



Variational calculation

General problem: find a function, $y(x)$ say, for which
a functional

$$I = \int_{x_1}^{x_2} \phi(y(x), y'(x), x) dx$$

is an extremum (often minimum)

what does this imply? Let $y(x)$ be the optimal choice and neighboring one is

$$Y(x) = y(x) + \varepsilon \eta(x) \quad (\varepsilon \text{ is small})$$

we keep end points fixed so $\eta(x_1) = \eta(x_2) = 0$

We don't care what $\eta(x)$ is. It is arbitrary.

We can compute the functional for this new path

$$I(\varepsilon) = \int_{x_1}^{x_2} \phi(Y(x), Y'(x), x) dx = \int_{x_1}^{x_2} \phi(y(x) + \varepsilon \eta(x), y'(x) + \varepsilon \eta'(x), x) dx$$

Expand the integrand in Taylor series about $\varepsilon = 0$

$$\Rightarrow I(\varepsilon) = \int_{x_1}^{x_2} \phi(y, y', x) dx + \varepsilon \int_{x_1}^{x_2} \left[\frac{\partial \phi}{\partial y} \eta(x) + \frac{\partial \phi}{\partial y'} \eta'(x) \right] dx + O(\varepsilon^2)$$

for extremum $\left. \frac{dI(\varepsilon)}{d\varepsilon} \right|_{\varepsilon=0} = 0$ and 2nd term should vanish

$$\Rightarrow \int_{x_1}^{x_2} \left[\frac{\partial \phi}{\partial y} \eta(x) + \frac{\partial \phi}{\partial y'} \frac{d}{dx} \eta(x) \right] dx = 0, \text{ use } \frac{\partial \phi}{\partial y'} \frac{d}{dx} \eta(x) = \frac{d}{dx} \left[\frac{\partial \phi}{\partial y'} \eta(x) \right] - \eta(x) \frac{d}{dx} \frac{\partial \phi}{\partial y'}$$

1st term due to $\int_{x_1}^{x_2} \frac{d}{dx} \left[\frac{\partial \phi}{\partial y'} m(x) \right] dx = \left. m(x) \frac{\partial \phi}{\partial y'} \right|_{x_1}^{x_2} = 0$

since $m(x)$ vanishes at end points.

$$\Rightarrow \int_{x_1}^{x_2} m(x) \left[\frac{\partial \phi}{\partial y} - \frac{d}{dx} \frac{\partial \phi}{\partial y'} \right] dx = 0$$

This must be true for ANY $m(x)$ so square brackets must be zero

$$(*) \Rightarrow \frac{d}{dx} \frac{\partial \phi}{\partial y'} - \frac{\partial \phi}{\partial y} = 0 \quad \text{Euler-Lagrange equation}$$

You can generalize this to more complicated integrands ϕ and for more than 1D.

Example: shortest distance between points? (Euclidian space)

$$s_{12} = \int_1^2 \sqrt{dx^2 + dy^2} = \int_1^2 \sqrt{1+y'^2} dx \Rightarrow \phi = \sqrt{1+y'^2}$$

$$(*) \Rightarrow \frac{d}{dx} \frac{y'}{\sqrt{1+y'^2}} = 0 \Rightarrow y'' \left\{ \frac{1}{(1+y'^2)^{3/2}} - \frac{(y')^2}{(1+y'^2)^{3/2}} \right\} = 0$$

or $y'' = 0 \Rightarrow y(x) = ax + b$ amazing!

Let us do the derivation also in terms of variation $\delta y(x)$. This is same as above, but with more convenient notation.

$$y(x) - y(x) = \varepsilon m(x) = \delta y(x)$$

derivation $\Rightarrow Y'(x) - y'(x) = \sum \eta'(x) \equiv \delta y'(x)$

$$\delta y'(x) = \frac{d}{dx} \delta y(x)$$

Variation of the functional:

$$\delta(Y(x), Y'(x), x) - \delta(y(x), y'(x), x) \equiv \delta \delta$$

Taylor series implies that

$$\delta \delta = \frac{\partial \delta}{\partial y} \delta y + \frac{\partial \delta}{\partial y'} \delta y' \quad (\text{up to 1st order})$$

This then gives variation in I as

$$\delta I \equiv \int \delta \delta dx = \int \left(\frac{\partial \delta}{\partial y} \delta y + \frac{\partial \delta}{\partial y'} \delta y' \right) dx = \int \left(\frac{\partial \delta}{\partial y} \delta y + \frac{\partial \delta}{\partial y'} \frac{d}{dx} \delta y \right) dx \quad (*)$$

fixed end points implies $\delta y(x_1) = \delta y(x_2) = 0$

Partial integration of the 2nd term in (*)

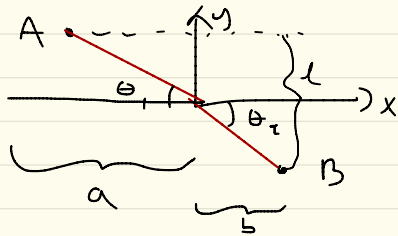
$$\Rightarrow \delta I = \int_{x_1}^{x_2} \delta y \left[\frac{\partial \delta}{\partial y} - \frac{d}{dx} \frac{\partial \delta}{\partial y'} \right] dx$$

This must vanish for extremum \Rightarrow Euler-Lagrange equation



Example: Fermat's principle

Light travels from A to B along such path that travel time is minimized



$n_A = \text{index of refraction}$

$$\rightarrow v_A = c/n_A$$

$$n_B \rightarrow v_B = c/n_B$$

A at $(-a, y)$ & B at $(b, -(l-y))$

from A to origin: $d_A = \sqrt{a^2 + y^2}$

from origin to B: $d_B = \sqrt{b^2 + (l-y)^2}$

$$T = \frac{d_A}{v_A} + \frac{d_B}{v_B} = \frac{\sqrt{a^2 + y^2}}{v_A} + \frac{\sqrt{b^2 + (l-y)^2}}{v_B}$$

$$\begin{cases} T = \int_A^B ds/v_s \\ v_s = \begin{cases} c/n_A & \text{in A} \\ c/n_B & \text{in B} \end{cases} \end{cases}$$

$$\frac{dT}{dy} = \frac{y}{v_A \sqrt{a^2 + y^2}} - \frac{(l-y)}{v_B \sqrt{(l-y)^2 + b^2}} = 0$$

$$\Leftrightarrow \frac{\sin \theta_1}{v_A} - \frac{\sin \theta_2}{v_B} = 0 \Leftrightarrow n_1 \sin \theta_1 = n_2 \sin \theta_2$$

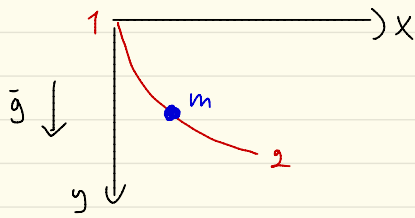
This is Snell's law.

$$\text{Generally: } T = \int_{t_0}^{t_f} dt = \frac{1}{c} \int_{t_0}^{t_f} \frac{c}{v} \frac{ds}{dt} dt = \int_A^B n ds$$

$$ds = \frac{\sqrt{dx^2 + dy^2}}{dx} dx = \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$



Example: Brachistochrone - problem



What path minimizes the travel time from 1 to 2?

$$t_{12} = \int_1^2 dt = \int_1^2 \frac{ds}{v}$$

Energy conservation: $\frac{1}{2}mv^2 = mgy$

$$\Rightarrow t_{12} = \int_1^2 \frac{\sqrt{1+(y')^2}}{\sqrt{2gy}} dx, \text{ since } ds = \sqrt{dx^2 + dy^2} = dx\sqrt{1+(y')^2}$$

$\phi(y, y', x)$

x doesn't appear in ϕ explicitly \Rightarrow we can use so-called Beltrami identity. In Euler-Lagrange eq. we calculate

$$\frac{d}{dx} \left(\frac{\partial \phi}{\partial y'} \right) = \frac{\partial^2 \phi}{\partial y \partial y'} y' + \frac{\partial^2 \phi}{\partial y'^2} y'' \quad (\text{Chain rule})$$

$$\text{E-L eq. } \Rightarrow \frac{\partial^2 \phi}{\partial y \partial y'} y' + \frac{\partial^2 \phi}{\partial y'^2} y'' = \frac{\partial \phi}{\partial y}$$

$$\begin{aligned} \text{Calculate } \frac{d}{dx} \left(y' \frac{\partial \phi}{\partial y'} - \phi \right) &= \left(\frac{\partial \phi}{\partial y'} y'' + \frac{\partial^2 \phi}{\partial y \partial y'} y'^2 + \frac{\partial^2 \phi}{\partial y'^2} y' y'' \right) - \\ &\quad \left(\frac{\partial \phi}{\partial y} y' + \frac{\partial \phi}{\partial y'} y'' \right) \\ &= y' \left(\frac{\partial^2 \phi}{\partial y \partial y'} y' + \frac{\partial^2 \phi}{\partial y'^2} y'' - \frac{\partial \phi}{\partial y} \right) = 0 \end{aligned}$$

$$\Leftrightarrow y' \frac{\partial \phi}{\partial y'} - \phi = L = \text{constant}$$

Brachistochrone continues ...

Ignore $2g$ since it is just a constant prefactor

$$\mathcal{D}(y, y') = \frac{\sqrt{1+y'^2}}{\sqrt{y}}, \quad y' \frac{\partial \mathcal{D}}{\partial y'} - \mathcal{D} = C$$

$$\Rightarrow \frac{y'^2}{\sqrt{1+y'^2}\sqrt{y}} - \frac{\sqrt{1+y'^2}}{\sqrt{y}} = C \quad (\Rightarrow) \quad \frac{-1}{\sqrt{1+y'^2}\sqrt{y}} = C$$

$$\text{Solve for } y' \Rightarrow \frac{dy}{dx} = \sqrt{\frac{k-y}{y}}, \quad k = 1/C^2$$

This can be a bit tricky, but $\tan \theta = \sqrt{\frac{y}{k-y}} \Rightarrow y = k \sin^2 \theta$

$$\frac{d\theta}{dx} = \frac{d\theta}{dy} \frac{dy}{dx} = \frac{1}{2k \sin \theta \cos \theta} \cdot \frac{1}{\tan \theta} = \frac{1}{2k \sin^2 \theta}$$

$$\text{so } dx = 2k \sin^2 \theta d\theta \Rightarrow \text{integrate} \Rightarrow x = 2k \int \sin^2 \theta d\theta$$

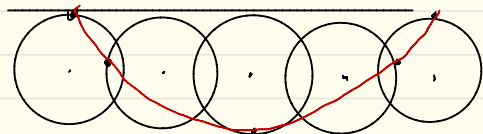
$$\text{Initial conditions: start at } (x, y) = (0, 0) = 2k \left(\frac{\theta}{2} - \frac{\sin 2\theta}{4} \right) + C_1$$

$y = k \sin^2 \theta = 0 \Rightarrow \theta = 0$, substitute to eq. for x

$$\Rightarrow x = C_1, \text{ or } C_1 = 0$$

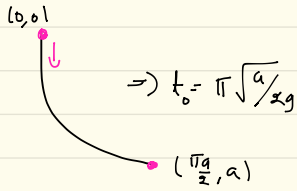
Define $a = k/2$, $\theta = \alpha$

$$\Rightarrow \begin{cases} x = a(\alpha - \sin \alpha) \\ y = a(1 - \cos \alpha) \end{cases} \quad \text{Cycloid}$$



Curve traced out by a fixed point on a circle of radius a rolling in a straight line.

○ Time it takes to fall: integrate the starting point using the found solution.



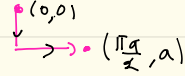
$$\Rightarrow t_0 = \pi \sqrt{\frac{a}{2g}}$$

Free fall over a :

$$\left. \begin{array}{l} \downarrow g \\ a \end{array} \right\} \begin{array}{l} y = \frac{1}{2} g t^2 \\ \Rightarrow t_F = \sqrt{\frac{2a}{g}} \end{array}$$

$t_0/t_F = \frac{\pi}{\sqrt{2}\sqrt{2}} = \frac{\pi}{2} > 1$ so it takes longer than free fall. Makes sense.

Find point $(\frac{\pi a}{2}, a)$: alternative guess. Drop straight \rightarrow turn right and travel at fixed vel.



$$\rightarrow t_A = t_F + \frac{\pi a}{2v}, \quad \frac{1}{2}mv^2 = mga, \quad v = \sqrt{2ga}$$

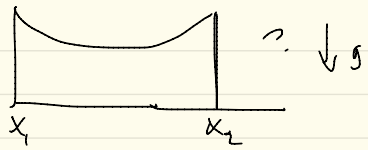
$$\Rightarrow t_A = \sqrt{\frac{2a}{g}} + \frac{\pi a}{2\sqrt{2ga}} = \sqrt{\frac{a}{g}} \left[\sqrt{2} + \frac{\pi}{2\sqrt{2}} \right] = \pi \sqrt{\frac{a}{2g}} \left[\frac{2}{\pi} + \frac{1}{2} \right]$$

≈ 1.14

\Rightarrow so we have certainly found a faster path than this!

Esimerkki

Suspended cable:



call linear density in the cable as ρ . Length of the cable L .

Potential energy of the cable: (there is no kinetic energy)

$$V = \rho g \int_0^L y ds = \rho g \int_{x_1}^{x_2} y \sqrt{1+y'^2} dx$$

There is a constraint in that length must be L .

$$\Rightarrow \int_{x_1}^{x_2} \sqrt{1+y'^2} dx = L$$

We are looking for optimum with integrand

$$F = \rho g y \sqrt{1+y'^2} - \lambda \sqrt{1+y'^2} = (\rho g y - \lambda) \sqrt{1+y'^2}$$

there is no explicit x -dependence so we can use Beltrami identity (amounts to Euler-Lagrange)

$$y' \frac{\partial F}{\partial y'} - F = C = \text{constant}$$

$$\Rightarrow \frac{y'^2}{\sqrt{1+y'^2}} (\rho g y - \lambda) - (\rho g y - \lambda) \sqrt{1+y'^2} = C$$

$$\text{which simplifies to } -\frac{\rho g y - \lambda}{\sqrt{1+y'^2}} = C$$

$$\text{solve for } y' \Rightarrow \left(\frac{dy}{dx} \right)^2 = \left(\frac{\rho g y - \lambda}{C} \right)^2 - 1$$

$\rho g y - \lambda = Cz$ change of variables

$$\rho g dy = C dz$$

(3.4) ... continues

$$\Rightarrow \frac{dz}{\sqrt{z^2-1}} = \frac{P_0}{c} dx \Rightarrow (\ln(z + \sqrt{z^2-1})) = \frac{P_0}{c} x + b \quad \leftarrow \text{constant of integration}$$

$b = -\frac{P_0}{c} \beta$ to simplify algebra

$$\Rightarrow z = \frac{P_0 y - \lambda}{c} = \cosh\left[\frac{P_0(x-\beta)}{c}\right]$$

$\Rightarrow y(x) = +\frac{\lambda}{P_0} + \frac{c}{P_0} \cosh\left[\frac{P_0(x-\beta)}{c}\right]$, we can choose $\beta = 0$ so cable hangs around $x=0$. Then $x_1 = -x_2$

$$y(x_1) = h = y(x_2)$$

$$\text{Length } L = \int_{-x_1}^{x_2} \sqrt{1+y'^2} dx = \int_{-x_1}^{x_2} \cosh\left[\frac{P_0 x}{c}\right] dx = \frac{2c}{P_0} \sinh\left(\frac{P_0 x_2}{c}\right)$$

If we know P_0, x_2 this determines c after which boundary condition $y(x_1) = h$ sets λ .

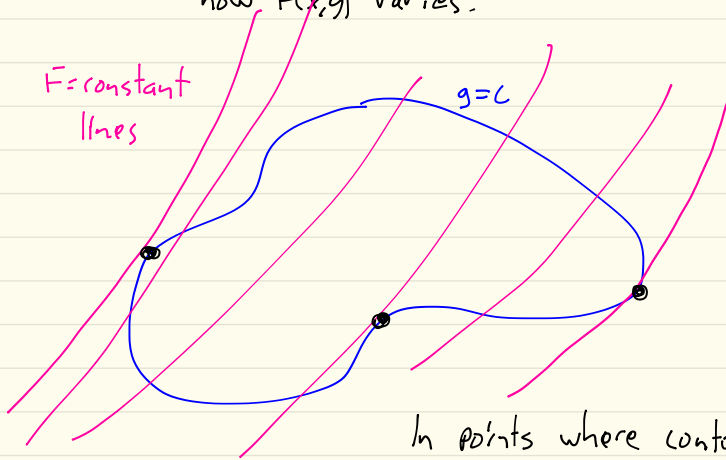
This shape is known as a catenary.

Why did we apply Euler-Lagrange to

$$M = \int (\phi - \lambda g) dx ??$$

Plausibility: Say you want extrema of $F(x,y)$ with constraint $g(x,y) = C$.

Strategy: Walk along the contour $g(x,y) = C$ and see how $F(x,y)$ varies.



In points where contours have same tangent F changes in the same direction on either side $\Rightarrow F = \text{extremum}$

Mathematically: $\nabla F \parallel \nabla g \Leftrightarrow \nabla F = \lambda \nabla g$ for some λ

$$\Rightarrow \begin{cases} \nabla F = \lambda \nabla g \\ g(x,y) = C \end{cases} \text{ pair of equations}$$

$\Rightarrow \nabla(F - \lambda g) = 0 \Rightarrow$ looking for where $F - \lambda g$ has extrema.