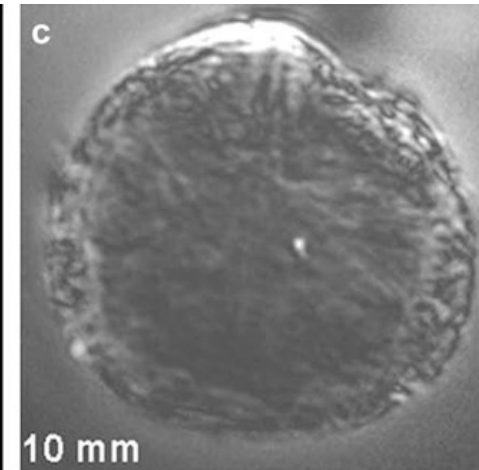
X-ray



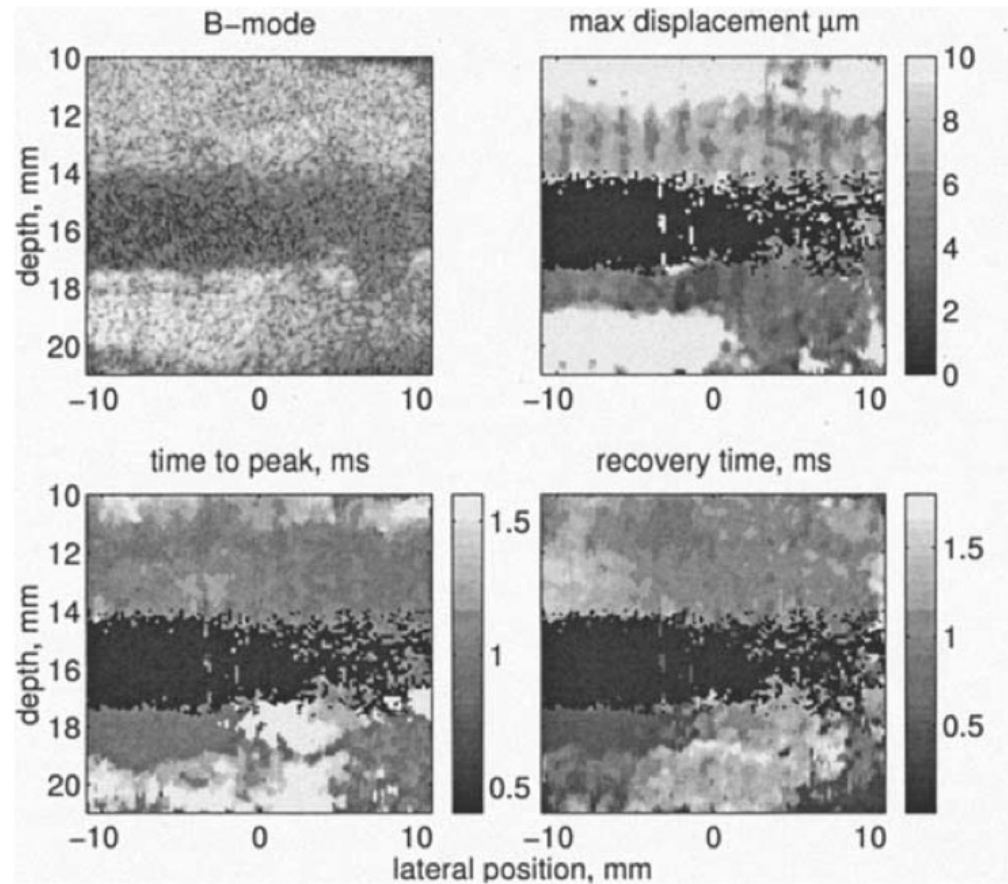
US (B-mode)



USVA



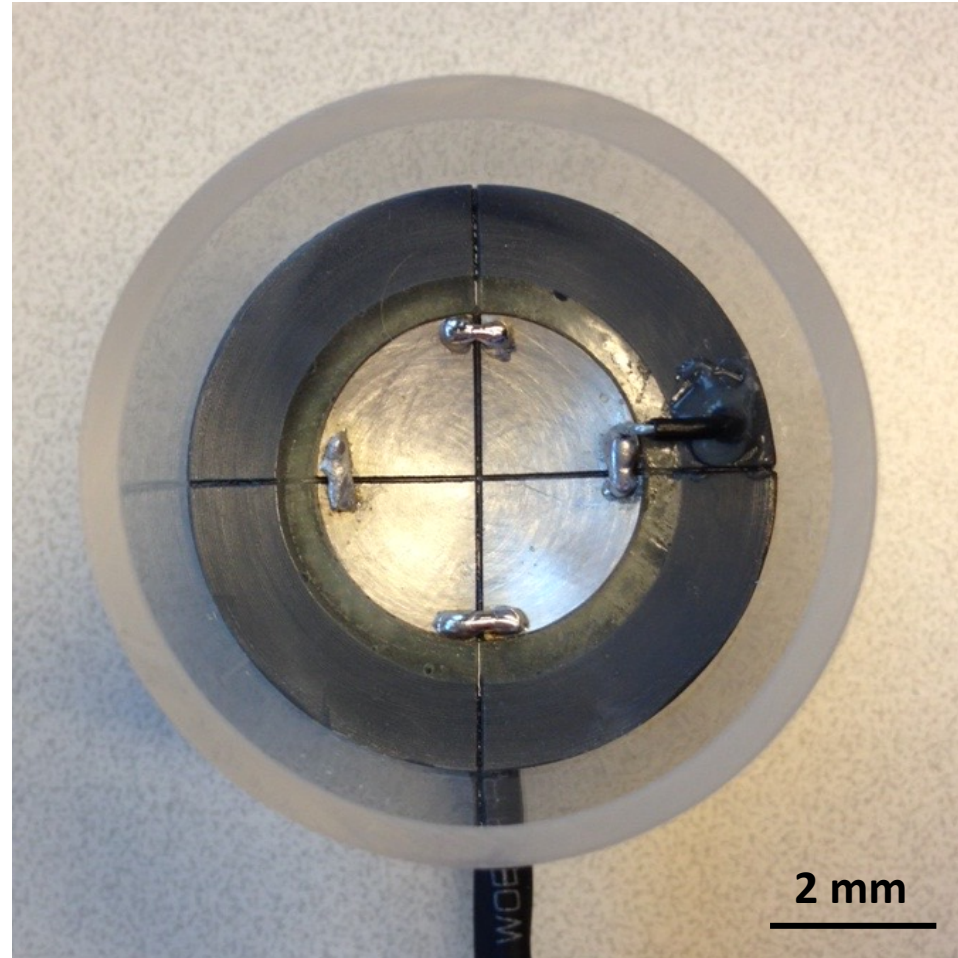
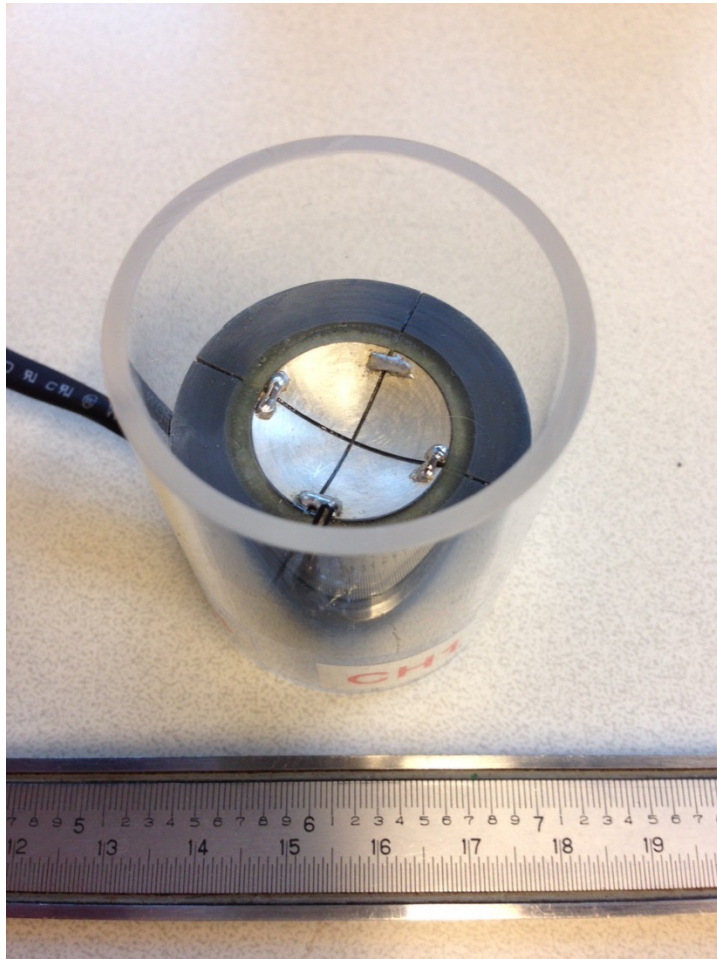
ARFI imaging (stiffening in vessel)



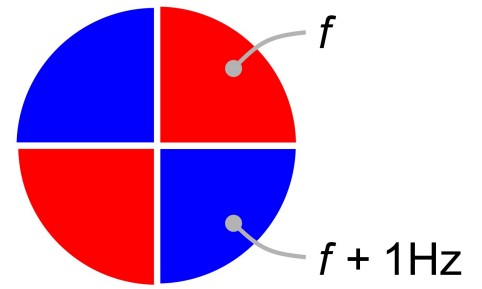
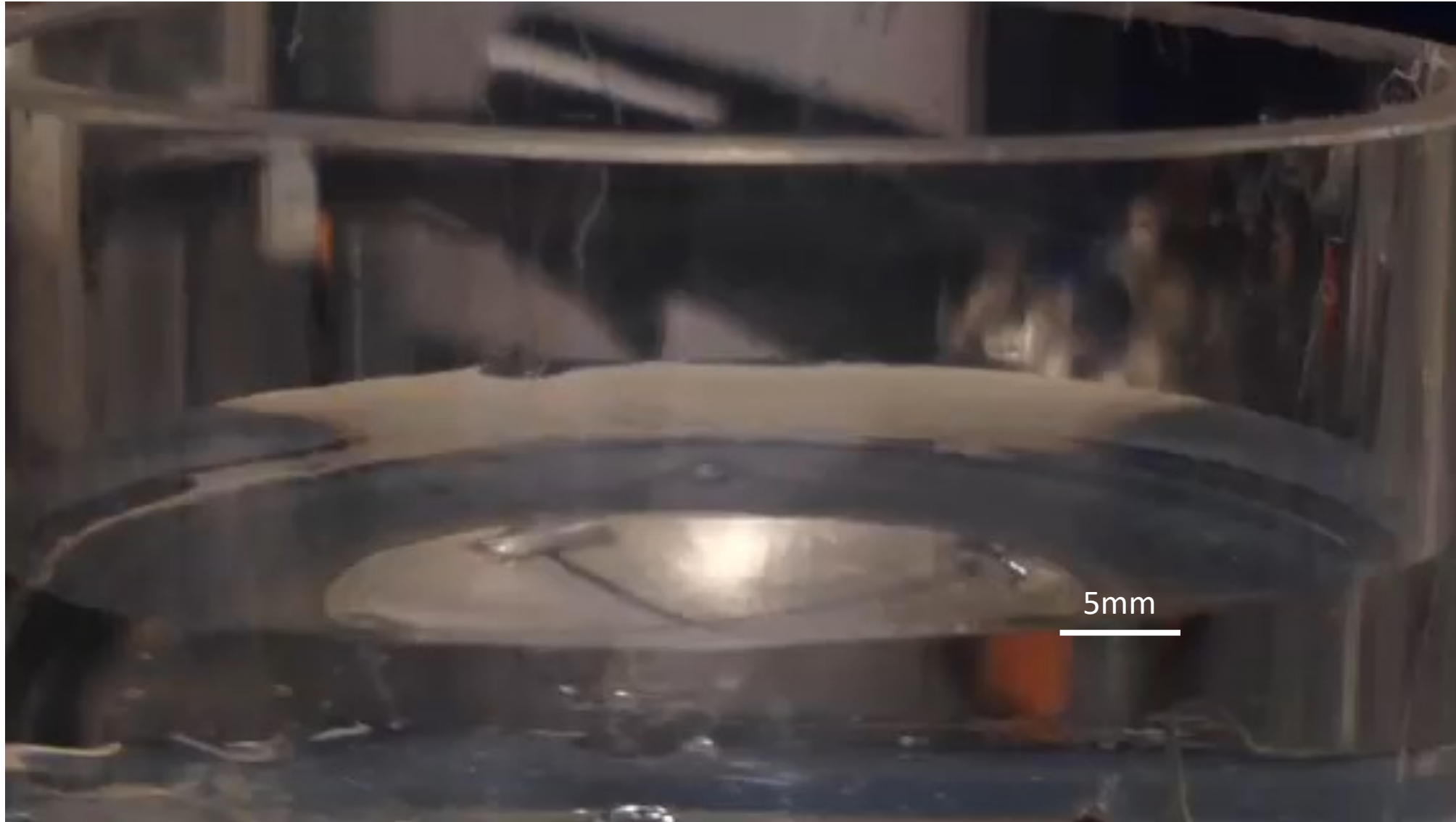
Human *ex vivo* vessel

What do you see in the images?

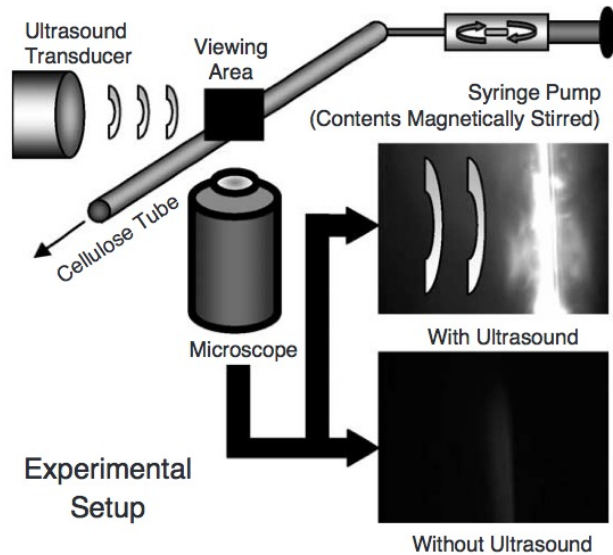
Sonic screwdriver / confocal transducer



Confocal transducer in action



Radiation force –based drug release of nanoparticles from lipid micro-bubbles



Step 1: 1.3-s radiation force pulse at 3 MHz, 150 kPa PNP

Step 2: 5-cycle fragmentation pulse at 1.5 MHz and 1.1 MPa PNP

Fluorescent Nanoparticles (20 or 400 nm) loaded on a lipid-shelle micro-bubble

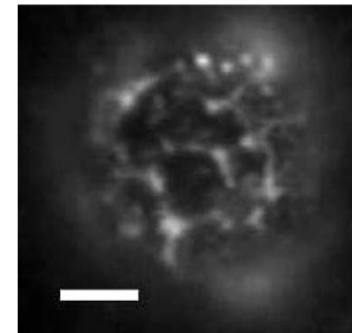
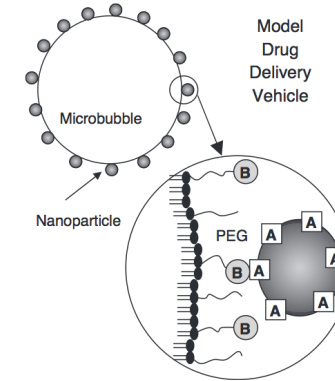
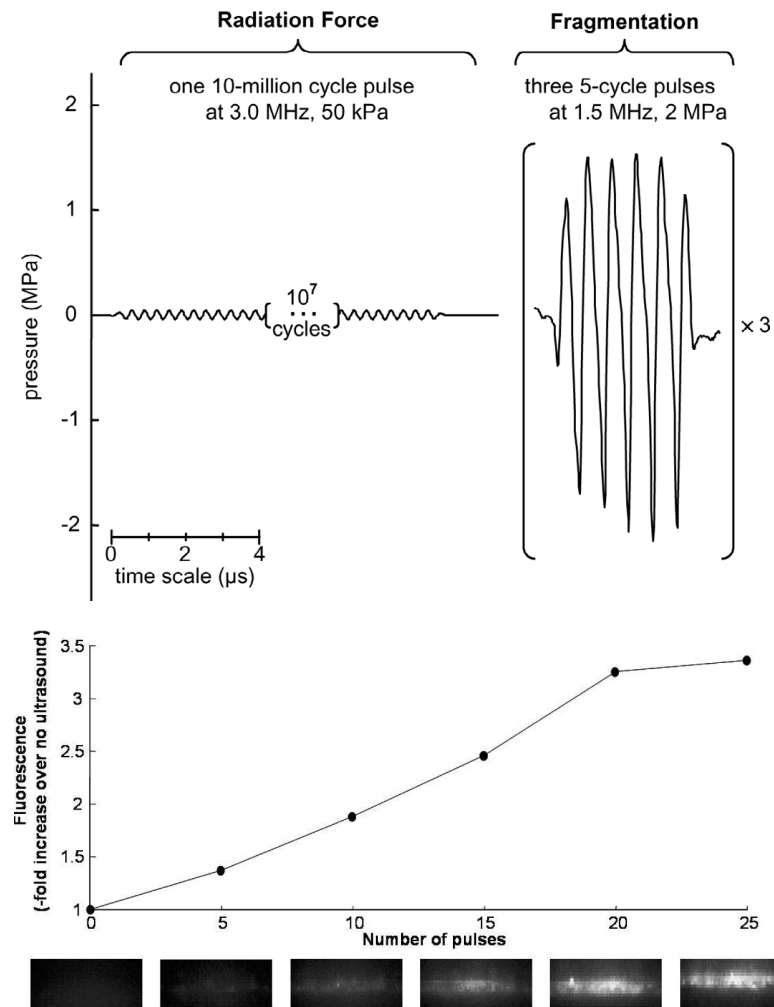
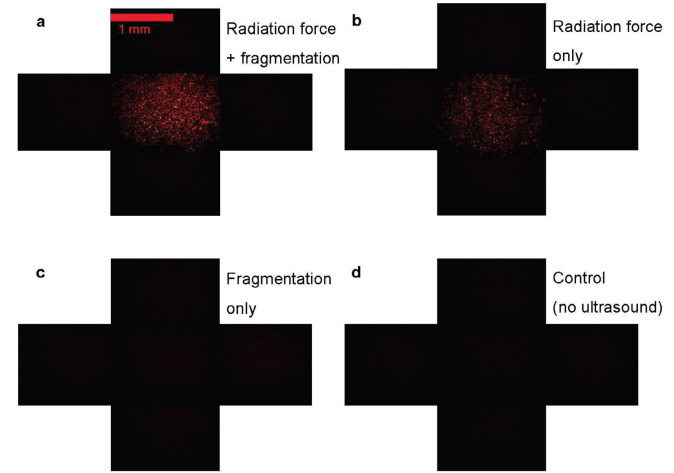


Fig. 3. Nanobead distribution on the surface of the vehicles. Vehicles were created as described in Materials and methods. A sample of the vehicle solution was observed on a 100 \times water immersion objective. The fluorescence within the image is yellow-green fluorescence emitted by the nanobeads bound to the microbubble surface. The scale bar corresponds to 5 μ m in length.

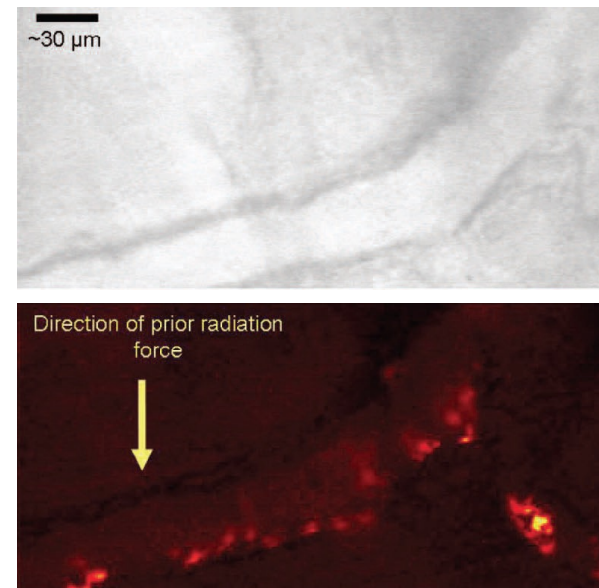
Radiation force –based drug release of agent from lipid micro-bubbles



Delivery on cell plate

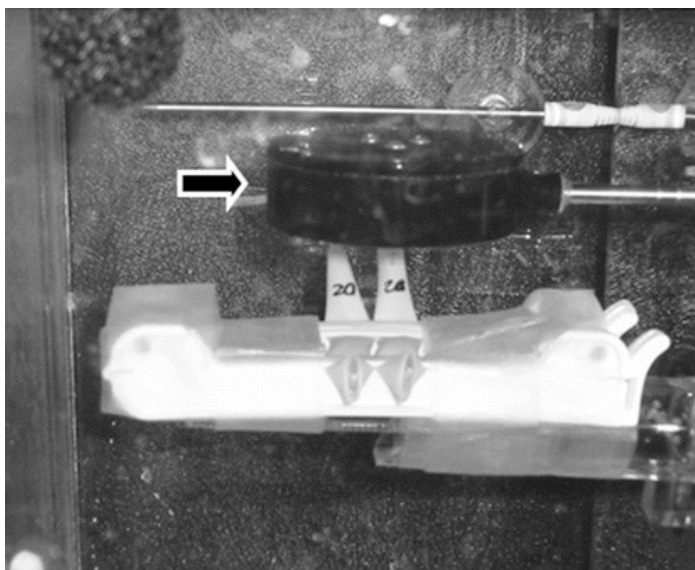
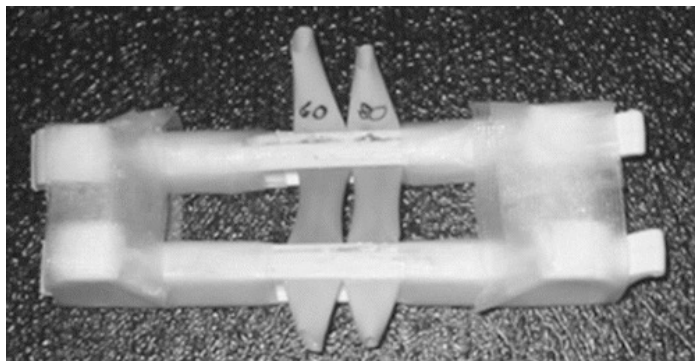


Delivery on mouse mouse vessel wall



Radiation force –induced thrombolysis

Blood clots in latex tubes



Goal: to improve tissue plasminogen activator (tPA)-mediated thrombolysis

Focus width (-3 dB) 1.38 mm, axial length (-3 dB) 7.2 mm.

100 ms bursts

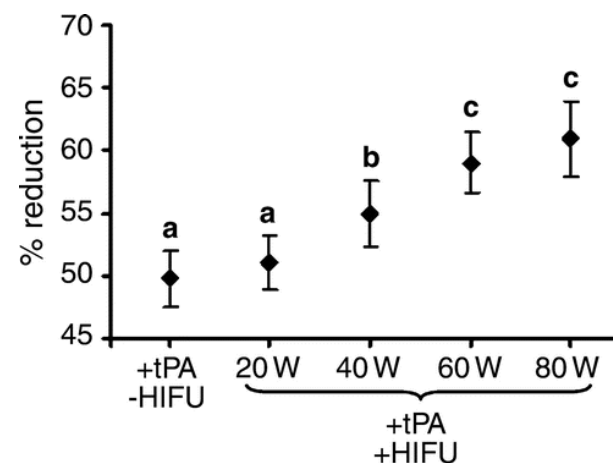
1 MHz pulses

10% duty cycle (100 msec/1000 msec)

PRF 1 Hz

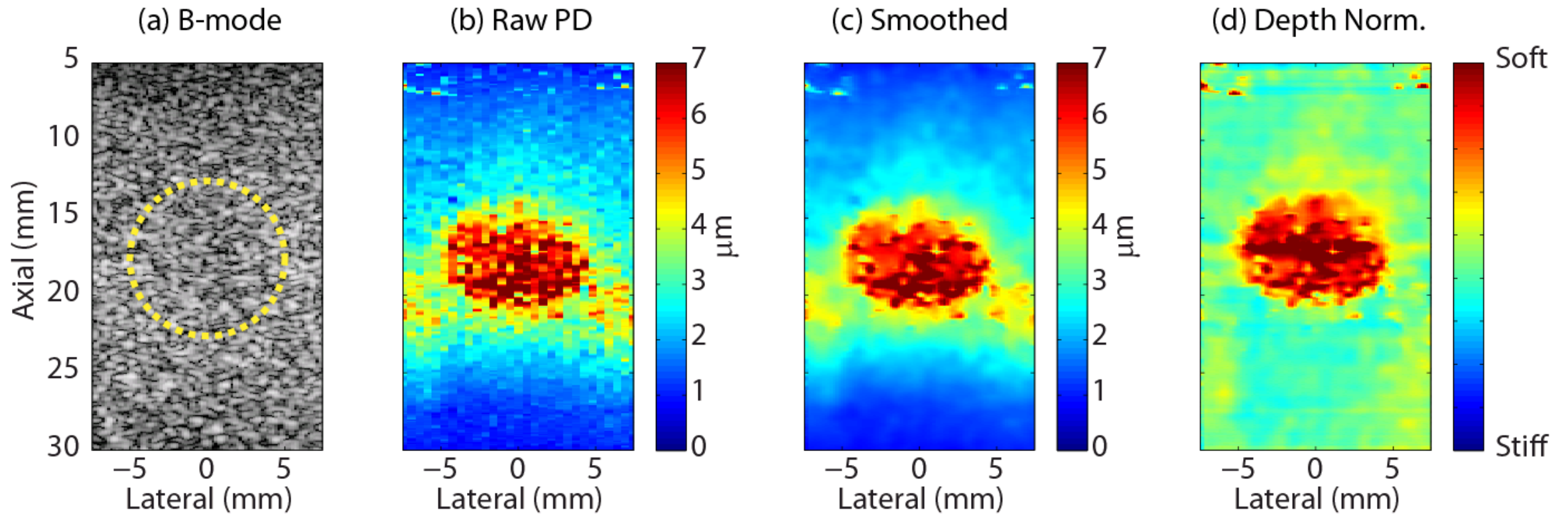
TAP (W)	Peak Axial Displacement (μm)
20	12.5
40	27.4
60	44.8
80	59.1

TAP = total acoustic power



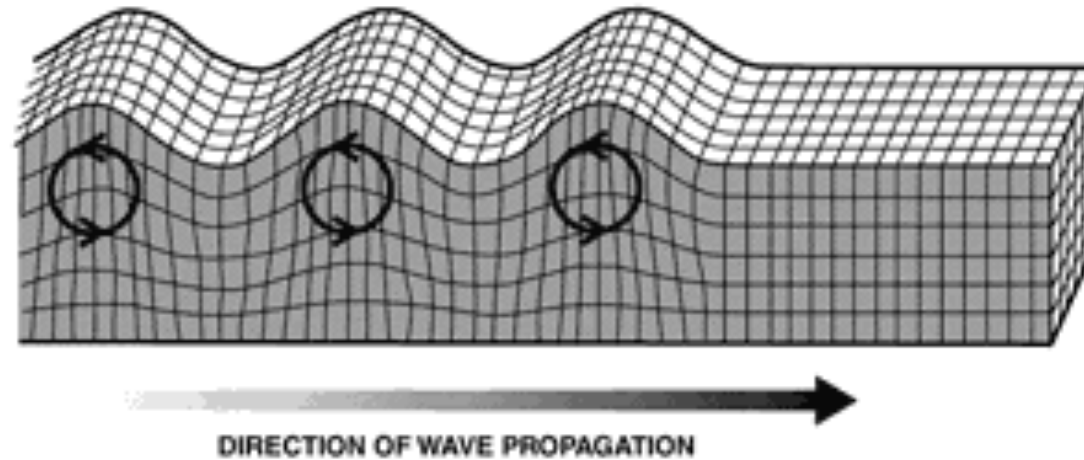
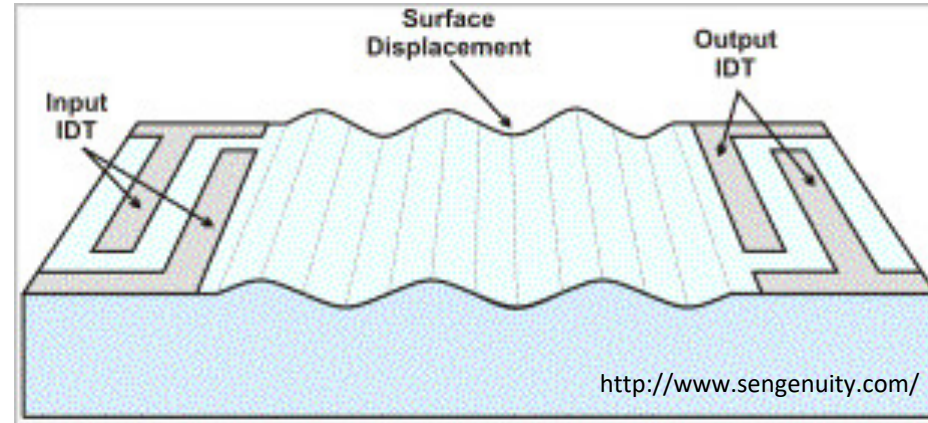
Widening of inter-cellular spacing resulting from acoustic radiation forces may enhance drug penetration

Acoustic radiation force impulse imaging

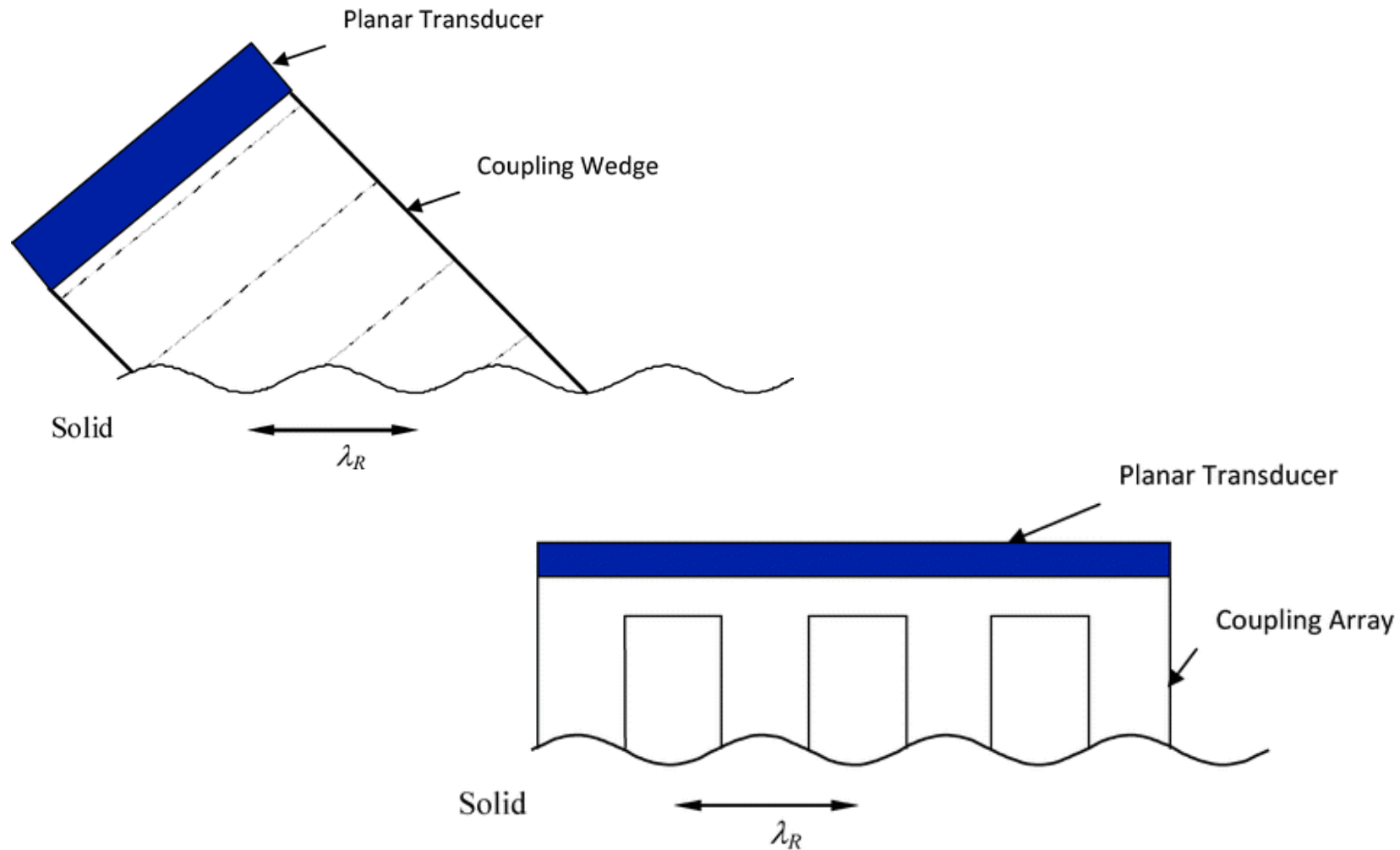


Radiation force
(travelling SAW)

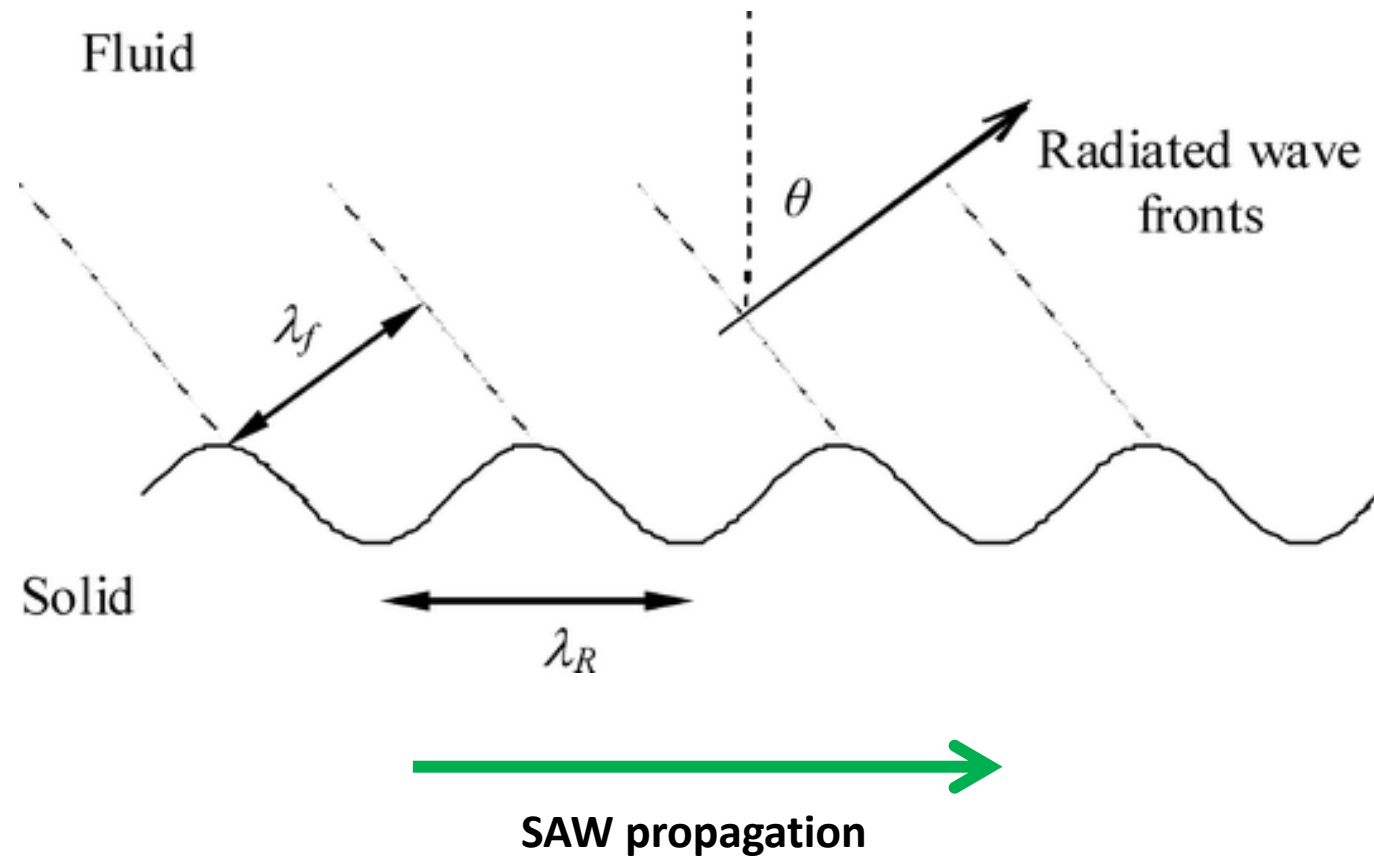
Schematic of SAW transducer



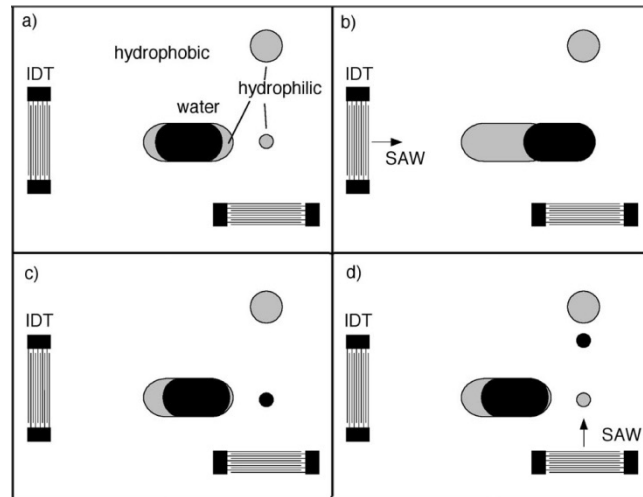
Other ways to generate SAWs



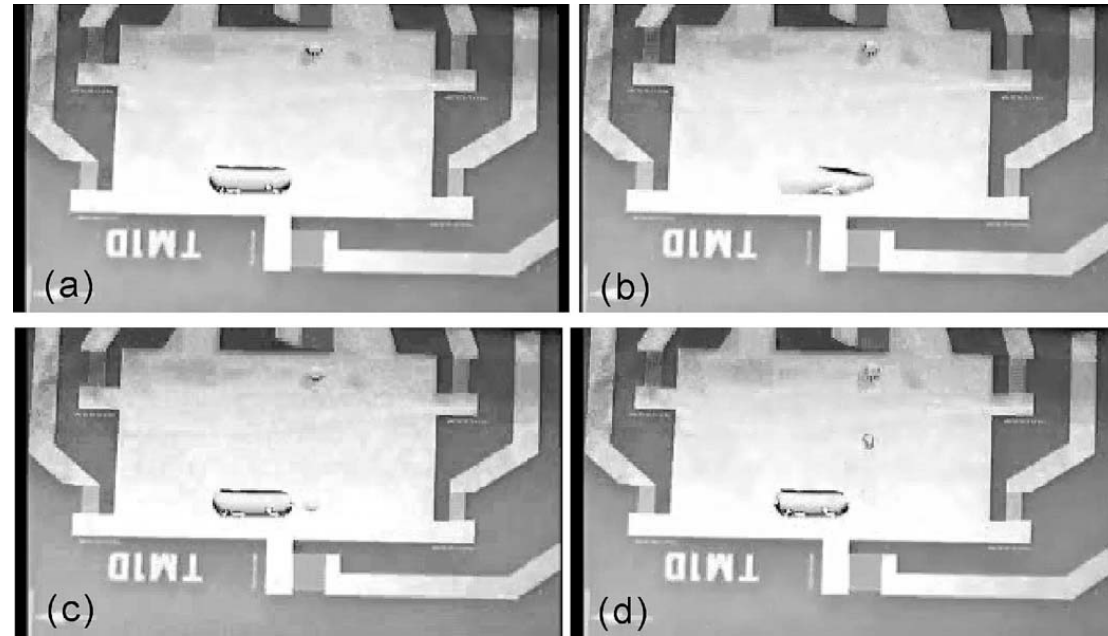
Leaky SAW



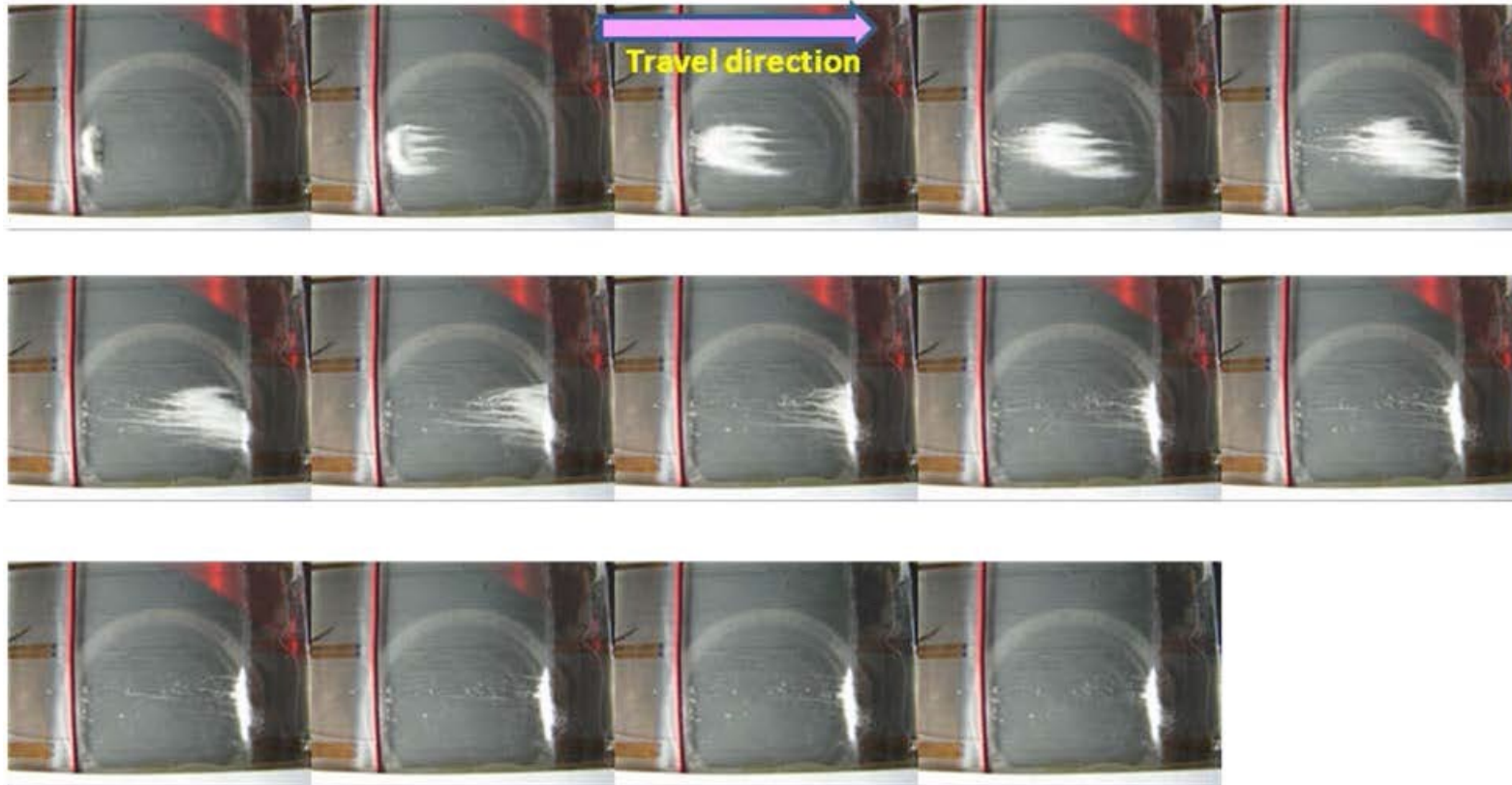
Ultrasonic "pinball": SAW drive-in



Sketch of the SAW-driven passive dispenser and time sequence of the dispensing process as explained in the text. In (a), the IDT on the left is activated to push the reservoir droplet towards the hydrophilic anchor. In (b), the hydrophilic anchor is wetted by the reservoir. In (c), switching off the SAW retracts the reservoir droplet leaving a small droplet at the anchor site. In (d), a second SAW is used to push the dispensed droplet toward a container anchor (larger gray area to the upper right).



Powder transportation



Transportation of Al₂O₃ particles (~50 μ m size particles). Translation speed 60-180 mm/s (30 fps)

Sand-water mixture transportation

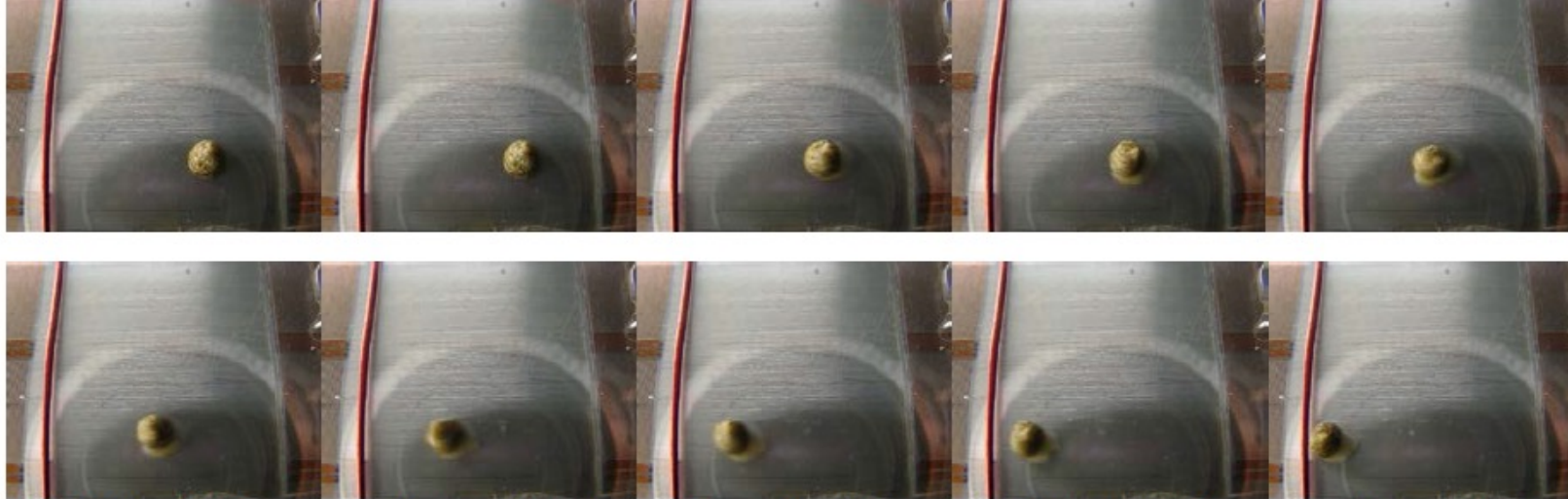
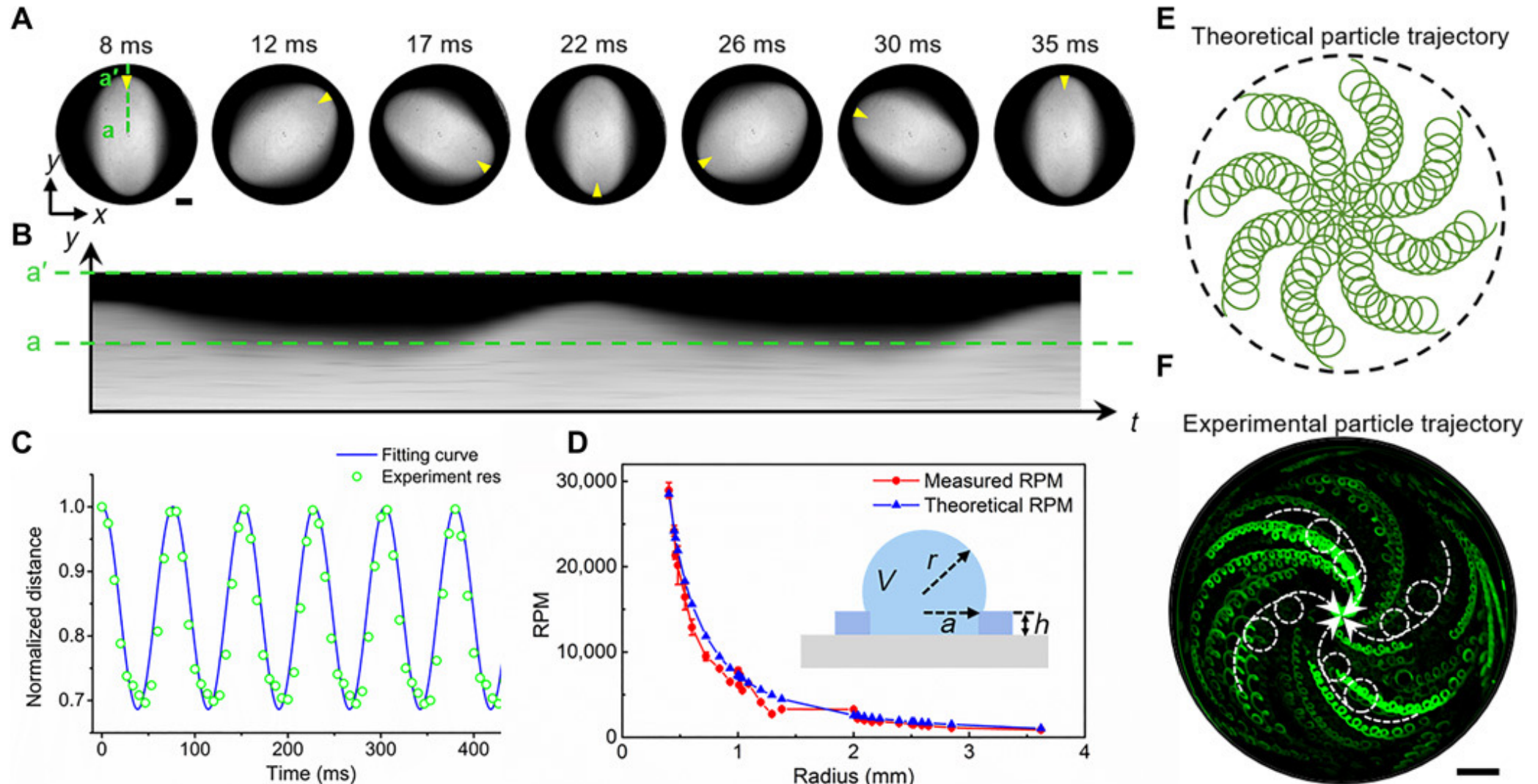
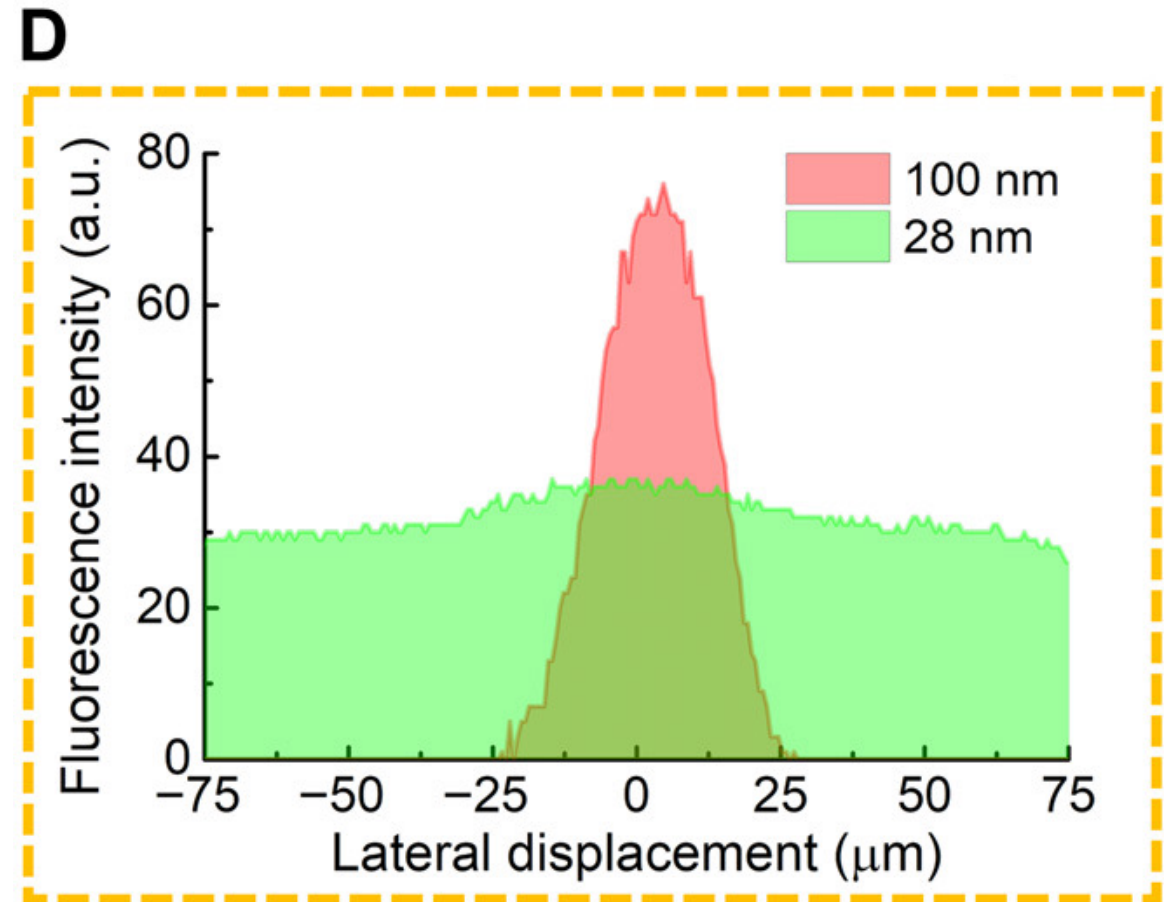
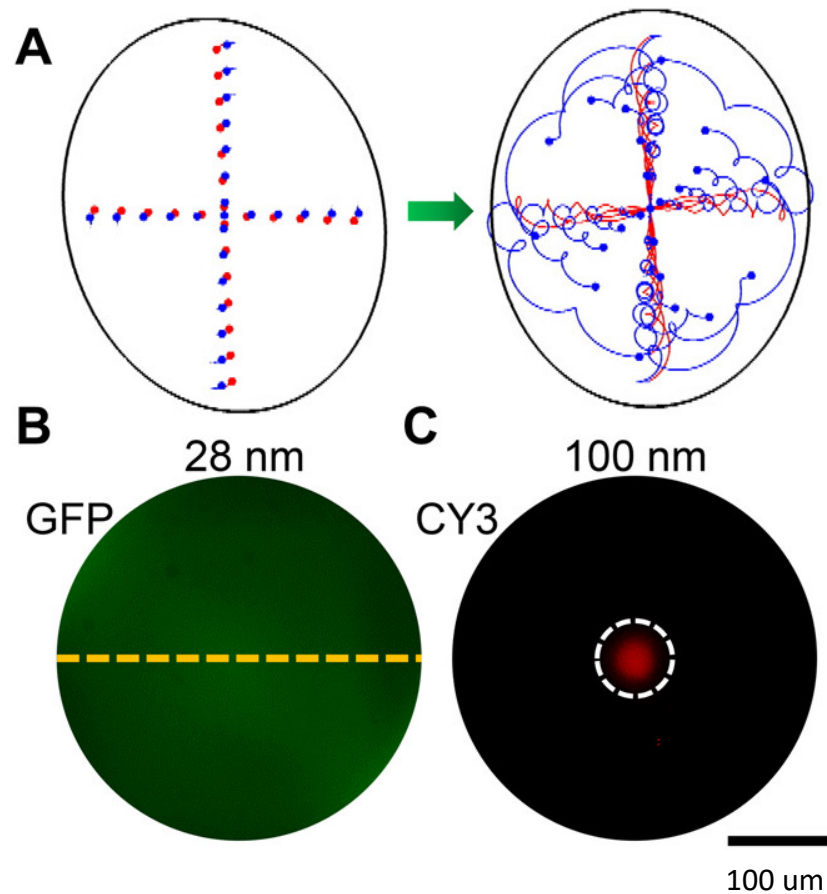


FIGURE 10: Sequence frames from the video of sand-water mixture traveling along the propagating direction of the SAW (from right to left). The frame rate is 30 f/s. The distance between the opposite IDT electrodes is 25 mm.

Acoustic micro-centrifuge



Acoustic micro-centrifuge



Feedback on this session

<https://presemo.aalto.fi/bmus>

