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## **Title, introduction and drafting of the paper**

### **Three candidates for title:**

- 1) LIDAR automated crane system
- 2) Autonomous warehouse management
- 3) Automated Indoor factory floor material management system

### **Introduction section:**

Automated cranes have been developed a lot since robots have become more general. That's why there are many scientific articles discussing the use of automated crane systems in warehouse (1) and other environments (2, 3). These articles also describe methods for collision detection and trajectory planning. These are very advanced systems, but our idea is to use a laser scanner for scanning the environment and using the point cloud for dynamic detection of environment, collision avoidance and trajectory planning. Laser scanners have been previously used for improving visibility of the crane operator (4, 5) and also for other path-planning applications, including UAVs (6), but not for providing data of the environment for autonomous crane operation. Using point cloud for building 3D map of environment is also quite common practice and there are a lot of research based on algorithms and methods for doing this (7). Also there is a lot of research done on trajectory planning, and there should be enough information and algorithms to make this part of the project work even in uncertain situations(8) (9). Path planning is possible to apply even in dynamic situations, where environment changes (10)

This research is done because collision avoidance makes crane operation safer for everyone. Also there are cost savings if no crane operator is required to operate the crane. For these reasons we are going to combine automated crane operation with laser scanner to achieve even better and safer automated crane operation. This project will show that how realistic is the idea of using a lidar to dynamically scan surrounding of a overhead crane, and how reasonable, safe and cost efficient this is. Crane manufacturers might be quite interested in the results of this research.

### **Methods**

In the methods chapter we discuss the process of how we got from the start of the project to a final design and demo model. The idea process, design process and building process are discussed through.

### **Results**

In the results chapter the final product is presented and it's working principle is explained thoroughly.

## Discussion

Finally, in the discussion chapter we look back at our goals and determine whether we have succeeded in them. We also discuss whether we succeeded in the competition.

## References:

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