

M-V Gaussian characterization

$$x \sim N_D(\mu, \Sigma) \quad \Sigma = E \Lambda E^T \quad E^T E = I \quad \Lambda = \text{diag}(\lambda_1, \dots, \lambda_D)$$

$$f(x) = (2\pi)^{-\frac{D}{2}} |\Sigma|^{-\frac{1}{2}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1} (x-\mu)}$$

$$y = \Lambda^{-\frac{1}{2}} E^T (x-\mu)$$

$$g(y) dy = f(x) dx$$

$$g(y) = f(x) \left| \frac{dx}{dy} \right|$$

↑
in terms
of y

↖ Jacobian

Formula
for multivariate
transformation

$$x = E \Lambda^{\frac{1}{2}} y + \mu \quad \frac{dx}{dy} = E \Lambda^{\frac{1}{2}}$$

$$\begin{aligned} \underline{g(y)} &= f(E \Lambda^{\frac{1}{2}} y + \mu) \left| \frac{dx}{dy} \right| = (2\pi)^{-\frac{D}{2}} |\Sigma|^{-\frac{1}{2}} e^{-\frac{1}{2}(E \Lambda^{\frac{1}{2}} y)^T \Sigma^{-1} E \Lambda^{\frac{1}{2}} y} |E \Lambda^{\frac{1}{2}}| \\ &= (2\pi)^{-\frac{D}{2}} |E|^{-\frac{1}{2}} |\Lambda|^{-\frac{1}{2}} |E^T|^{-\frac{1}{2}} e^{-\frac{1}{2} y^T \Lambda^{\frac{1}{2}} E^T (E^T)^{-1} \Lambda^{-1} E^{-1} E \Lambda^{\frac{1}{2}} y} |E| |\Lambda|^{\frac{1}{2}} \\ &= (2\pi)^{-\frac{D}{2}} e^{-\frac{1}{2} y^T y} \equiv \underline{N_D(y | 0, I)} \end{aligned}$$

Completing the square

Claim: $\frac{1}{2} x^T A x - b^T x = \frac{1}{2} (x - A^{-1} b)^T A (x - A^{-1} b) - \frac{1}{2} b^T A^{-1} b$

Proof: $\frac{1}{2} (x - A^{-1} b)^T A (x - A^{-1} b) = \frac{1}{2} x^T A x - \frac{1}{2} x^T A A^{-1} b - \frac{1}{2} b^T (A^T)^{-1} A x + \frac{1}{2} b^T (A^T)^{-1} A A^{-1} b$

$$= \frac{1}{2} x^T A x - b^T x + \frac{1}{2} b^T A^{-1} b$$

Note: this requires that $A^T = A$
i.e. that A is symmetric.

Further: $\int \exp(-\frac{1}{2} x^T A x + b^T x) dx = \int \exp(-\frac{1}{2} (x - A^{-1} b)^T A (x - A^{-1} b)) \exp(\frac{1}{2} b^T A^{-1} b) dx$

$$= \exp(\frac{1}{2} b^T A^{-1} b) (2\pi)^{\frac{D}{2}} |A|^{-\frac{1}{2}} \int (2\pi)^{-\frac{D}{2}} |A^{-1}|^{-\frac{1}{2}} \exp(-\frac{1}{2} (x - A^{-1} b)^T A (x - A^{-1} b)) dx$$

$$= \exp(\frac{1}{2} b^T A^{-1} b) (2\pi)^{\frac{D}{2}} |A|^{-\frac{1}{2}} = \exp(\frac{1}{2} b^T A^{-1} b) |2\pi A^{-1}|^{\frac{1}{2}}$$

Linear Gaussian systems

$$p(x) = N(x | \mu_x, \Sigma_x)$$

$$p(y|x) = N(y | Ax+b, \Sigma_y)$$

Then

$$p(y) = N(y | A\mu_x + b, \Sigma_y + A\Sigma_x A^T) \quad (*)$$

$$p(x|y) = N(x | \mu_{x|y}, \Sigma_{x|y})$$

$$\Sigma_{x|y}^{-1} = \Sigma_x^{-1} + A^T \Sigma_y^{-1} A$$

$$\mu_{x|y} = \Sigma_{x|y} \left[A^T \Sigma_y^{-1} (y-b) + \Sigma_x^{-1} \mu_x \right]$$

Proof of (*): $\log p(x,y) = -\frac{1}{2} (x-\mu_x)^T \Sigma_x^{-1} (x-\mu_x) - \frac{1}{2} (y-Ax-b)^T \Sigma_y^{-1} (y-Ax-b) + \text{constant}$

Because this is a quadratic form of x and y , this is a joint Gaussian.

Hence, we know that y has a Gaussian distribution (marginally).

$$E(y) = E(E(y|x)) = E(Ax+b) = A\mu_x + b \quad \text{"law of total expectation"}$$

$$\text{Var}(y) = E(\text{Var}(y|x)) + \text{Var}(E(y|x)) \quad \text{"law of total variance"}$$

$$= \Sigma_y + \text{Var}(Ax+b) = \Sigma_y + \text{Var}(Ax)$$

"Wikipedia: $\text{cov}(AX+a) = A \text{cov}(X) A^T$ "

$$= \Sigma_y + A \text{Var}(x) A^T = \Sigma_y + A \Sigma_x A^T \quad \square$$